## Ma 221

## CHAPTER 4 - Linear Differential Equations

We shall now begin a detailed study of the second-order linear differential equation

$$
a(x) y^{\prime \prime}+b(x) y^{\prime}+c(x) y=f(x)
$$

## Fundamental theory of second-order linear equations

The following theorem gives information concerning the existence of solutions of second-order linear differential equations. We shall accept it as valid without proof.

Theorem 1: Consider the Initial Value Problem

$$
\begin{gathered}
\text { D.E. } a(x) y^{\prime \prime}+b(x) y^{\prime}+c(x) y=f(x) \\
\text { I.C. } y\left(x_{0}\right)=y_{0} \quad y^{\prime}\left(x_{0}\right)=y_{0}^{\prime}
\end{gathered}
$$

If $a(x), b(x), c(x), f(x)$ are all continuous functions in the interval $I$, where $x_{0} \in I$ and $a(x) \neq 0$ for all $x$ in $I$, then the IVP possesses a unique solution. This solution has a continuous derivative and is defined throughout I.

## Example

$$
\begin{array}{rlrl}
\text { D.E. } a(x) y^{\prime \prime}+b(x) y^{\prime}+c(x) y & =0 & & \text { Homogeneous Equation } \\
\text { I.C. } y\left(x_{0}\right) & =0 & y^{\prime}\left(x_{0}\right)=0
\end{array}
$$

One solution is $y(x) \equiv 0$. Theorem $1 \Rightarrow$ only solution is $y \equiv 0$.
We shall assume from now on that $a, b, c$, and $f$ are continuous in a common interval $I$ and $a(x) \neq 0$ in $I$ so that Theorem 1 holds.

Notation: Let

$$
L[y] \equiv a(x) y^{\prime \prime}+b(x) y^{\prime}+c(x) y .
$$

Then $L[2]=2 c(x)$

$$
L[3 x]=3 b(x)+3 x c(x) .
$$

With this notation the second order differential equation $a(x) y^{\prime \prime}+b(x) y^{\prime}+c(y) y=f(x)$ can be written as $L[y]=f(x)$. The homogeneous case is when $f(x)=0 \Rightarrow L[y]=0$. This is called the homogeneous equation. If $f(x) \neq 0 \Rightarrow$ a nonhomogeneous equation. $L[y]$ is called a linear operator because it has the following property.

Theorem 2:

$$
L\left[c_{1} y_{1}+c_{2} y_{2}\right]=c_{1} L\left[y_{1}\right]+c_{2} L\left[y_{2}\right]
$$

where $y_{1}$ and $y_{2}$ are any twice differential functions and $c_{1}$ and $c_{2}$ are any constants.
Proof:

$$
\begin{aligned}
L\left[c_{1} y_{1}+c_{2} y_{2}\right] & =a(x)\left(c_{1} y_{1}+c_{2} y_{2}\right)^{\prime \prime}+b(x)\left(c_{1} y_{1}+c_{2} y_{2}\right)^{\prime}+c(x)\left(c_{1} y_{1}+c_{2} y_{2}\right) \\
& =a(x)\left(c_{1} y_{1}^{\prime \prime}+c_{2} y_{2}^{\prime \prime}\right)+b(x)\left(c_{1} y_{1}^{\prime}+c_{2} y_{2}^{\prime}\right)+c(x)\left(c_{1} y_{1}+c_{2} y_{2}\right) \\
& =c_{1}\left[a(x) y_{1}^{\prime \prime}+b(x) y_{1}^{\prime}+c(x) y_{1}\right]+c_{2}\left[a(x) y_{2}^{\prime \prime}+b(x) y_{2}^{\prime}+c(x) y_{2}\right] \\
\Rightarrow L\left[c_{1} y_{1}+c_{2} y_{2}\right]=c_{1} L\left[y_{1}\right] & +c_{2} L\left[y_{2}\right]
\end{aligned}
$$

## Properties of solutions of second order equations.

Theorem 3: If $y_{1}(x)$ and $y_{2}(x)$ are solutions of the homogeneous equation $L[y]=0$, then $y=c_{1} y_{1}(x)+c_{2} y_{2}(x)$ is also a solution.
Proof. $L\left[c_{1} y_{1}+c_{2} y_{2}\right]=c_{1} L\left[y_{1}\right]+c_{2} L\left[y_{2}\right]$ from above. Since $y_{1}$ is a solution of $L[y]=0 \Rightarrow L\left[y_{1}\right]=0$. Similarly $L\left[y_{2}\right]=0$.
Hence $L\left[c_{1} y_{1}+c_{2} y_{2}\right]=c_{1} L\left[y_{1}\right]+c_{2} L\left[y_{2}\right]=0+0=0 \Rightarrow y=c_{1} y_{1}+c_{2} y_{2}$ is also a solution of $L(y)=0$.

