

# Logspace and compressed-word computations in nilpotent groups

Andrey Nikolaev

Stevens Institute of Technology

New York

March 13, 2015

Joint work with J. Macdonald, A. Miasnikov, S. Vassileva

## Approaches to algorithmic problems in nilpotent groups:

- Enumerative algorithms via residual finiteness.  
No reasonable complexity estimates (until recently).
- Embedding  $G \hookrightarrow UT(n, \mathbb{Z})$ .  
Only for torsion-free case. Does not work well for all problems.
- Normal forms via polycyclic/Mal'cev bases.  
Reasonable algorithms, no specific complexity estimates in most cases.

Approaches to algorithmic problems in nilpotent groups:

- Enumerative algorithms via residual finiteness.  
No reasonable complexity estimates (until recently).
- Embedding  $G \hookrightarrow UT(n, \mathbb{Z})$ .  
Only for torsion-free case. Does not work well for all problems.
- Normal forms via polycyclic/Mal'cev bases.  
Reasonable algorithms, no specific complexity estimates in most cases.

Approaches to algorithmic problems in nilpotent groups:

- Enumerative algorithms via residual finiteness.  
No reasonable complexity estimates (until recently).
- Embedding  $G \hookrightarrow UT(n, \mathbb{Z})$ .  
Only for torsion-free case. Does not work well for all problems.
- Normal forms via polycyclic/Mal'cev bases.  
Reasonable algorithms, no specific complexity estimates in most cases.

Approaches to algorithmic problems in nilpotent groups:

- Enumerative algorithms via residual finiteness.  
No reasonable complexity estimates (until recently).
- Embedding  $G \hookrightarrow UT(n, \mathbb{Z})$ .  
Only for torsion-free case. Does not work well for all problems.
- Normal forms via polycyclic/Mal'cev bases.  
Reasonable algorithms, no specific complexity estimates in most cases.

Approaches to algorithmic problems in nilpotent groups:

- Enumerative algorithms via residual finiteness.  
No reasonable complexity estimates (until recently).
- Embedding  $G \hookrightarrow UT(n, \mathbb{Z})$ .  
Only for torsion-free case. Does not work well for all problems.
- Normal forms via polycyclic/Mal'cev bases.  
Reasonable algorithms, no specific complexity estimates in most cases.

Approaches to algorithmic problems in nilpotent groups:

- Enumerative algorithms via residual finiteness.  
No reasonable complexity estimates (until recently).
- Embedding  $G \hookrightarrow UT(n, \mathbb{Z})$ .  
Only for torsion-free case. Does not work well for all problems.
- Normal forms via polycyclic/Mal'cev bases.  
Reasonable algorithms, no specific complexity estimates in most cases.

Approaches to algorithmic problems in nilpotent groups:

- Enumerative algorithms via residual finiteness.  
No reasonable complexity estimates (until recently).
- Embedding  $G \hookrightarrow UT(n, \mathbb{Z})$ .  
Only for torsion-free case. Does not work well for all problems.
- Normal forms via polycyclic/Mal'cev bases.  
Reasonable algorithms, no specific complexity estimates in most cases.



# The problems

For  $G$  finitely generated nilpotent group.

- (I) Compute Mal'cev normal form.
- (II) Membership problem.
- (III) Compute the kernel of a homomorphism.
- (IV) Compute subgroup presentations.
- (V) Compute the centralizer of an element.
- (VI) Conjugacy (search) problem.

# The results

- 1 Problems (I)-(VI) are decidable
  - in space  $O(\log L)$ , and simultaneously
  - in time  $O(L \log^3 L)$ .
- 2 We give polynomial bounds on the length of outputs.
- 3 Compressed-word versions of problems (I)-(VI) are decidable in polynomial time.

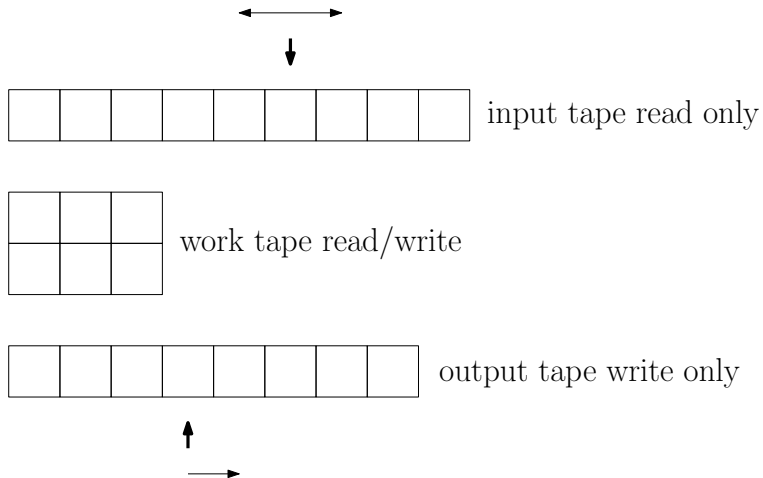
# The results

- 1 Problems (I)-(VI) are decidable
  - in space  $O(\log L)$ , and simultaneously
  - in time  $O(L \log^3 L)$ .
- 2 We give polynomial bounds on the length of outputs.
- 3 Compressed-word versions of problems (I)-(VI) are decidable in polynomial time.

# The results

- ① Problems (I)-(VI) are decidable
  - in space  $O(\log L)$ , and simultaneously
  - in time  $O(L \log^3 L)$ .
- ② We give polynomial bounds on the length of outputs.
- ③ Compressed-word versions of problems (I)-(VI) are decidable in polynomial time.

# Log-space transducers



# Logspace $\Rightarrow$ P-time.

- Input length =  $n$ .
- Number of cells on work tape  $\leq k \log n$ .
- Configurations cannot be repeated.
- Total number of configurations  $\sim 2^{k \log n} \sim n^k$
- Therefore,  $O(n^k)$  time.
- P-time  $\stackrel{?}{\Rightarrow}$  logspace: open problem.

