

Optimal Security Inspection with a Single-server Queue

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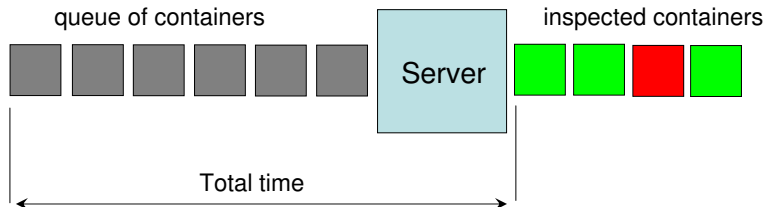
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- Motivation
- Formulation of security inspection problem
- Approach of Riemann boundary-value problems for analytic functions to Wiener-Hopf integral equation
- Optimization problem for distribution parameters
- Examples with frequently used distribution
- Conclusions

1 Passenger screening at airports:

Randomized security inspection versus deterministic profiling systems, e.g., Computer Assisted Passenger Prescreening System (CAPPS), introduced in 1999

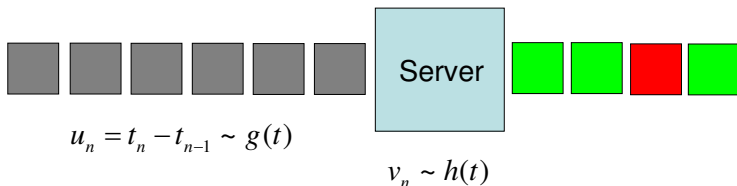
2 Container examination at ports



Queueing Process

- 1 $u_n = t_n - t_{n-1}$ = interarrival time of the n^{th} entity,
 $u_n \sim g(t) \begin{cases} = 0, & t < 0 \\ \geq 0, & t \geq 0 \end{cases}$
- 2 v_n = inspection (service) time for the n^{th} entity,
 $v_n \sim h(t) \begin{cases} = 0, & t < 0 \\ \geq 0, & t \geq 0 \end{cases}$
- 3 w_n = queue waiting time for the n^{th} entity to be inspected.

$$w_{n+1} = \max \{ w_n + v_n - u_{n+1}, 0 \}, \quad n \in \mathbb{N},$$



Steady State of Queueing Process

- $u_n - v_{n+1} \sim k(t) = \int_{-\infty}^{\infty} h(t + \tau) g(\tau) d\tau$

$$f_{n+1}(t) = \int_0^{\infty} k(t - \tau) f_n(\tau) d\tau + F_n(0) k(t), \quad t \geq 0$$

- For $n \rightarrow \infty$, $f_n(t) \rightarrow f(t)$ and $F_n(0) \rightarrow F(0) = 1 - \int_0^{\infty} f(t) dt$

- **Wiener-Hopf integral equation**

$$f(t) - \int_0^{\infty} k(t - \tau) f(\tau) d\tau = F(0) k(t), \quad t \geq 0$$

- System stability condition $E[v] < E[u]$

Performance Functionals

- 1 \mathcal{H} = set of nonnegative random variables

$$v + c \in \mathcal{H} \quad \forall v \in \mathcal{H} \text{ and } \forall c \in \mathbb{R}^+$$

- 2 $\mathcal{F}(v)$ = performance functional

$$\mathcal{F}(v) \leq \mathcal{F}(v + c) \quad \forall v \in \mathcal{H} \text{ and } \forall c \in \mathbb{R}^+$$

- The percentage of entities subjected to the security inspection with time greater than a specified threshold T_1

$$\mathcal{F}(v) = \text{Prob}\{v \geq T_1\} = \int_{T_1}^{\infty} h(t) dt$$

- The minimal inspection time specified for $\alpha * 100\%$ percentage of all entities

$$\mathcal{F}(v) = \inf \{t \mid \text{Prob}\{v \geq t\} \geq \alpha\}$$

Problem Formulation

Maximize the performance functional subject to a constraint on the total time spent in the system

$$\max_{v \in \mathcal{H}} \mathcal{F}(v)$$

s.t.