Example $y^{\prime \prime}-9 y=0 \quad e^{3 x}$ and $e^{-3 x}$ are solutions. Theorem $3 \Rightarrow y=c_{1} e^{3 x}+c_{2} e^{-3 x}$ is also a solution.

Remark. We desire to be able to find the general solution of $L[y]=0$. The above theorem tells us that if $y_{1}$ and $y_{2}$ are solutions, then $c_{1} y_{1}+c_{2} y_{2}$ is a solution, but it does not tell us that this is the general solution. In order to know when one has a general solution it is necessary to introduce the concept of the linear independence of two functions.

Definition: Two functions $y_{1}(x)$ and $y_{2}(x)$ are called linearly dependent (LD) in an interval $I$ if it is possible to find two constants $c_{1}$ and $c_{2}$, not both zero, so that

$$
c_{1} y_{1}(x)+c_{2} y_{2}(x)=0 \quad \forall x \in I .
$$

Two functions are called linearly independent (LI) if they are not linearly dependent, i.e., if

$$
c_{1} y_{1}(x)+c_{2} y_{2}(x)=0 \quad \forall x \in I \Rightarrow c_{1}=c_{2}=0 .
$$

Remark. If two functions are $L D$ in $I \Rightarrow$ one of the functions is equal to a constant times the other in $I$.

Example (a) $x, 2 x$ are $L D$ in any interval $I$, since

$$
(-2) x+(1) 2 x=0 \quad \forall x \in I
$$

(b) $x^{2}, x$ are $L I$ in any interval $I$, since

$$
c_{1} x^{2}+c_{2} x=0 \quad \forall x \in I
$$

is impossible because this equation has at most two real roots in $I$. Thus, we must have $c_{1}=c_{2}=0$.
(c) Two functions are $L D$ if one of them is the zero function. If $y_{1} \equiv 0$, then

$$
c_{1} y_{1}+0 \cdot y_{2}=c_{1} 0+0 \cdot y \equiv 0 \forall x \in I
$$

and any $c_{1} \neq 0$.
(d) If $\lambda_{1} \neq \lambda_{2}$, then $e^{\lambda_{1} x}$ and $e^{\lambda_{2} x}$ are LI for if

$$
\Rightarrow \quad c_{1} e^{\lambda_{1} x}+c_{2} e^{\lambda_{2} x} \equiv 0 .
$$

But $c_{1}$ is a constant and therefore the last equation $\Rightarrow \lambda_{1}=\lambda_{2}$, which is a contradiction.

## Facts from algebra needed in the proofs of the next theorems.

1. $\left.\begin{array}{l}d_{1} x+d_{2} y=d_{3} \\ e_{1} x+e_{2} y=e_{3}\end{array}\right\}$ has a unique solution $\Leftrightarrow\left|\begin{array}{ll}d_{1} & d_{2} \\ e_{1} & e_{2}\end{array}\right| \neq 0$

If $d_{3}=e_{3}=0$ and $\operatorname{det} \neq 0 \Rightarrow x=y=0$ is the only solution.
2. $\left.\begin{array}{l}d_{1} x+d_{2} y=0 \\ e_{1} x+e_{2} y=0\end{array}\right\}$ has nontrivial solution. $\Leftrightarrow\left|\begin{array}{ll}d_{1} & d_{2} \\ e_{1} & e_{2}\end{array}\right|=0$

Definition: The Wronskian of two differentiable functions $y_{1}$ and $y_{2}$ is defined to be

$$
W\left[y_{1}(x), y_{2}(x)\right] \equiv\left|\begin{array}{ll}
y_{1}(x) & y_{2}(x) \\
y_{1}^{\prime}(x) & y_{2}^{\prime}(x)
\end{array}\right| \equiv y_{1}(x) y_{2}^{\prime} \quad(x)-y_{1}^{\prime}(x) y_{2}(x) .
$$

Theorem 4. If $W\left[y_{1}(x), y_{2}(x)\right]$ is different from zero for at least one point in an interval $I$, then $y_{1}(x)$ and $y_{2}(x)$ are $L I$ in $I$.