# Compressed words

- $\Sigma$  is a set of symbols, called *terminal symbols* with  $\epsilon \in \Sigma$ .
- A *straight-line program* or *compressed word*  $\mathbb{A}$  over  $\Sigma$  consists of
  - $(\mathcal{A}, <)$  – ordered finite set, called the set of *non-terminal symbols*,
  - exactly one *production rule* for each  $A \in \mathcal{A}$  of the form
    - $A \rightarrow BC$  where  $B, C \in \mathcal{A}$  and  $B, C < A$  or
    - $A \rightarrow x$  where  $x \in \Sigma$ .
- The *root* is the greatest non-terminal.
- $\text{eval}(\mathbb{A})$  is the word in  $\Sigma^*$  obtained by starting with the root non-terminal and successively replacing every non-terminal symbol with the right-hand side of its production rule.
- The *size*,  $|\mathbb{A}|$ , of  $\mathbb{A}$  is the number of non-terminal symbols.

## Example of compression

Consider the program  $\mathbb{B}$  over  $\{x\}$  with production rules

$$B_n \rightarrow B_{n-1} B_{n-1},$$

$$B_{n-1} \rightarrow B_{n-2} B_{n-2},$$

...

$$B_1 \rightarrow B_0 B_0,$$

$$B_0 \rightarrow x.$$

Unravel,  $\text{eval}(B_2) = x^4$  and  $\text{eval}(\mathbb{B}) = x^{2^n}$ .

Size of  $\mathbb{B}$  is  $n + 1$ , size of  $\text{eval}(\mathbb{B})$  is  $2^n$ .



# Nilpotent group

A group  $G$  is called *nilpotent* if it has a central series, i.e. a normal series

$$G = G_1 \triangleright G_2 \triangleright \dots \triangleright G_c \triangleright G_{c+1} = 1 \quad (1)$$

such that  $[G, G_i] \leq G_{i+1}$  for all  $i = 1, \dots, c$ .

# Mal'cev basis

- $G_i/G_{i+1}$  is abelian.  
Pick  $a_{i1}, \dots, a_{im_i}$  a good basis for  $G_i/G_{i+1}$ .
- $A = \{a_{11}, a_{12}, \dots, a_{cm_c}\}$  is a polycyclic generating set for  $G$ .
- Relabel  $A$  as  $\{a_1, \dots, a_m\}$  for convenience.
- $A$  is a *Mal'cev basis associated to the central series (1)*.

# Mal'cev basis

- $G_i/G_{i+1}$  is abelian.  
Pick  $a_{i1}, \dots, a_{im_i}$  a good basis for  $G_i/G_{i+1}$ .
- $A = \{a_{11}, a_{12}, \dots, a_{cm_c}\}$  is a polycyclic generating set for  $G$ .
- Relabel  $A$  as  $\{a_1, \dots, a_m\}$  for convenience.
- $A$  is a *Mal'cev basis associated to the central series (1)*.

# Normal forms and word problem

# Mal'cev normal forms

Let  $A = \{a_1, \dots, a_m\}$  be a Mal'cev basis for  $G$ .

“Collect to the left” relations ( $i < j$ ) and “Torsion” relations

$$a_j a_i = a_i a_j \cdot a_{j+1}^{\beta_{j+1}} \cdots a_m^{\beta_m} \quad a_i^{\tau_i} = a_{i+1}^{\beta_{i+1}} \cdots a_m^{\beta_m}$$

allow to write every element  $g \in G$  uniquely as

$$g = a_1^{\alpha_1} \cdots a_m^{\alpha_m},$$

with appropriate  $\alpha_j \in \mathbb{Z}$ .

$\text{Coord}(g) = (\alpha_1, \dots, \alpha_m)$  is the *coordinate tuple* of  $g$ .

$a_1^{\alpha_1} \cdots a_m^{\alpha_m}$  is the (*Mal'cev*) *normal form* of  $g$ .

Denote  $\alpha_j = \text{Coord}_j(g)$ .

# Mal'cev normal forms

Let  $A = \{a_1, \dots, a_m\}$  be a Mal'cev basis for  $G$ .

“Collect to the left” relations ( $i < j$ ) and “Torsion” relations

$$a_j a_i = a_i a_j \cdot a_{j+1}^{\beta_{j+1}} \cdots a_m^{\beta_m} \quad a_i^{\tau_i} = a_{i+1}^{\beta_{i+1}} \cdots a_m^{\beta_m}$$

allow to write every element  $g \in G$  uniquely as

$$g = a_1^{\alpha_1} \cdots a_m^{\alpha_m},$$

with appropriate  $\alpha_i \in \mathbb{Z}$ .

$\text{Coord}(g) = (\alpha_1, \dots, \alpha_m)$  is the *coordinate tuple* of  $g$ .

$a_1^{\alpha_1} \cdots a_m^{\alpha_m}$  is the *(Mal'cev) normal form* of  $g$ .

Denote  $\alpha_i = \text{Coord}_i(g)$ .

# Mal'cev normal forms

Let  $A = \{a_1, \dots, a_m\}$  be a Mal'cev basis for  $G$ .

“Collect to the left” relations ( $i < j$ ) and “Torsion” relations

$$a_j a_i = a_i a_j \cdot a_{j+1}^{\beta_{j+1}} \cdots a_m^{\beta_m} \quad a_i^{\tau_i} = a_{i+1}^{\beta_{i+1}} \cdots a_m^{\beta_m}$$

allow to write every element  $g \in G$  uniquely as

$$g = a_1^{\alpha_1} \cdots a_m^{\alpha_m},$$

with appropriate  $\alpha_i \in \mathbb{Z}$ .

$\text{Coord}(g) = (\alpha_1, \dots, \alpha_m)$  is the *coordinate tuple* of  $g$ .

$a_1^{\alpha_1} \cdots a_m^{\alpha_m}$  is the (*Mal'cev*) *normal form* of  $g$ .

Denote  $\alpha_i = \text{Coord}_i(g)$ .

