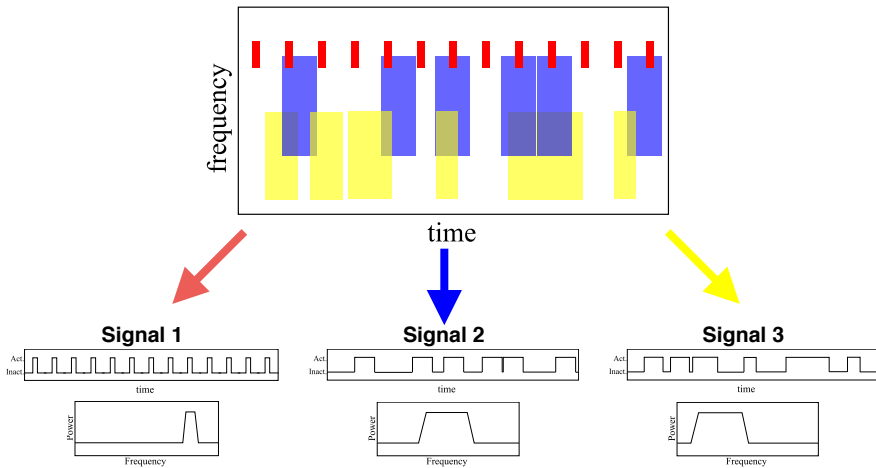
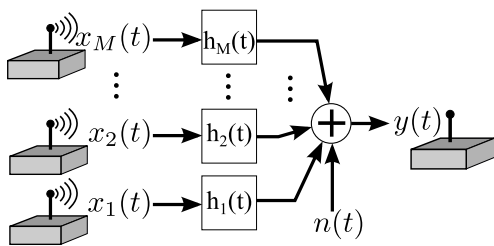


PROBLEM STATEMENT

- M transmitters are broadcasting in a bandwidth W
- Their transmissions are discontinuous in time
- Their transmissions are non-orthogonal in both time and frequency
- **Goal:** estimate each transmitter's signal parameters (activity in time, PSD, kurtosis) using a single sensor node



SYSTEM MODEL



M transmitters with modulations approximated by finite sum of linear modulations (AM, OFDM, etc.):

$$x_m(t) = \sum_{r=1}^{R_m} \sum_{k=-\infty}^{\infty} a_{m,r,k} p_{m,r}(t - kT_{m,r})$$

i.i.d. symbols pulse shape

Transmissions are discontinuous in time (periods of time where transmitter is "off", $a_{m,r,k} = 0$ for some k).

Sensor receives:

$$y(t) = \sum_{m=1}^M h_m(t) * x_m(t) + n(t)$$

TRISPECTRUM SLICES

After preprocessing to find I_{cl} groups whose samples in-time have statistically similar signal contributions [1] we have a slice of the trispectrum for each group $i=1, \dots, I_{cl}$:

$$S_{04}(f, v, i) = \sum_{m=1}^M |H_m(f)|^2 |H_m(v)|^2 S_{04}^{x_m}(f, v) c_{im} + S_{04}^n(f, v)$$

channel response m trispectrum slice of noise = 0
on/off

Trispectrum slice of signal m :

$$S_{04}^{x_m}(f, v) = \sum_{r=1}^{R_m} \frac{S_{04}^{a_{mr}}(f, v)}{T_{mr}} |P_{mr}(f)|^2 |P_{mr}(v)|^2$$

Trispectrum slice of symbols of sub-signal r of signal m :

$$\frac{S_{04}^{a_{mr}}(f, v)}{T_{mr}} = \frac{\text{cum}_4(a_{mrk}, a_{mrk}, a_{mrk}^*, a_{mrk}^*)}{T_{mr}} = k_{mr}$$