$$f(t) - \int_0^\infty k(t - \tau) f(\tau) d\tau = F(0) k(t), \quad t \geq 0,$$

$$E[v + w] \leq T, \quad T \in \mathbb{R}^+ \quad (\text{expected time in the system})$$

$$E[v] < E[u] \quad (\text{stability condition})$$

(calculus of variations problem with isoperimetric constraints)

Exponential Interarrival time

$$u \sim \lambda e^{-\lambda t}, t \geq 0 \quad \Rightarrow \quad k(t) = \lambda \int_{-\infty}^{\infty} h(t + \tau) e^{-\lambda t} d\tau$$

$$f(t) - \int_0^{\infty} k(t - \tau) f(\tau) ds = F(0) k(t), \quad t \geq 0$$

Three methods to derive the steady-state waiting-time distribution for a single-server queue:

- (a) The method of embedded Markov chains (Cohen);
- (b) The method of Riemann-Hilbert boundary-value problems for moment generation functions (Fayolle and Iasnogorodski, 1979, and further Cohen and Boxma, 1983);
- (c) The method of Wiener-Hopf integral equations (Lindley, 1952).

Waiting time for M/G/1/FCFS Queue

Theorem

For interarrival time $u \sim \lambda e^{-\lambda t}$, $t \geq 0$, and arbitrary inspection time, v , the distribution of the steady-state waiting-time, w , has the probability atom at $t = 0$

$$\Pr\{w = 0\} = 1 - \lambda E[v],$$

and for $t > 0$, its probability density function, $f(t)$, is given by

$$f(t) = (1 - \lambda E[v]) \frac{i\lambda}{2\pi} \int_{-\infty}^{\infty} \frac{(1 - H^+(s)) e^{-ist}}{s - i\lambda(1 - H^+(s))} ds, \quad t > 0,$$

where $H^+(s) = \int_0^{\infty} h(\tau) e^{i s \tau} d\tau$ and $i = \sqrt{-1}$.

Sketch of the Proof

$$f(t) - \int_0^{\infty} k(t-\tau)f(\tau) d\tau = F(0)k(t) + f_-(t), \quad t \in \mathbb{R}.$$

Wiener-Hopf integral equation \rightarrow Fourier integral transform

$$\Phi^+(s) = \int_0^{\infty} f(t) e^{ist} dt, \quad \Phi^-(s) = \int_{-\infty}^0 f_-(t) e^{ist} dt, \quad s \in \mathbb{R},$$

$$K(s) = \int_{-\infty}^{\infty} k(t) e^{ist} dt = -\frac{i\lambda}{s - i\lambda} \int_0^{\infty} h(\tau) e^{is\tau} d\tau = -\frac{i\lambda}{s - i\lambda} H^+(s)$$

Riemann-boundary value problem (RBVP) for piece-wise analytic function $\Phi(z)$ in the complex plane with the branch cut along \mathbb{R} :

$$\Phi^+(s) [1 - K(s)] = F(0)K(s) + \Phi^-(s), \quad s \in \mathbb{R}$$

or

$$\Phi^+(s) = \frac{s - i\lambda}{s - i\lambda (1 - H^+(s))} \Phi^-(s) - \frac{i\lambda F(0) H^+(s)}{s - i\lambda (1 - H^+(s))}, \quad s \in \mathbb{R}.$$

Simplest Riemann-boundary Value Problem

RBVP on \mathbb{R} (applications in fluid mechanics, elasticity, etc.)