# Working with Mal'cev coordinates

Let  $\{a_1, \dots, a_m\}$  be a Mal'cev basis for  $G$ . Then there are quasi-polynomials (compositions of polynomials and division with a remainder functions)

$$p_1, \dots, p_m, q_1, \dots, q_m$$

such that for  $\text{Coord}(g) = (\gamma_1, \dots, \gamma_m)$  and  $\text{Coord}(h) = (\delta_1, \dots, \delta_m)$ ,

- (i)  $\text{Coord}_i(gh) = p_i(\gamma_1, \dots, \gamma_m, \delta_1, \dots, \delta_m)$ ,
  - (ii)  $\text{Coord}_i(g^l) = q_i(\gamma_1, \dots, \gamma_m, l)$ , and
  - (iii) if  $\text{Coord}(g) = (0, \dots, 0, \gamma_k, \dots, \gamma_m)$ , then
    - (a)  $\forall i < k, \text{Coord}_i(gh) = \delta_i$  and  $\text{Coord}_k(gh) = \gamma_k + \delta_k$
    - (b)  $\forall i < k, \text{Coord}_i(g^l) = 0$  and  $\text{Coord}_k(g^l) = l\gamma_k$ .
- Example.  $(a_1 a_2 a_3 a_4 a_5) \cdot (a_3^2 a_4 a_5) = a_1 a_2 a_3^3 a_4^? a_5^?$ .



# Length bound for Mal'cev normal forms

## Theorem

Let  $G$  be nilpotent group of class  $c$  with a Mal'cev basis  $A$ .  
Then, for any word  $w$  over  $A$ ,

$$|\text{Coord}_i(w)| \leq \kappa |w|^c$$

where  $\kappa$  is a constant that depends only on the presentation of  $G$ .

- $|\text{Coord}_i(w)|$  is the absolute value of the integer  $\text{Coord}_i(w)$ ;
- $|w|$  is the word length of  $w$  in terms of  $A$ .
- Number of bits of  $\text{Coord}(w)$  is  $\sim \log |w|$  (so can store  $\text{Coord}(w)$  in memory).

## Remark on nilpotent vs. polycyclic

### Proposition

Let  $H$  be a polycyclic group with polycyclic generators  $A = \{a_1, \dots, a_m\}$ . Suppose there is a polynomial  $P(n)$  such that if  $w$  is a word over  $A^{\pm 1}$  of length  $n$  then

$$|\text{Coord}_i(w)| \leq P(n)$$

for all  $i = 1, 2, \dots, m$ . Then  $H$  is virtually nilpotent.

Therefore, the results cannot be immediately extended to polycyclic groups.

# Usual vs. Mal'cev encoding

Consider  $\mathbb{Z} = \langle a \rangle$ .

- Encode a word  $w$  as  $w = aaaaaaaaaa$ , so  $|w| = 9$ .
- Encode a word  $w$  as  $w = a^9$ , or,  $w = 9$ . So  $\|w\| = \lceil \log_2 9 \rceil = 4$ .

Similar with nilpotent groups. Let  $G$  have Mal'cev basis  $a_1, \dots, a_m$ .

- Encode a word  $w$  as  $w = a_{i_1} a_{i_2} \dots a_{i_n}$ . So  $|w| = n$ .
- This can be rewritten as  $w = a_1 \dots a_1 a_2 \dots a_2 \dots a_m \dots a_m$ .
- Here  $|w| \sim n^c$ .
- So  $w = a_1^{\alpha_1} \dots a_m^{\alpha_m}$  with  $\alpha_1, \dots, \alpha_m \in \mathbb{Z}$ .
- Encode  $w = (\alpha_1, \dots, \alpha_m) \in \mathbb{Z}^m$ .
- Here  $\|w\| \sim O(\log_2 n)$ .

What about compressed words?

# Usual vs. Mal'cev encoding

Consider  $\mathbb{Z} = \langle a \rangle$ .

- Encode a word  $w$  as  $w = aaaaaaaaaa$ , so  $|w| = 9$ .
- Encode a word  $w$  as  $w = a^9$ , or,  $w = 9$ . So  $\|w\| = \lceil \log_2 9 \rceil = 4$ .

Similar with nilpotent groups. Let  $G$  have Mal'cev basis  $a_1, \dots, a_m$ .

- Encode a word  $w$  as  $w = a_{i_1} a_{i_2} \dots a_{i_n}$ . So  $|w| = n$ .
- This can be rewritten as  $w = a_1 \dots a_1 a_2 \dots a_2 \dots a_m \dots a_m$ .
- Here  $|w| \sim n^c$ .
- So  $w = a_1^{\alpha_1} \dots a_m^{\alpha_m}$  with  $\alpha_1, \dots, \alpha_m \in \mathbb{Z}$ .
- Encode  $w = (\alpha_1, \dots, \alpha_m) \in \mathbb{Z}^m$ .
- Here  $\|w\| \sim O(\log_2 n)$ .

What about compressed words?

# Working with compressed words

The strategy to do the compressed word version of problems is as follows.

- Convert the input SLPs to Mal'cev coordinates.
- Apply algorithms which work with Mal'cev coordinates in binary.
- Convert the output coordinate vectors to SLPs.

What about the size?

- Let  $L$  be the length of the SLP  $\mathbb{A}$ .
- The length of  $\text{eval}(\mathbb{A})$  is  $\sim 2^L$ .
- Each Mal'cev coordinate of  $\text{eval}(\mathbb{A})$  is  $\sim 2^{cL}$ .
- In binary, coordinates are  $O(L)$  bits long.

## Theorem

Let  $G$  be a f.g. nilpotent group with Mal'cev generating set  $A$ .

- There is an algorithm that, given a straight-line program  $\mathbb{A}$  over  $A^\pm$ , computes the coordinate vector  $\text{Coord}(\text{eval}(\mathbb{A}))$ .
- The algorithm runs in time  $O(L^3)$ , where  $L = |\mathbb{A}|$ .
- Each coordinate of  $\text{eval}(\mathbb{A})$  is expressed as a  $O(L)$ -bit number.

## Theorem

For every finitely generated nilpotent group  $G$ , the Mal'cev normal form of a word of length  $L$  is computable in

- space  $O(\log(L))$  and, simultaneously,
- time  $O(L \cdot \log^2 L)$ .

The algorithm – compute coordinates element by element.

- Denote  $w = x_1 \cdots x_L$ .
- Keep an array  $\gamma = (\gamma_1, \dots, \gamma_m)$  of coordinates in memory.
- At the end of step  $j$ ,  $\gamma$  holds the coordinates of  $x_1 \dots x_j$ .
- For  $0 \leq j < L$ , compute  $\text{Coord}(x_1 \cdots x_j x_{j+1})$  using the  $p_i$  with
  - $\text{Coord}(x_1 \cdots x_j) = (\gamma_1, \dots, \gamma_m)$  and
  - $\text{Coord}(x_{j+1}) = (0, \dots, 0, \pm 1, 0, \dots, 0)$ .