Proof. Suppose $y_{1}, y_{2}$ are $L D$. Then $\exists$ constants $c_{1}, c_{2}$, not both zero, such that

$$
\left.\begin{array}{l}
c_{1} y_{1}(x)+c_{2} y_{2}(x) \equiv 0 \\
c_{1} y_{1}^{\prime}(x)+c_{2} y_{2}^{\prime}(x) \equiv 0
\end{array}\right\}
$$

By assumption these two equations have a nontrivial solution $c_{1}, c_{2}$ at each point $x$ in $I$. Therefore the determinant of the coefficients (by 2) must be zero for each $x$. But the determinant of coefficients $=W\left[y_{1}(x), y_{2}(x)\right]$ and $W \neq 0$ for at least one point in $\mathrm{I} . \Rightarrow y_{1}$ and $y_{2}$ are not $L D$.

Corollary. If $y_{1}, y_{2}$ are $L D$ in $I \Rightarrow W\left[y_{1}(x), y_{2}(x)\right] \equiv 0$ in $I$.
Remark. Converse of Theorem 4 is not true in general, i.e., there exist functions which are $L I$ in an
interval $I$ and whose Wronskian is $\equiv 0$ in $I$.
However, if $y_{1}$ and $y_{2}$ are solutions of $L[y]=0$ then the following converse holds.

Theorem 5. If $y_{1}(x), y_{2}(x)$ are $L I$ solutions of $L[y]=0$ in $I$, then $W\left[y_{1}(x), y_{2}(x)\right]$ is never zero in $I$.

Proof. If $W\left[y_{1}(x), y_{2}(x)\right]=0$ for some $x_{0} \in I$, then the equations

$$
\begin{aligned}
& c_{1} y_{1}\left(x_{0}\right)+c_{2} y_{2}\left(x_{0}\right)=0 \\
& c_{1} y_{1}^{\prime}\left(x_{0}\right)+c_{2} y_{2}^{\prime}\left(x_{0}\right)=0
\end{aligned}
$$

have a nontrivial solution, i.e. $\exists c_{1}, c_{2}$ not both zero satisfying the system. For these values of $c_{1}$ and $c_{2}$ the function $y(x)=c_{1} y_{1}(x)+c_{2} y_{2}(x)$ is a solution of $L[y]=0$ and satisfies the initial conditions $y\left(x_{0}\right)=0, y^{\prime}\left(x_{0}\right)=0$. However, by Theorem 1 the only solution of this problem is $y(x) \equiv 0 \Rightarrow$ $c_{1} y_{1}(x)+c_{2} y_{2}(x) \equiv 0 \forall x \in I \Rightarrow y_{1}, y_{2}$ are $L D$. Contradiction! $\Rightarrow W[]$ is never zero in $I$.

Corollary. The Wronskian of 2 solutions of $L[y]=0$ is either identically zero (if solutions are $L D$ ) or never zero (if solutions are $L I$ ).

Theorem 6. If $y_{1}(x)$ and $y_{2}(x)$ are $L I$ solutions of $L[y]=0$, then $y=c_{1} y_{1}+c_{2} y_{2}$ is the general solution of $L[y]=0$.

Example $e^{3 x}$ and $e^{-3 x}$ are $L I$ solutions of $y^{\prime \prime}-9 y=0 \Rightarrow$ general solution is $y=c_{1} e^{3 x}+c_{2} e^{-3 x}$.
Theorem 6 tells us that the problem of finding the general solution of $L[y]=0$ is reduced to finding any two linearly independent solutions.

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Question: Do two $L I$ solutions of $L[y]=0$ actually exist? The answer is given in the affirmative by the next theorem.