$$\Phi^+(s) = G(s) \Phi^-(s) + g(s), \quad s \in \mathbb{R}.$$

Factorization:

$$\frac{X^+(s)}{X^-(s)} = G(s) \implies \ln X^+(s) - \ln X^-(s) = \ln G(s)$$

Sokhotski formulas:

$$X^\pm(s) = \pm \frac{1}{2} \ln G(s) + \frac{1}{2\pi i} \int_{-\infty}^{+\infty} \frac{\ln G(t)}{t-s} dt, \quad s \in \mathbb{R}$$

$$\frac{\Phi^+(s)}{X^+(s)} = \frac{\Phi^-(s)}{X^-(s)} + \frac{g(s)}{X^+(s)}, \quad s \in \mathbb{R}.$$

$$\frac{\Phi^\pm(s)}{X^\pm(s)} = \pm \frac{g(s)}{2X^+(s)} + \frac{1}{2\pi i} \int_{-\infty}^{+\infty} \frac{g(t)}{X^+(t)} \frac{dt}{t-s}, \quad s \in \mathbb{R}$$

Sketch of the Proof (cont'd)

In this case, $G(s) = \frac{s-i\lambda}{s-i\lambda(1-H^+(s))}$ with $E[v] = \int_0^\infty t h(t) dt < \frac{1}{\lambda}$

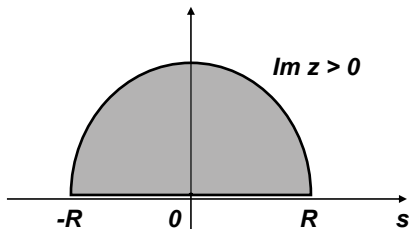
$$X^+(z) = \frac{1}{1 - i\lambda \left(\frac{1-H^+(z)}{z} \right)}, \quad \text{Im } z \geq 0,$$

$$X^-(z) = \frac{1}{z - i\lambda}, \quad \text{Im } z \leq 0,$$

Rouche's theorem: if $|A(z)| > |B(z)|$ for ∂D , then $A(z)$ and $A(z) + B(z)$ have the same number of zeros in D .

$$A(z) = 1 \text{ and } B(z) = \frac{1-H^+(z)}{z}.$$

$$1 > \lim_{s \rightarrow 0} \frac{1-H^+(s)}{s} = \lambda E[v]$$



Sketch of the Proof (cont'd)

RBVP on the infinite contour

$$\phi^+(s) = G(s) \phi^-(s) + g(s), \quad s \in \mathbb{R}.$$

Factorization:

$$G(s) = \frac{X^+(s)}{X^-(s)} = \frac{1}{1 - i\lambda \left(\frac{1 - H^+(s)}{s} \right)} = \frac{1}{\frac{1}{s - i\lambda}}$$

$$\frac{\phi^+(s)}{X^+(s)} - \frac{\phi^-(s)}{X^-(s)} = \frac{g(s)}{X^+(s)} = \psi^+(s) - \psi^-(s), \quad s \in \mathbb{R}.$$

$$\frac{\phi^+(s)}{X^+(s)} - \psi^+(s) = \frac{\phi^-(s)}{X^-(s)} - \psi^-(s) \equiv \text{const}$$

The solution to the RBVP takes on the form

$$\phi^+(s) = \frac{i\lambda F(0) (1 - H^+(s))}{s - i\lambda (1 - H^+(s))}$$

Positiveness of $f(t)$

$$B(s) = \frac{1-H^+(s)}{s} \text{ such that } |B(s)| < 1.$$

For $t > 0$:

$$f(t) = (1 - \lambda E[v]) \sum_{n=1}^{\infty} \psi_n(t), \quad \psi_n(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} B^n(s) e^{-ist} ds$$

$$\psi_1(t) = \text{Prob} \{v \geq t\}, \quad t > 0$$

$$\psi_n(t) = \underbrace{\int_{-\infty}^{+\infty} \dots \int_{-\infty}^{+\infty}}_{n-1} \psi_1 \left(t - \sum_{k=1}^{n-1} \tau_k \right) \prod_{k=1}^{n-1} \psi_1(\tau_k) d\tau_1 \dots d\tau_{n-1} > 0$$

$$\psi_n(t) \leq \lambda (\lambda E[v])^{n-1}$$

Optimal Security Inspection for M/G/1 Queue

Pollaczek-Khinchin formulas (corollary from the theorem):

$$E[w] = \frac{\lambda E[v^2]}{2(1 - \lambda E[v])}, \quad \text{var}[w] = \frac{\lambda E[v^3]}{3(1 - \lambda E[v])} + \left(\frac{\lambda E[v^2]}{2(1 - \lambda E[v])} \right)^2$$