Complexity

- $|x_1 \cdots x_j| \leq L$ , so  $\gamma \leq \kappa L^c$  can be stored in logspace.
- $m(L-1)$  total evaluations of the polynomials  $p_i$ .
- Each evaluation of  $p_i$  requires arithmetic with  $O(\log L)$ -bit numbers, so can be performed in required space and time.



The algorithm – compute coordinates element by element.

- Denote  $w = x_1 \cdots x_L$ .
- Keep an array  $\gamma = (\gamma_1, \dots, \gamma_m)$  of coordinates in memory.
- At the end of step  $j$ ,  $\gamma$  holds the coordinates of  $x_1 \cdots x_j$ .
- For  $0 \leq j < L$ , compute  $\text{Coord}(x_1 \cdots x_j x_{j+1})$  using the  $p_i$  with
  - $\text{Coord}(x_1 \cdots x_j) = (\gamma_1, \dots, \gamma_m)$  and
  - $\text{Coord}(x_{j+1}) = (0, \dots, 0, \pm 1, 0, \dots, 0)$ .

Complexity

- $|x_1 \cdots x_j| \leq L$ , so  $\gamma \leq \kappa L^c$  can be stored in logspace.
- $m(L-1)$  total evaluations of the polynomials  $p_i$ .
- Each evaluation of  $p_i$  requires arithmetic with  $O(\log L)$ -bit numbers, so can be performed in required space and time.

The algorithm – compute coordinates element by element.

- Denote  $w = x_1 \cdots x_L$ .
- Keep an array  $\gamma = (\gamma_1, \dots, \gamma_m)$  of coordinates in memory.
- At the end of step  $j$ ,  $\gamma$  holds the coordinates of  $x_1 \cdots x_j$ .
- For  $0 \leq j < L$ , compute  $\text{Coord}(x_1 \cdots x_j x_{j+1})$  using the  $p_i$  with
  - $\text{Coord}(x_1 \cdots x_j) = (\gamma_1, \dots, \gamma_m)$  and
  - $\text{Coord}(x_{j+1}) = (0, \dots, 0, \pm 1, 0, \dots, 0)$ .

Complexity

- $|x_1 \cdots x_j| \leq L$ , so  $\gamma \leq \kappa L^c$  can be stored in logspace.
- $m(L - 1)$  total evaluations of the polynomials  $p_i$ .
- Each evaluation of  $p_i$  requires arithmetic with  $O(\log L)$ -bit numbers, so can be performed in required space and time.

## Corollary

The compressed word problem in every finitely generated nilpotent group is decidable in (sub)cubic time.

**Note.** Haubold, Lohrey, Mathissen had already observed that the compressed word problem is decidable in polynomial time via embedding in  $UT_n(\mathbb{Z})$ .

# Subgroup membership and matrix reduction

# Matrix notation

Let  $G$  have Mal'cev basis  $\{a_1, \dots, a_m\}$ ,  
subgroup  $H \leq G$  be given as  $H = \langle h_1, \dots, h_n \rangle$ .

$$\left\{ \begin{array}{ccc} h_1 = a_1^{\alpha_{11}} & \cdots & a_m^{\alpha_{1m}} \\ \vdots & & \vdots \\ h_n = a_1^{\alpha_{n1}} & \cdots & a_m^{\alpha_{nm}} \end{array} \right\} \longleftrightarrow \begin{pmatrix} \alpha_{11} & \cdots & \alpha_{1m} \\ \vdots & \ddots & \vdots \\ \alpha_{n1} & \cdots & \alpha_{nm} \end{pmatrix} = A.$$

- $\pi_i$  is the column of the first non-zero entry ('pivot') in row  $i$ .
- $(h_1, \dots, h_n)$  is in *standard form* if the matrix of coordinates  $A$  is in row-echelon form and entries above pivots are reduced.
- $(h_1, \dots, h_n)$  is *full* if for each  $1 \leq i \leq m$ , the subgroup  $H \cap \langle a_i, a_{i+1}, \dots, a_m \rangle$  is generated by  $\{h_j \mid \pi_j \geq i\}$ .

# Matrix notation

Let  $G$  have Mal'cev basis  $\{a_1, \dots, a_m\}$ ,  
subgroup  $H \leq G$  be given as  $H = \langle h_1, \dots, h_n \rangle$ .

$$\left\{ \begin{array}{ccc} h_1 = a_1^{\alpha_{11}} & \cdots & a_m^{\alpha_{1m}} \\ \vdots & & \vdots \\ h_n = a_1^{\alpha_{n1}} & \cdots & a_m^{\alpha_{nm}} \end{array} \right\} \longleftrightarrow \begin{pmatrix} \alpha_{11} & \cdots & \alpha_{1m} \\ \vdots & \ddots & \vdots \\ \alpha_{n1} & \cdots & \alpha_{nm} \end{pmatrix} = A.$$

- $\pi_i$  is the column of the first non-zero entry ('pivot') in row  $i$ .
- $(h_1, \dots, h_n)$  is in *standard form* if the matrix of coordinates  $A$  is in row-echelon form and entries above pivots are reduced.
- $(h_1, \dots, h_n)$  is *full* if for each  $1 \leq i \leq m$ , the subgroup  $H \cap \langle a_i, a_{i+1}, \dots, a_m \rangle$  is generated by  $\{h_j \mid \pi_j \geq i\}$ .

# Uniqueness of standard form

## Lemma [Sims]

Let  $H \leq G$ . There is a unique full sequence  $U = (h_1, \dots, h_s)$  that generates  $H$ . Further,

$$H = \{h_1^{\beta_1} \cdots h_s^{\beta_s} \mid \beta_i \in \mathbb{Z}\}$$

and  $s \leq m$ .