Theorem 7. $\exists$ two linear independent solutions of $L[y]=0$.
Proof. Let $y_{1}(x)$ be the unique solution of $L[y]=0$ with initial conditions $y_{1}\left(x_{0}\right)=1, y_{1}^{\prime}\left(x_{0}\right)=0$, and $y_{2}(x)$ be the unique solution of $L[y]=0$ with initial conditions $y_{2}\left(x_{0}\right)=0, y_{2}^{\prime}\left(x_{0}\right)=1$. Note that $y_{1}$ and $y_{2}$ exist by Theorem 1 . Now $y_{1}$ and $y_{2}$ are $L I$ by Theorem 5 since

$$
W\left[y_{1}\left(x_{0}\right), y_{2}\left(x_{0}\right)\right]=\left|\begin{array}{ll}
1 & 0 \\
0 & 1
\end{array}\right|=1 .
$$

Theorem 8. If $y_{p}$ is any particular solution of the nonhomogeneous equation $L[y]=f(x)$ and $y_{h}$ is the general solution of the homogeneous equation $L[y]=0$, then the general solution of $L[y]=f(x)$ is $y=y_{p}+y_{h}$.

Example Solve $y^{\prime \prime}-9 y=e^{x}$
We know that $y_{h}=c_{1} e^{3 x}+c_{2} e^{-3 x} . y_{p}=$ ? Assume $y_{p}=A e^{x}$

$$
\Rightarrow A e^{x}-9 A e^{x}=e^{x} \Rightarrow-8 A=1 \quad A=-\frac{1}{8} \Rightarrow y_{p}=-\frac{1}{8} e^{x}
$$

$\Rightarrow y=c_{1} e^{3 x}+c_{2} e^{-3 x}-\frac{1}{8} e^{x}$ is the general solution.
Theorem 9. Principle of superposition. If $y_{1}$ is a solution of $L[y]=f_{1}$ and $y_{2}$ is a solution of $L[y]=f_{2}$, then $y=y_{1}+y_{2}$ is a solution of $L[y]=f_{1}+f_{2}$.

Example Solve $y^{\prime \prime}-9 y=e^{x}+5$. Before we found that $y=-\frac{1}{8} e^{x}$ was a particular solution of $y^{\prime \prime}-9 y=e^{x}$. To find
a particular solution of $y^{\prime \prime}-9 y=5$ assume $y \equiv k \Rightarrow k=-\frac{5}{9}$. The general solution of equation is therefore

$$
y=c_{1} e^{3 x}+c_{2} e^{-3 x}-\frac{1}{8} e^{x}-\frac{5}{9}
$$

Extension: If for $i=1,2, \ldots, n, y_{i}$ is a solution of $L[y]=f_{i}$, then $\sum_{i=1}^{n} y_{i}$ is a solution of $L[y]=\sum_{i=1}^{n} f_{i}$.

## Complex-valued Solutions

A complex-valued function $f$ of a real variable $x$ is a function of the form

$$
f(x)=u(x)+i v(x)
$$

where $u(x)$ and $v(x)$ are real functions and $i=\sqrt{-1}$.
Definition. If $f=u+i v, u, v$ real functions, then $f$ is continuous if $u$ and $v$ are continuous; $f$ is differential if $u$ and $v$ are differential and

$$
f^{\prime}(x)=u^{\prime}(x)+i v^{\prime}(x) .
$$

Example a) $f(x)=3 x+i x^{2} \Rightarrow f^{\prime}(x)=3+2 i x$
b) $\frac{d}{d x}\left(3 x+i x^{2}\right)^{2}=2\left(3 x+i x^{2}\right)(3+2 i x)=2\left(9 x-2 x^{3}+9 i x^{2}\right)$
c) Let

$$
E(x)=e^{a x}(\cos b x+i \sin b x)
$$

Then

$$
\begin{aligned}
E^{\prime}(x) & =a e^{a x}(\cos b x+i \sin b x)+e^{a x}(-b \sin b x+b i \cos b x) \\
& =e^{a x}[a(\cos b x+i \sin b x)+b i(\cos b x+i \sin b x)] \\
& =e^{a x}[a+b i](\cos b x+i \sin b x) .
\end{aligned}
$$

Hence

$$
E^{\prime}(x)=(a+b i) E(x) .
$$

Based on this we define the complex exponential via

$$
e^{(a+b i) x}=e^{a x} \cos b x+i e^{a x} \sin b x
$$

$a=0 \Rightarrow$

$$
e^{b i x}=\cos b x+i \sin b x .
$$

This is called Euler's formula. Hence

$$
e^{(a+b i) x}=e^{a x} \cdot e^{b i x} .
$$

Example $y=e^{i x}$ satisfies $y^{\prime \prime}+y=0$ since $y^{\prime}=i e^{i x} y^{\prime \prime}=-e^{i x} \Rightarrow-e^{i x}+e^{i x}=0$.
The theorem below gives the connection between real and complex solutions of a linear differential equation with real coefficients.
Theorem 1. Consider the differential equation

$$
a(x) y^{\prime \prime}+b(x) y^{\prime}+c(x) y=0
$$

where $a(x), b(x)$, and $c(x)$ are real functions. The complex function $y=u+i v$, where $u$ and $v$ are real, is a solution of this equation $\Leftrightarrow \bar{u}$ and $v$ are solutions.