Theorem (Optimal security inspection for M/G/1 queue)

The optimal security problem for M/G/1 queue reduces to

$$\max_{v \in \mathcal{H}} \mathcal{F}(v)$$

$$\text{s.t.} \quad E[v] \leq \frac{1}{\lambda} + T - \sqrt{\frac{1}{\lambda^2} + T^2 + \text{var}[v]}, \quad \text{var}[v] \in \left[0, \frac{2T}{\lambda} \right],$$

where $\text{var}[v]$ is the variance of the inspection time v .

Shifted-exponential Inspection Time

Inspection time, v , follows **shifted-exponential distribution** with the shift a and rate γ

$$h(t) = \begin{cases} 0, & t < a \\ \gamma e^{\gamma(a-t)}, & t \geq a \end{cases}$$

System stability condition reduces to $a + \frac{1}{\gamma} < \frac{1}{\lambda}$, and the steady-state waiting-time, w , is determined by

$$\Pr\{w = 0\} = 1 - \lambda \left(a + \frac{1}{\gamma} \right),$$

$$f(t) = \frac{\lambda}{2\pi} \left(1 - \lambda \left(a + \frac{1}{\gamma} \right) \right) \int_{-\infty}^{+\infty} \frac{(i + \frac{\gamma}{s} (e^{ias} - 1)) e^{-ist}}{s + i(\gamma - \lambda) - \frac{\lambda\gamma}{s} (e^{ias} - 1)} ds$$

for $t \geq 0$.

Shifted-exp. Inspection Time: Waiting Time

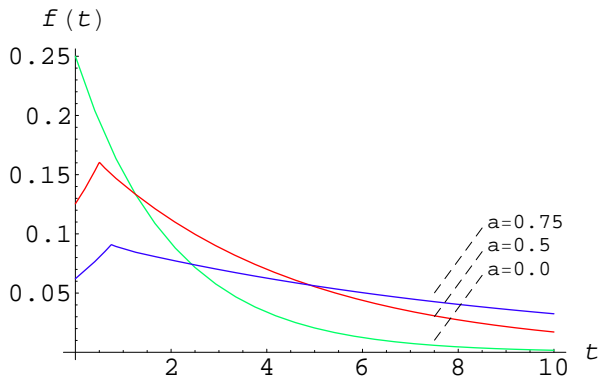


Figure: Density function $f(t)$ for $\lambda = 0.5$ and shifted-exponential inspection time with $\gamma = 1$, and $a = 0.0, 0.5, 0.75$

Shifted-exp. Inspection Time: Waiting Time

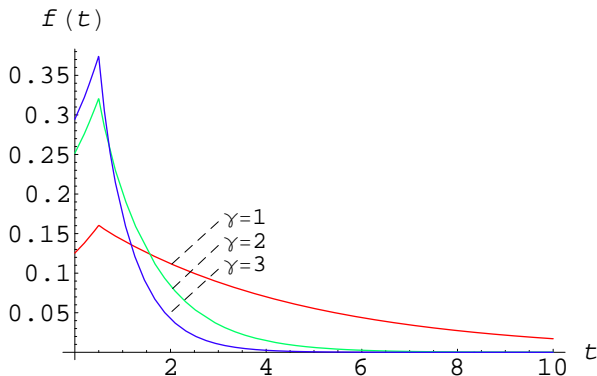


Figure: Density function $f(t)$ for $\lambda = 0.5$ and shifted-exponential inspection time with $a = 0.5$, and $\gamma = 1, 2, 3$