**Goal:** convert  $(h_1, \dots, h_n)$  to a full sequence in standard form generating the same subgroup.

# Uniqueness of standard form

## Lemma [Sims]

Let  $H \leq G$ . There is a unique full sequence  $U = (h_1, \dots, h_s)$  that generates  $H$ . Further,

$$H = \{h_1^{\beta_1} \cdots h_s^{\beta_s} \mid \beta_i \in \mathbb{Z}\}$$

and  $s \leq m$ .

**Goal:** convert  $(h_1, \dots, h_n)$  to a full sequence in standard form generating the same subgroup.



# Matrix operations

Define three operations on tuples  $(h_1, \dots, h_n)$  of elements of  $G$  by their corresponding operations on the associated matrix are:

- (1) swap row  $i$  with row  $j$ ;
- (2) replace row  $i$  by  $\text{Coord}(h_i h_j^N)$ ;
- (3) add or remove a trivial row.

All three of these operations preserve the subgroup  $\langle h_1, \dots, h_n \rangle$ .

# Row-reducing the matrix

Let  $A$  be an  $n \times m$  matrix. Similar to row-reducing a matrix over  $\mathbb{Z}$  (in fact, works same as over  $\mathbb{Z}$  in the first column).

- Identify pivot.
- Use the gcd of the pivot column to clear out the column.
- Number of operations  $\sim n$ .
- Repeat for each column ( $m$  times).
- Total number of operations  $\sim mn$ .

# Magnitude of entries may increase

There is an issue:

- When using the operation  $h_i \rightarrow h_i h_j^N$ , the magnitude of the largest entry may increase from  $M$  to  $M^d$ ,  $d = \text{degree of multiplication polynomials}$ .
- Greatest entry could be size  $\sim M^{d^{mn}}$ .

# Length bound for reduced matrix

## Lemma

Let  $h_1, \dots, h_n \in G$  and let  $R$  be the standard form of the associated matrix of coordinates. Then every entry,  $\alpha_{ij}$ , of  $R$  is bounded by

$$|\alpha_{ij}| \leq CL^K,$$

where  $L = |h_1| + \dots + |h_n|$  is the total length of the given elements, and  $K$  and  $C$  are constants depending on  $G$ .

# Computing standard form

## Lemma

There is an algorithm that, given  $h_1, \dots, h_n \in G$ , computes the standard form of the matrix of coordinates in space logarithmic in  $L = \sum_{i=1}^n |h_i|$  and in time  $O(L \log^3 L)$ .

- Start with  $m \times m$  matrix (constant size).
- Reduce to standard form.
- Add a row and reduce (still constant size).
- Repeat until all  $n$  rows accounted for.
- Size never goes beyond  $\sim 2m \times m$ . Entries are bounded.
- The size of the reduced matrix is  $m \times m$ .

# Computing standard form

## Lemma

There is an algorithm that, given  $h_1, \dots, h_n \in G$ , computes the standard form of the matrix of coordinates in space logarithmic in  $L = \sum_{i=1}^n |h_i|$  and in time  $O(L \log^3 L)$ .

- Start with  $m \times m$  matrix (constant size).
- Reduce to standard form.
- Add a row and reduce (still constant size).
- Repeat until all  $n$  rows accounted for.
- Size never goes beyond  $\sim 2m \times m$ . Entries are bounded.
- The size of the reduced matrix is  $m \times m$ .

# Computing standard form

## Lemma

There is an algorithm that, given  $h_1, \dots, h_n \in G$ , computes the standard form of the matrix of coordinates in space logarithmic in  $L = \sum_{i=1}^n |h_i|$  and in time  $O(L \log^3 L)$ .

- Start with  $m \times m$  matrix (constant size).
- Reduce to standard form.
- Add a row and reduce (still constant size).
- Repeat until all  $n$  rows accounted for.
- Size never goes beyond  $\sim 2m \times m$ . Entries are bounded.
- The size of the reduced matrix is  $m \times m$ .

# Computing standard form

## Lemma

There is an algorithm that, given  $h_1, \dots, h_n \in G$ , computes the standard form of the matrix of coordinates in space logarithmic in  $L = \sum_{i=1}^n |h_i|$  and in time  $O(L \log^3 L)$ .

- Start with  $m \times m$  matrix (constant size).
- Reduce to standard form.
- Add a row and reduce (still constant size).
- Repeat until all  $n$  rows accounted for.
- Size never goes beyond  $\sim 2m \times m$ . Entries are bounded.
- The size of the reduced matrix is  $m \times m$ .



# Computing standard form

## Lemma

There is an algorithm that, given  $h_1, \dots, h_n \in G$ , computes the standard form of the matrix of coordinates in space logarithmic in  $L = \sum_{i=1}^n |h_i|$  and in time  $O(L \log^3 L)$ .

- Start with  $m \times m$  matrix (constant size).
- Reduce to standard form.
- Add a row and reduce (still constant size).
- Repeat until all  $n$  rows accounted for.
- Size never goes beyond  $\sim 2m \times m$ . Entries are bounded.
- The size of the reduced matrix is  $m \times m$ .

# Computing standard form

## Lemma

There is an algorithm that, given  $h_1, \dots, h_n \in G$ , computes the standard form of the matrix of coordinates in space logarithmic in  $L = \sum_{i=1}^n |h_i|$  and in time  $O(L \log^3 L)$ .

- Start with  $m \times m$  matrix (constant size).
- Reduce to standard form.
- Add a row and reduce (still constant size).
- Repeat until all  $n$  rows accounted for.
- Size never goes beyond  $\sim 2m \times m$ . Entries are bounded.
- The size of the reduced matrix is  $m \times m$ .

# Computing standard form

## Lemma

There is an algorithm that, given  $h_1, \dots, h_n \in G$ , computes the standard form of the matrix of coordinates in space logarithmic in  $L = \sum_{i=1}^n |h_i|$  and in time  $O(L \log^3 L)$ .

- Start with  $m \times m$  matrix (constant size).
- Reduce to standard form.
- Add a row and reduce (still constant size).
- Repeat until all  $n$  rows accounted for.
- Size never goes beyond  $\sim 2m \times m$ . Entries are bounded.
- The size of the reduced matrix is  $m \times m$ .

## Theorem

Let  $G$  be a finitely generated nilpotent group.

Let  $h_1, \dots, h_n \in G$  and  $h \in G$ .

Denote  $L = |h| + |h_1| + \dots + |h_n|$  and  $H = \langle h_1, \dots, h_n \rangle$ .