Proof. As before we denote the equation by $L[y]=0$. It is easily shown that $L[y]=L[u]+i L[v]$ where $L[u]$ and $L[v]$ are real. Therefore $y$ is a solution $\Leftrightarrow L[y]=L[u]+i L[v] \equiv 0$. Since a complex number is zero $\Leftrightarrow$ its real and imaginary parts are zero,
$\Rightarrow L[y]=0 \Leftrightarrow L[u]=0$ and $L[v]=0 \Leftrightarrow u$ and $v$ solutions.

Example $y=e^{i x}$ is a solution of $y^{\prime \prime}+y=0$. Since $e^{i x}=\cos x+i \sin x \Rightarrow \cos x$ and $\sin x$ are solutions. This is easily verified.

## Homogeneous Linear Equations with Constant Coefficients

We shall now discuss the problem of solving the homogeneous equation

$$
a y^{\prime \prime}+b y^{\prime}+c y=0(*)
$$

where $a, b$ and $c$ are real constants and $a \neq 0$.

Possible candidates for a solution are $x$ and powers of $x$. These are no good. $\ln x$ is also no good. We shall try $e^{\lambda x}$. If $y=e^{\lambda x}$ is a solution of $\left({ }^{*}\right)$
$\Rightarrow a \lambda^{2} e^{\lambda x}+b \lambda e^{\lambda x}+c e^{\lambda x}=e^{\lambda x}\left(a \lambda^{2}+b \lambda+c\right)=0$. This is to be a solution $\forall x . \Rightarrow$

$$
a \lambda^{2}+b \lambda+c=0 .
$$

This equation for $\lambda$ is called the auxiliary or characteristic equation.
It has the solution $\lambda=\frac{-b \pm \sqrt{b^{2}-4 a c}}{2 a}=\frac{-b \pm \sqrt{\Delta}}{2 a} \quad \Delta=b^{2}-4 a c$
There are three possibilities:
(1) $\Delta>0$ two real, distinct roots
(2) $\Delta=0$ one real root, repeated
(3) $\Delta<0$ two imaginary roots which are the complex conjugates of each other, i.e. if $\lambda_{1}=\alpha+i \beta \Rightarrow$ $\lambda_{2}=\alpha-i \beta$
We shall now discuss the three cases in detail.

Case 1. $\Delta>0$. There are two real distinct roots $\lambda_{1}, \lambda_{2}$, where $\lambda_{1} \neq \lambda_{2}$

$$
\lambda_{1}=\frac{-b+\sqrt{b^{2}-4 a c}}{2 a} \quad \lambda_{2}=\frac{-b-\sqrt{b^{2}-4 a c}}{2 a}
$$

$\Rightarrow e^{\lambda_{1} x}$ and $e^{\lambda_{2} x}$ are both solutions of the differential equation. These functions are LI, $\Rightarrow$ general solution is

$$
y=c_{1} e^{\lambda_{1} x}+c_{2} e^{\lambda_{2} x} .
$$

where $\lambda_{1}$ and $\lambda_{2}$ are both real and $\lambda_{1} \neq \lambda_{2}$.
Example $2 y^{\prime \prime}-y^{\prime}-3 y=0$
$\Rightarrow 2 \lambda^{2}-\lambda-3=0$
or

$$
(2 \lambda-3)(\lambda+1)=0 \Rightarrow \lambda_{1}=-1 \quad \lambda_{2}=\frac{3}{2} \Rightarrow y=c_{1} e^{-x}+c_{2} e^{+\frac{3}{2} x} .
$$