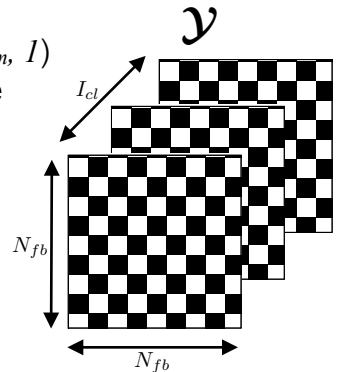
BLOCK TENSOR STRUCTURE

After discretizing the trispectrum slices into N_{fb} frequency bins

$$y_{jni} = \int_{(j-1)\Delta f}^{j\Delta f} \int_{(n-1)\Delta f}^{n\Delta f} S_{04}^y(f, v, i) df dv = \sum_{m=1}^M c_{im} \sum_{r=1}^{R_m} k_{mr} f_{mrj} f_{mrn}$$

we see the tensor has a rank- (R_m, R_m, I) block-partitioned tensor structure

$$\begin{aligned} \mathcal{Y} &= \sum_{m=1}^M \llbracket \mathbf{k}_m; \mathbf{F}_m, \mathbf{F}_m, [\mathbf{c}_m \dots \mathbf{c}_m] \rrbracket \\ &= \sum_{m=1}^M \sum_{r=1}^{R_m} k_{mr} \cdot \mathbf{f}_{mr} \circ \mathbf{f}_{mr} \circ \mathbf{c}_m \\ &= \sum_{m=1}^M \mathbf{F}_m \cdot \text{diag}(\mathbf{k}_m) \cdot \mathbf{F}_m^T \circ \mathbf{c}_m \end{aligned}$$



$$\mathcal{Y} = \mathbf{f}_{11}^{\mathbf{c}_1} + \mathbf{f}_{12}^{\mathbf{c}_1} + \dots + \mathbf{f}_{MR_M}^{\mathbf{c}_M}$$

- Decomposing the tensor will allow us to estimate the desired parameters:

$\mathbf{F}_m \rightarrow$ PSD, $\mathbf{c}_m \rightarrow$ active/inactive sequence, $\mathbf{k}_m \rightarrow$ kurtosis

FACTOR MATRIX ESTIMATION

- Block partition decomposition algorithms [2] assume prior knowledge of the partitioning.
- Our scenario: partitioning unknown, so we reformulate the tensor structure as

$$\mathcal{Y} = \llbracket \mathbf{k}; \mathbf{F}, \mathbf{F}, \mathbf{C}\mathbf{W} \rrbracket = \llbracket \mathbf{F}, \mathbf{F}, \mathbf{C}\mathbf{W} \rrbracket$$

where \mathbf{W} is a sparse block-diagonal selection matrix.

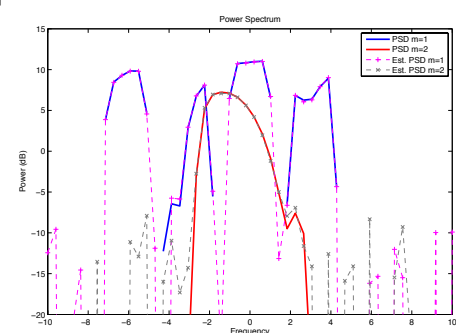
- Estimate factor matrices and partitions by solving:

$$[\hat{\mathbf{F}}, \hat{\mathbf{C}}, \hat{\mathbf{W}}] = \arg \min_{\mathbf{F}, \mathbf{C}, \mathbf{W}} \frac{1}{2} \|\mathcal{Y} - \llbracket \mathbf{F}, \mathbf{F}, \mathbf{C}\mathbf{W} \rrbracket\|_2^2 + \lambda \|\mathbf{W}\|_1$$

- For each column, \mathbf{w}_r , fix $w_{mr} = 0$ if $m \neq \max_m |w_{mr}|$
- Redo minimization to find final estimates of \mathbf{F} , \mathbf{C} , and \mathbf{k}

SIMULATION

- We ran limited simulations at high SNR with an 8-tap random Rayleigh fading channel to test the operation of the algorithm.
- Algorithm successfully estimated signal parameters for appropriately selected L1 regularization coefficient for overlapping signals using Root Raised Cosine pulse shape ($W=80\text{MHz}$).
- Tested Configurations:
 - ▶ $M=2, R_m=\{1,1\}$, identical bandwidths, different f_c
 - ▶ $M=4, R_m=\{1,1,1,1\}$, identical bandwidths, different f_c
 - ▶ $M=2, R_m=\{3 \text{ narrowband}, 2 \text{ wideband}\}$, different f_c
- More simulations need to be run to fully quantify the algorithm performance.



Example PSD Estimate

FUTURE WORK

- Improve decomposition speed and scalability
- Selection of L1 regularization coefficient
- Extensive Monte Carlo simulations to quantify algorithm performance.