- There is an algorithm that, decides whether or not  $h \in H$ .
- The algorithm runs in space  $O(\log L)$  and time  $O(L \log^3 L)$ .
- If  $h \in H$  the algorithm returns the unique expression  $h = g_1^{\gamma_1} \dots g_s^{\gamma_s}$ , where  $(g_1, \dots, g_s)$  is the unique full standard-form sequence for  $H$ , and the length of  $h$  is bounded by a degree  $2m(6c^3)^m$  polynomial function of  $L$ .

- $(h_1, \dots, h_n) \rightsquigarrow (g_1, \dots, g_s)$ .
- Denote  $\text{Coord}(h) = (\beta_1, \dots, \beta_m)$ .

- If  $\beta_l \neq 0$  for some  $1 \leq l < \pi_1$ , then  $h \notin H$ .
- If  $\text{Coord}_{\pi_1}(g_1) \nmid \beta_{\pi_1}$ , then  $h \notin H$ .
- Else, let

$$\gamma_1 = \frac{\beta_{\pi_1}}{\text{Coord}_{\pi_1}(g_1)} \quad h' = g_1^{-\gamma_1} h.$$

- Repeat, replacing  $h$  by  $h'$  and  $(g_1, \dots, g_s)$  by  $(g_2, \dots, g_s)$ .

- $(h_1, \dots, h_n) \rightsquigarrow (g_1, \dots, g_s)$ .
- Denote  $\text{Coord}(h) = (\beta_1, \dots, \beta_m)$ .
- If  $\beta_l \neq 0$  for some  $1 \leq l < \pi_1$ , then  $h \notin H$ .
- If  $\text{Coord}_{\pi_1}(g_1) \nmid \beta_{\pi_1}$ , then  $h \notin H$ .
- Else, let

$$\gamma_1 = \frac{\beta_{\pi_1}}{\text{Coord}_{\pi_1}(g_1)} \quad h' = g_1^{-\gamma_1} h.$$

- Repeat, replacing  $h$  by  $h'$  and  $(g_1, \dots, g_s)$  by  $(g_2, \dots, g_s)$ .

# Compressed word membership problem

## Theorem

There is an algorithm that, given compressed words  $\mathbb{A}_1, \dots, \mathbb{A}_n, \mathbb{B}$  over a fixed finitely generated nilpotent group  $G$ , decides in time polynomial in  $|\mathbb{B}| + |\mathbb{A}_1| + \dots + |\mathbb{A}_n|$  whether or not  $\text{eval}(\mathbb{B})$  belongs to the subgroup generated by  $\text{eval}(\mathbb{A}_1), \dots, \text{eval}(\mathbb{A}_n)$ .

Kernels, centralizers,  
conjugacy problem



# Computing the kernel and pre-image of a homomorphism

- Let  $G$  and  $H$  be disjoint finitely generated nilpotent groups.
- Let  $K = \langle g_1, \dots, g_n \rangle \leq G$
- We specify a homomorphism  $\phi : K \rightarrow H$  by a list of elements  $h_1, \dots, h_n \in H$  such that  $\phi(g_i) = h_i$  for  $i = 1, \dots, n$ .
- Denote  $L = |h| + \sum_{i=1}^m (|h_i| + |g_i|)$ .

## Theorem

There is an algorithm that, given an element  $h \in H$  guaranteed to be in the image of  $\phi$ ,

- (i) computes a generating set  $X$  for the kernel of  $\phi$ , and
- (ii) computes an element  $g \in G$  such that  $\phi(g) = h$ .

The algorithm runs in space  $O(\log L)$  and time  $O(L \log^3 L)$ .

# Computing subgroup presentation

## Theorem

Let  $G$  be a finitely presented nilpotent group. Let  $g_1, \dots, g_n$  be finite set of elements of  $G$ . Denote  $L = \sum_{i=1}^n |g_i|$ . There is an algorithm that computes a presentation for the subgroup  $\langle g_1, \dots, g_n \rangle$ . The algorithm runs in space  $O(\log L)$  and time  $O(L \log^3 L)$ .

- Let  $N = \langle x_1, \dots, x_n \rangle$  be the free nilpotent group of class  $c$ .
- Define  $\phi : N \rightarrow G$  by  $x_i \mapsto g_i$ .
- Compute  $\ker \phi$ .
- $N / \ker \phi \simeq \text{im} \phi \simeq \langle g_1, \dots, g_n \rangle$ .

# Presentation for compressed-word subgroups

## Theorem

- Let  $G$  be a finitely presented nilpotent group.
- Let  $\mathbb{A}_1, \dots, \mathbb{A}_n$  be a finite set of straight-line programs over  $G$ .
- Denote  $L = \sum_{i=1}^n |\mathbb{A}_i|$ .

There is an algorithm that

- computes a presentation for  $\langle \text{eval}(\mathbb{A}_1), \dots, \text{eval}(\mathbb{A}_n) \rangle$ ,
- runs in time polynomial in  $L$ , and
- the size of the presentation is bounded by a polynomial of  $L$ .

Note. Size of presentation = number of generators plus sum of the lengths of the relators.

# An example on encoding presentations for SLPs

- When working with SLPs, we get the relators as SLPs.
- How do we write down a presentation involving these relators?

**Example.** Suppose the following SLP is a relator.

$$\mathbb{A} = \{A_1 \rightarrow A_2 A_3; \quad A_2 \rightarrow A_3 A_4; \quad A_3 \rightarrow A_4 A_4; \quad A_4 \rightarrow x\}.$$

Then  $\text{eval}(\mathbb{A}) = x^5$  and  $|\text{eval}(\mathbb{A})| \sim 2^L$ .

To write a presentation using this relator we might do the following.

(1)  $\langle x | \text{xxxxx} \rangle$  (but the length here is  $\sim 2^L$ ), so bad. Or,

(2)  $\langle x | \mathbb{A} \rangle$  (but this mixes encodings), so bad.

(3)  $\left\langle x, a_1, a_2, a_3, a_4 \mid a_1 = 1, \begin{array}{ll} a_1 = a_2 a_3, & a_2 = a_3 a_4, \\ a_3 = a_4 a_4, & a_4 = x \end{array} \right\rangle$ . Size  $O(L)$ .