Case 2. $\Delta=0$. There is one real, repeated root $\lambda_{1}=-\frac{b}{2 a} \Rightarrow e^{\lambda_{1} x}$ is a solution. We need a second LI solution. To find it we shall use the method of variation of parameters. We seek a solution of the form

$$
y=v(x) e^{\lambda_{1} x},
$$

where $v(x)$ is a function to be determined. Now

$$
y^{\prime}=v^{\prime} e^{\lambda_{1} x}+v \lambda_{1} e^{\lambda_{1} x}
$$

and

$$
y^{\prime \prime}=v^{\prime \prime} e^{\lambda_{1} x}+2 v^{\prime} \lambda_{1} e^{\lambda_{1} x}+v \lambda_{1}^{2} e^{\lambda_{1} x}
$$

$\Rightarrow$

$$
a v^{\prime \prime}(x) e^{\lambda_{1} x}+2 a v^{\prime} \lambda_{1} e^{\lambda_{1} x}+a v \lambda_{1}^{2} e^{\lambda_{1} x}+b v^{\prime} e^{\lambda_{1} x}+b v \lambda_{1} e^{\lambda_{1} x}+c v e^{\lambda_{1} x}=0
$$

$\Rightarrow$

$$
a v^{\prime \prime}+\underbrace{\left(2 a \lambda_{1}+b\right)} v^{\prime}+\underbrace{\left(a \lambda_{1}^{2}+b \lambda_{1}+c\right)} v=0
$$

$\Rightarrow v^{\prime \prime}=0($ why? $) \Rightarrow$

$$
v=c_{1}+c_{2} x
$$

$\Rightarrow$

$$
y=v e^{\lambda_{1} x}=c_{1} e^{\lambda_{1} x}+c_{2} x e^{\lambda_{1} x}
$$

is a solution of the differential equation in the case where there exists one repeated root $\lambda_{1}$. Since $e^{\lambda_{1} x}$
and $x c^{\lambda_{1} \chi}$ are $\mathrm{LI} \Rightarrow$ this is the general solution.

$$
\begin{gathered}
\text { Example } \quad y^{\prime \prime}-4 y^{\prime}+4 y=0 \\
\lambda^{2}-4 \lambda+4=0 \text { or }(\lambda-2)^{2}=0 \Rightarrow \text { one real, repeated root } \lambda=2 . \Rightarrow \\
\\
\\
y=c_{1} e^{2 x}+c_{2} x e^{2 x} .
\end{gathered}
$$

Case 3. $\Delta<02$ complex roots

$$
\begin{array}{r}
\lambda=\frac{-b \pm \sqrt{b^{2}-4 a c}}{2 a}=-\frac{b}{2 a} \pm \frac{i \sqrt{4 a c-b^{2}}}{2 a} \\
\lambda_{1}=\alpha+i \beta=-\frac{b}{2 a}+i \sqrt{\frac{c}{a}-\frac{b^{2}}{4 a^{2}}} \\
\lambda_{2}=\alpha-i \beta=-\frac{b}{2 a}-i \sqrt{\frac{c}{a}-\frac{b^{2}}{4 a^{2}}}
\end{array}
$$

where $\alpha$ and $\beta$ are real numbers.
$\Rightarrow$ two complex solutions. $e^{(\alpha+i \beta) x}=e^{\alpha x}(\cos \beta x+i \sin \beta x)$ and $e^{(\alpha-i \beta) x}=e^{\alpha x}(\cos \beta x-i \sin \beta x)$
Since the differential equation has real coefficients, $\Rightarrow$ real and imaginary parts of above are solutions, i.e.,
$e^{\alpha x} \cos \beta x$ and $e^{\alpha x} \sin \beta x$ are both solutions in this case. These are LI functions.
$\Rightarrow$ the solution is

$$
y=e^{\alpha x}(A \cos \beta x+B \sin \beta x) \quad \text { where } A, B \text { real constants. }
$$

## Example

$$
\begin{gathered}
32 y^{\prime \prime}-40 y^{\prime}+17 y=0 \\
32 \lambda^{2}-40 \lambda+17=0 \\
\lambda=\frac{40 \pm \sqrt{1600-4(32)(17)}}{2(32)}=\frac{40 \pm \sqrt{1600-2176}}{2(32)}=\frac{40 \pm i \sqrt{576}}{2(32)}=\frac{5 \pm \sqrt{9}}{8}=\frac{5}{8} \pm \frac{3}{8} i
\end{gathered}
$$

Thus

$$
\begin{aligned}
\lambda_{1} & =\frac{5}{8}+\frac{3}{8} i \text { and } \lambda_{2}=\frac{5}{8}-\frac{3}{8} i \\
y & =e^{\frac{5}{8} x}\left(A \cos \frac{3}{8} x+B \sin \frac{3}{8} x\right)
\end{aligned}
$$