Shifted-exp. Inspection Time: Waiting Time

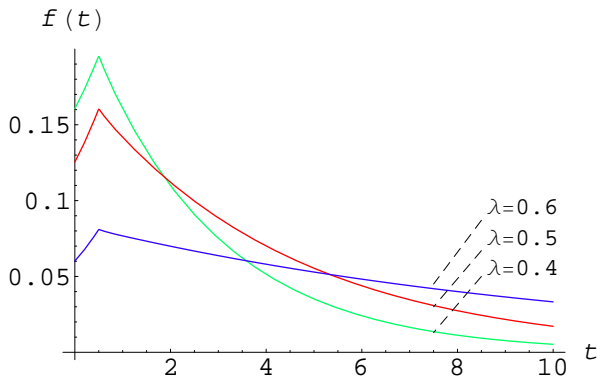


Figure: Density function $f(t)$ for $\lambda = 0.4, 0.5, 0.6$ and shifted-exponential inspection time with $a = 0.5$ and $\gamma = 1$

Shifted-exp. Inspection Time: Optimal Parameters

Performance functional: $\mathcal{F}(v) = \text{Prob}\{v \geq T_1\} = \int_{T_1}^{\infty} h(t) dt$

Let $d_1 = T + \frac{1}{\lambda} - \sqrt{\frac{1}{\lambda^2} + T^2}$ and $d_2 = \frac{T(1+\lambda T)}{1+\lambda T+\lambda^2 T^2}$

- 1 if $T_1 \geq d_2$, then $a = 0$ and $\gamma = \lambda + \frac{1}{T}$
- 2 If $d_1 \leq T_1 \leq d_2$, then

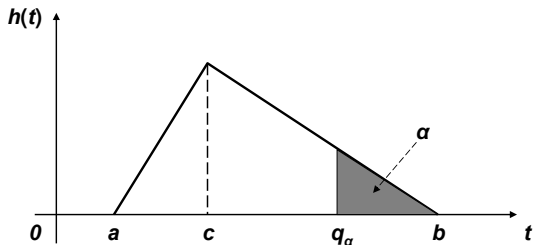
$$a = \frac{\frac{2T}{\lambda} - T_1 \left(\frac{1}{\lambda} + T\right) - \sqrt{\left(\frac{1}{\lambda^2} + T^2\right) \left(\frac{2(T_1 - T)}{\lambda} + 2T_1 T - T_1^2\right)}}{\frac{1}{\lambda} + T - T_1}$$

$$\gamma = \frac{\frac{1}{\lambda} + T - T_1}{\sqrt{\left(\frac{1}{\lambda^2} + T^2\right) \left(\frac{2(T_1 - T)}{\lambda} + 2T_1 T - T_1^2\right)}}$$

- 3 If $T_1 \leq d_1$, then $a = d_1$ and $\gamma \rightarrow \infty$.

Triangular Inspection Time

Inspection time, v , follows **triangular distribution** with parameters a , b and c



System stability condition: $a + b + c < \frac{3}{\lambda}$, and the function H^+ takes on the form

$$H^+(s) = -\frac{2 \left((b-c) e^{ias} + (c-a) e^{ibs} - (b-a) e^{ics} \right)}{(b-a)(c-a)(b-c) s^2}.$$

Triangular Inspection Time: Waiting Time

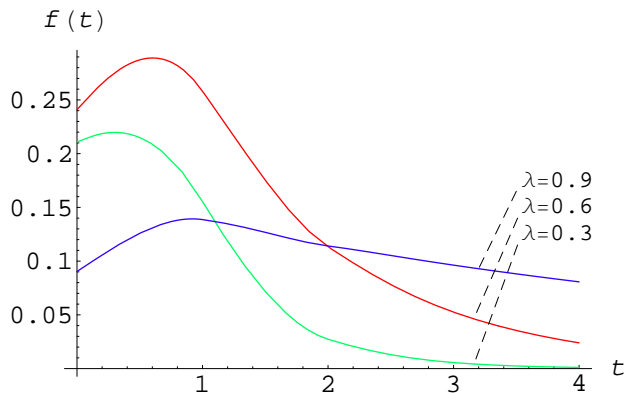


Figure: Density function $f(t)$ for $\lambda = 0.3, 0.6, 0.9$ and triangular inspection time with $a = 0, c = 1, b = 2$