# An example on encoding presentations for SLPs

- When working with SLPs, we get the relators as SLPs.
- How do we write down a presentation involving these relators?

**Example.** Suppose the following SLP is a relator.

$$\mathbb{A} = \{A_1 \rightarrow A_2 A_3; \quad A_2 \rightarrow A_3 A_4; \quad A_3 \rightarrow A_4 A_4; \quad A_4 \rightarrow x\}.$$

Then  $\text{eval}(\mathbb{A}) = x^5$  and  $|\text{eval}(\mathbb{A})| \sim 2^L$ .

To write a presentation using this relator we might do the following.

- (1)  $\langle x | \text{xxxxx} \rangle$  (but the length here is  $\sim 2^L$ ), so bad. Or,
- (2)  $\langle x | \mathbb{A} \rangle$  (but this mixes encodings), so bad.
- (3)  $\left\langle x, a_1, a_2, a_3, a_4 \mid a_1 = 1, \begin{array}{l} a_1 = a_2 a_3, \quad a_2 = a_3 a_4, \\ a_3 = a_4 a_4, \quad a_4 = x \end{array} \right\rangle$ . Size  $O(L)$ .

# Conjugacy problem

- A group is *conjugately separable* if whenever two elements are not conjugate, there is a finite quotient in which they are not conjugate.
- Gives rise to an enumerative algorithm to decide CP.
- F.g. nilpotent groups are conjugately separable (Remeslennikov '69, Formanek '76).
- Sims '94 gave an algorithm based on matrix reductions and homomorphisms.
- Complexity not analysed.

## Theorem

- Let  $G$  be a f.p. nilpotent group with Mal'cev basis of length  $m$ .
- Let  $g \in G$ .
- Denote  $L = |g|$ .

There is an algorithm that

- computes a generating set  $X$  for the centralizer of  $g$  in  $G$ ,
- runs in space  $O(\log L)$  and time  $O(L \log^2 L)$ .
- $X$  contains at most  $m$  elements, and
- there is a degree  $(6mc^2)^{m^2}$  polynomial function of  $L$  that bounds the length of each element of  $X$ .

# The conjugacy problem is logspace decidable

## Theorem

- Let  $G$  be a finitely presented nilpotent group.
- Let  $g, h \in G$  be given as words.
- Denote  $L = |g| + |h|$ .

There is an algorithm that

- (i) produces  $u \in G$  such that  $g = u^{-1}hu$ , or
- (ii) determines that no such element  $u$  exists,
- runs in space  $O(\log L)$  and time  $O(L \log^2 L)$ , and
- the word length of  $u$  is bounded by a degree  $2^m(6mc^2)^{m^2}$  polynomial function of  $L$ .



# Compressed-word CP is polynomial-time decidable

## Theorem

Let  $G$  be a finitely presented nilpotent group. There is an algorithm that, given two straight-line programs  $\mathbb{A}$  and  $\mathbb{B}$  over  $G$ , determines in time polynomial in  $n = |\mathbb{A}| + |\mathbb{B}|$  whether or not  $\text{eval}(\mathbb{A})$  and  $\text{eval}(\mathbb{B})$  are conjugate in  $G$ . If so, a straight-line program over  $G$  of size polynomial in  $n$  producing a conjugating element is returned.

# Presentation-uniform algorithms

# Presentation-uniform algorithms

Main issue: given an arbitrary presentation of a nilpotent group, to use the above algorithms, one needs to find a “good” presentation first.

## Theorem

Let  $c, r$  be fixed. There is a polynomial time algorithm that, given a group presentation  $\langle X \mid R \rangle$  for  $G$  in the class of  $r$ -generated class  $\leq c$  nilpotent groups, produces a “good” presentation for  $G$ .

## Corollary

Let  $\Pi$  denote any of the problems (I)–(VI). For all  $c, r \in \mathbb{N}$ , there is a polynomial time algorithm that, given a finite presentation  $\langle X|R \rangle$  of a group in  $\mathcal{N}_{c,r}$  and input of  $\Pi$  as words in  $X$ , solves  $\Pi$  in  $\langle X|R \rangle$  on that input.

- (I) Compute Mal'cev normal form.
- (II) Membership problem.
- (III) Compute the kernel of a homomorphism.
- (IV) Compute subgroup presentations.
- (V) Compute the centralizer of an element.
- (VI) Conjugacy (search) problem.

Free stuff

Theorem [K.Bou-Rabee, D.Studenmund 2014]

Let  $G$  be a finitely generated nilpotent group. There is a polynomial  $P(n)$  such that the ball  $B_n$  in the Cayley graph of  $G$  is discriminated in a finite group of order  $\leq P(n)$ .

Add our poly bounds, obtain

### Theorem

Let  $G$  be a finitely generated nilpotent group. There is a polynomial  $R$  such that  $g, h \in G$  are conjugate in  $G$  if and only if their images are conjugate in some finite quotient  $\bar{G}$  of  $G$  with  $|\bar{G}| \leq R(|g| + |h|)$ .

### Theorem

Let  $G$  be a finitely generated nilpotent group. There is a polynomial  $S$  such that  $h \in G$  belongs to a subgroup generated by  $h_1, \dots, h_k \in G$  if and only if the same is true for their images in some finite quotient  $\bar{G}$  of  $G$  with  $|\bar{G}| \leq S(|g| + |h|)$ .

Add our poly bounds, obtain

### Theorem

Let  $G$  be a finitely generated nilpotent group. There is a polynomial  $R$  such that  $g, h \in G$  are conjugate in  $G$  if and only if their images are conjugate in some finite quotient  $\bar{G}$  of  $G$  with  $|\bar{G}| \leq R(|g| + |h|)$ .

### Theorem

Let  $G$  be a finitely generated nilpotent group. There is a polynomial  $S$  such that  $h \in G$  belongs to a subgroup generated by  $h_1, \dots, h_k \in G$  if and only if the same is true for their images in some finite quotient  $\bar{G}$  of  $G$  with  $|\bar{G}| \leq S(|g| + |h|)$ .