Example Write down a second order homogeneous linear differential equation with real constant coefficients whose solutions are

$$
\frac{1}{2} e^{-2 x} \cos 3 x \text { and } \frac{3 e^{-2 x}}{4} \sin 3 x .
$$

$\Rightarrow \alpha=-2 \quad \beta=3$ so that $\lambda_{1}=-2+3 i$ and $\quad \lambda_{2}=-2-3 i$.

$$
\begin{aligned}
p(\lambda) & =[\lambda-(-2+3 i)][\lambda-(-2-3 i)] \\
& =[\lambda+2-3 i][\lambda+2+3 i] \\
& =\lambda^{2}+(2+3 i) \lambda+(2-3 i) \lambda+4+9 \\
& =\lambda^{2}+4 \lambda+13
\end{aligned}
$$

(Check: $\lambda=\frac{-4 \pm \sqrt{16-4(1)(13)}}{2}=\frac{-4 \pm b i}{2}=-2 \pm 3 i$ )
$\Rightarrow$ equation is

$$
y^{\prime \prime}+4 y^{\prime}+13 y=0
$$

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## Undetermined Coefficients

Let us now consider the problem of solving

$$
\begin{equation*}
a y^{\prime \prime}+b y^{\prime}+c y=f(x) \quad a \neq 0 \tag{*}
\end{equation*}
$$

$a, b, c$ real constants. We know that the general solution is $y=y_{h}+y_{p}$, where

$$
y_{h}=\text { the solution of the homogeneous equation }
$$

and

$$
y_{p}=\text { a particular solution of the equation }
$$

We know how to find $y_{h}$. We shall now discuss ways of finding $y_{p}$ for certain special functions $f(x)$.

1. $f(x)=K e^{\alpha x} \quad K$ constant, $\alpha$ constant.

Thus we seek $y_{p}$ for

$$
a y^{\prime \prime}+b y^{\prime}+c y=K e^{\alpha x} .
$$

Due to the exponential form of $f(x)$ we seek $y_{p}$ of the form

$$
y_{p}=A e^{\alpha x}
$$

$A=$ ? The differential equation $\left({ }^{*}\right) \Rightarrow$

$$
\left(a \alpha^{2}+b \alpha+c\right) A e^{\alpha x}=K e^{\alpha x}
$$

$\Rightarrow$

$$
A=\frac{K}{a \alpha^{2}+b \alpha+c}
$$

$\Rightarrow$

$$
y_{p}=\frac{K e^{\alpha x}}{a \alpha^{2}+b \alpha+c}
$$

The above is a particular solution provided the denominator is non-zero. Note that the denominator is $p(\lambda)=a \lambda^{2}+b \lambda+c$ with $\lambda=\alpha$. This is the characteristic polynomial with $\lambda=\alpha$.

If $p(\alpha)=0, \Rightarrow$ we do not have a $y_{p}$. However, $p(\alpha)=0 \Rightarrow \alpha$ is a root of characteristic equation. $\Rightarrow e^{\alpha x}$ is solution of the homogeneous equation, and therefore $A e^{\alpha x}$ cannot be a solution of the nonhomogeneous equation. If $p(\alpha)=0$, we try

$$
y_{p}=A x e^{\alpha x}
$$

$\Rightarrow y_{p}^{\prime}=A \alpha x e^{\alpha x}+A e^{\alpha x}$ and $y_{p}^{\prime \prime}=A \alpha^{2} x e^{\alpha x}+A \alpha e^{\alpha x}+A \alpha e^{\alpha x}=A \alpha^{2} x e^{\alpha x}+2 A \alpha e^{\alpha x}$
Substitution into the differential equation $(*) \Rightarrow$

$$
\begin{array}{cc} 
& A x e^{\alpha x}\left[a \alpha^{2}+b \alpha+c\right]+A e^{\alpha x}[2 a \alpha+b]=K e^{\alpha x} \\
\Rightarrow & A=\frac{K}{2 a \alpha+b} \\
\Rightarrow \quad & y_{p}=\frac{K x e^{\alpha x}}{2 a \alpha+b} \text { if } p(\alpha)=0
\end{array}
$$

provided, of course, that $2 a \alpha+b \neq 0$. Note that $p(\lambda)=a \lambda^{2}+b \lambda+c \Rightarrow p^{\prime}(\lambda)=2 a \lambda+b$ $\Rightarrow$

$$
y_{p}=\frac{K x e^{\alpha x}}{p^{\prime}(\alpha)} \text { when } p(\alpha)=0 \text { and } p^{\prime}(\alpha) \neq 0
$$