Triangular Inspection Time: Waiting Time

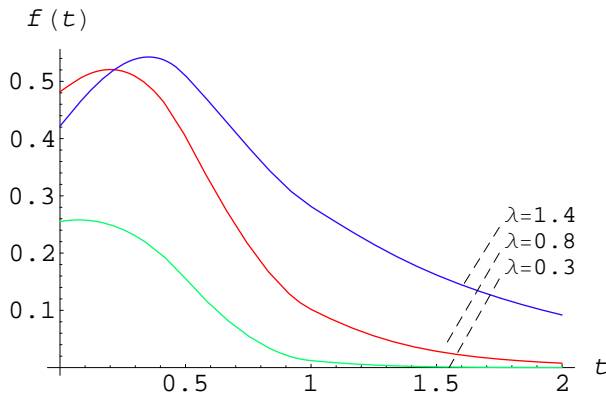


Figure: Density function $f(t)$ for $\lambda = 0.3, 0.8, 1.4$ and triangular inspection time with $a = 0, c = 0.5, b = 1$

Triangular Inspection Time: Optimal Security problem

Performance functional: $\mathcal{F}(v) = \inf \{t \mid \text{Prob} \{v \geq t\} \geq \alpha\}$

$$\mathcal{F}(a, b, c, \alpha) = \begin{cases} b - \sqrt{\alpha(b-c)(b-a)}, & \alpha \leq \frac{b-c}{b-a}, \\ a + \sqrt{(1-\alpha)(c-a)(b-a)}, & \alpha > \frac{b-c}{b-a}. \end{cases}$$

Optimal security problem: parameter optimization

$$F(\alpha, \lambda) = \max_{b \geq c \geq a \geq 0} \mathcal{F}(a, b, c, \alpha)$$

s.t.

$$\begin{aligned} \frac{1}{\lambda} + T - \sqrt{\frac{1}{\lambda^2} + T^2 + \frac{1}{18}(a^2 + b^2 + c^2 - ab - ac - bc)} \\ \leq \frac{1}{3}(a + b + c) \end{aligned}$$

Triangular Inspection Time: Numerical Analysis

$$F(\alpha, \lambda) = \max_{a,b,c} \inf \{t \mid \text{Prob} \{v \geq t\} \geq \alpha\} \text{ s.t. constraints}$$

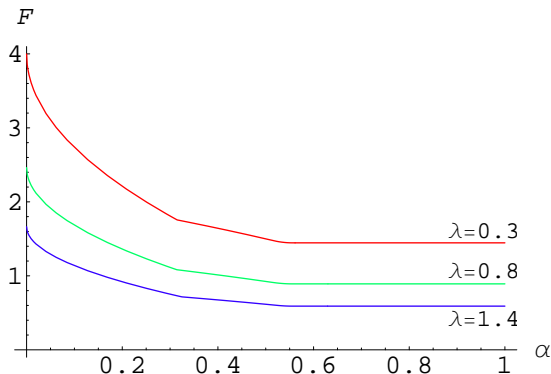


Figure: Optimal value of the performance functional as a function of α for $\lambda = 0.3, 0.8, 1.4$, and $T = 2$

Conclusions

- 1 Formalization of optimal security-inspection problem
- 2 Derivation of the Pollachek-Khinchin formulas for the M/G/1 queue in the framework of RBVP for analytic functions
- 3 Analytical treatment of the optimal security-inspection problem for the M/G/1 queue
- 4 Optimal security inspection for the M/G/1 queue and shifted-exponential and triangular inspection time

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