Add our poly bounds, obtain

### Theorem

Let  $G$  be a finitely generated nilpotent group. There is a polynomial  $R$  such that  $g, h \in G$  are conjugate in  $G$  if and only if their images are conjugate in some finite quotient  $\bar{G}$  of  $G$  with  $|\bar{G}| \leq R(|g| + |h|)$ .

### Theorem

Let  $G$  be a finitely generated nilpotent group. There is a polynomial  $S$  such that  $h \in G$  belongs to a subgroup generated by  $h_1, \dots, h_k \in G$  if and only if the same is true for their images in some finite quotient  $\bar{G}$  of  $G$  with  $|\bar{G}| \leq S(|g| + |h|)$ .

# Conjugacy in relatively hyperbolic groups

## Theorem [I.Bumagin 2014]

Conjugacy (search) problem is polynomial time solvable in relatively hyperbolic groups if it is solvable in polynomial time in each parabolic subgroup.

Add our results, get

## Theorem

Conjugacy (search) problem is polynomial time solvable in groups hyperbolic relative to nilpotent subgroups.

# Conjugacy in relatively hyperbolic groups

## Theorem [I.Bumagin 2014]

Conjugacy (search) problem is polynomial time solvable in relatively hyperbolic groups if it is solvable in polynomial time in each parabolic subgroup.

Add our results, get

## Theorem

Conjugacy (search) problem is polynomial time solvable in groups hyperbolic relative to nilpotent subgroups.

Not so free stuff

# Further developments

Work in progress (J.M, A.M, A.N., S.V., K.Blaney, A.Garreta, F.Gul, D.Ovchinnikov, M.Sohrabi):

- Finite separability questions.
- Algorithms to compute torsion subgroup and isolators.
- Algorithms to compute intersections of subgroups and cosets.
- Algorithms to solve subgroup conjugacy, simultaneous conjugacy, to compute normalizers.
- Distortion of embeddings into  $UT(n, \mathbb{Z})$ .
- (Un)solvability of systems of quadratic equations over nilpotent groups.
- Fast practical algorithms in generalized Heisenberg groups.

# Further developments

Work in progress (J.M, A.M, A.N., S.V., K.Blaney, A.Garreta, F.Gul, D.Ovchinnikov, M.Sohrabi):

- Finite separability questions.
- Algorithms to compute torsion subgroup and isolators.
- Algorithms to compute intersections of subgroups and cosets.
- Algorithms to solve subgroup conjugacy, simultaneous conjugacy, to compute normalizers.
- Distortion of embeddings into  $UT(n, \mathbb{Z})$ .
- (Un)solvability of systems of quadratic equations over nilpotent groups.
- Fast practical algorithms in generalized Heisenberg groups.

# Further developments

Work in progress (J.M, A.M, A.N., S.V., K.Blaney, A.Garreta, F.Gul, D.Ovchinnikov, M.Sohrabi):

- Finite separability questions.
- Algorithms to compute torsion subgroup and isolators.
- Algorithms to compute intersections of subgroups and cosets.
- Algorithms to solve subgroup conjugacy, simultaneous conjugacy, to compute normalizers.
- Distortion of embeddings into  $UT(n, \mathbb{Z})$ .
- (Un)solvability of systems of quadratic equations over nilpotent groups.
- Fast practical algorithms in generalized Heisenberg groups.

# Further developments

Work in progress (J.M, A.M, A.N., S.V., K.Blaney, A.Garreta, F.Gul, D.Ovchinnikov, M.Sohrabi):

- Finite separability questions.
- Algorithms to compute torsion subgroup and isolators.
- Algorithms to compute intersections of subgroups and cosets.
- Algorithms to solve subgroup conjugacy, simultaneous conjugacy, to compute normalizers.
- Distortion of embeddings into  $UT(n, \mathbb{Z})$ .
- (Un)solvability of systems of quadratic equations over nilpotent groups.
- Fast practical algorithms in generalized Heisenberg groups.



# Further developments

Work in progress (J.M, A.M, A.N., S.V., K.Blaney, A.Garreta, F.Gul, D.Ovchinnikov, M.Sohrabi):

- Finite separability questions.
- Algorithms to compute torsion subgroup and isolators.
- Algorithms to compute intersections of subgroups and cosets.
- Algorithms to solve subgroup conjugacy, simultaneous conjugacy, to compute normalizers.
- Distortion of embeddings into  $UT(n, \mathbb{Z})$ .
- (Un)solvability of systems of quadratic equations over nilpotent groups.
- Fast practical algorithms in generalized Heisenberg groups.

# Further developments

Work in progress (J.M, A.M, A.N., S.V., K.Blaney, A.Garreta, F.Gul, D.Ovchinnikov, M.Sohrabi):

- Finite separability questions.
- Algorithms to compute torsion subgroup and isolators.
- Algorithms to compute intersections of subgroups and cosets.
- Algorithms to solve subgroup conjugacy, simultaneous conjugacy, to compute normalizers.
- Distortion of embeddings into  $UT(n, \mathbb{Z})$ .
- (Un)solvability of systems of quadratic equations over nilpotent groups.
- Fast practical algorithms in generalized Heisenberg groups.

# Further developments

Work in progress (J.M, A.M, A.N., S.V., K.Blaney, A.Garreta, F.Gul, D.Ovchinnikov, M.Sohrabi):

- Finite separability questions.
- Algorithms to compute torsion subgroup and isolators.
- Algorithms to compute intersections of subgroups and cosets.
- Algorithms to solve subgroup conjugacy, simultaneous conjugacy, to compute normalizers.
- Distortion of embeddings into  $UT(n, \mathbb{Z})$ .
- (Un)solvability of systems of quadratic equations over nilpotent groups.
- Fast practical algorithms in generalized Heisenberg groups.

# Further developments

Work in progress (J.M, A.M, A.N., S.V., K.Blaney, A.Garreta, F.Gul, D.Ovchinnikov, M.Sohrabi):

- Finite separability questions.
- Algorithms to compute torsion subgroup and isolators.
- Algorithms to compute intersections of subgroups and cosets.
- Algorithms to solve subgroup conjugacy, simultaneous conjugacy, to compute normalizers.
- Distortion of embeddings into  $UT(n, \mathbb{Z})$ .
- (Un)solvability of systems of quadratic equations over nilpotent groups.
- Fast practical algorithms in generalized Heisenberg groups.