If $p(\alpha)=0$ and $p^{\prime}(\alpha)=0 \Rightarrow$ above $y_{p}$ is no good. But $p^{\prime}(\alpha)=0 \Rightarrow 2 a \alpha+b=0 \Rightarrow \alpha=-\frac{b}{2 a} . \quad \Rightarrow \alpha$ is a double (repeated) root of $a \lambda^{2}+b \lambda+c=0$. Hence both $e^{\alpha x}$ and $x e^{\alpha x}$ are solutions of the homogeneous equation if $p(\alpha)=p^{\prime}(\alpha)=0$, and these cannot therefore be solutions of the nonhomogeneous equation. If $p(\alpha)=p^{\prime}(\alpha)=0$ we try

$$
y_{p}=A x^{2} e^{\alpha x}
$$

Differentiating and substituting into the equation leads to $\Rightarrow$

$$
A=\frac{K}{2 a}=\frac{K}{p^{\prime \prime}(\alpha)}
$$

since $p^{\prime}(\lambda)=2 a \lambda+b \quad \Rightarrow p^{\prime \prime}(\lambda)=2 a$
Thus

$$
y_{p}=\frac{K}{p^{\prime \prime}(\alpha)} x^{2} e^{\alpha x} \text { if } p(\alpha)=p^{\prime}(\alpha)=0 .
$$

$p^{\prime \prime}(\alpha) \neq 0$ since $a \neq 0$ by assumption.
Summary: A particular solution of $L[y]=k e^{\alpha x}$ is

$$
\begin{aligned}
& y_{p}=\frac{K e^{\alpha x}}{p(\alpha)} \quad \text { if } p(\alpha) \neq 0 \\
& y_{p}=\frac{K x e^{\alpha x}}{p^{\prime}(\alpha)} \text { if } p(\alpha)=0, p^{\prime}(\alpha) \neq 0 \\
& y_{p}=\frac{K}{p^{\prime \prime}(\alpha)} x^{2} e^{\alpha x} \quad \text { if } p(\alpha)=p^{\prime}(\alpha)=0
\end{aligned}
$$

Example (a) $y^{\prime \prime}-5 y^{\prime}+4 y=2 e^{x}$
Homogeneous solution: $p(\lambda)=\lambda^{2}-5 \lambda+4=(\lambda-4)(\lambda-1) \quad \Rightarrow \lambda=4,1 \Rightarrow y_{h}=c_{1} e^{x}+c_{2} e^{4 x}$
Now to find a particular solution for $2 e^{x} . \Rightarrow \alpha=1 \quad p(1)=0 \quad$ Since $p^{\prime}(\lambda)=2 \lambda-5$
$p^{\prime}(1)=2-5=-3 \neq 0$
$\Rightarrow$

$$
y_{p}=\frac{k x e^{\alpha x}}{p^{\prime}(\alpha)}=\frac{2 x e^{x}}{-3}
$$

$\Rightarrow$

$$
y=y_{h}+y_{p}=c_{1} e^{x}+c_{2} e^{4 x}-\frac{2}{3} x e^{x}
$$

(b) $y^{\prime \prime}-5 y^{\prime}+4 y=3+2 e^{x}$
$y_{h}=c_{1} e^{x}+c_{2} e^{4 x} \quad p(\lambda)=\lambda^{2}-5 \lambda+4$
Consider $y^{\prime \prime}-5 y^{\prime}+4 y=3$
$3=k e^{\alpha x}$ with $k=3 \alpha=0 p(0)=4 \neq 0 \quad \Rightarrow y_{p}^{\prime}=\frac{3}{4}$
$\Rightarrow$

$$
y(x)=c_{1} e^{x}+c_{2} e^{4 x}+\frac{3}{4}-\frac{2}{3} x e^{x}
$$

(c) Let us now consider an IVP for this DE.

$$
\begin{gathered}
y^{\prime \prime}-5 y^{\prime}+4 y=3+2 e^{x} y(0)=1 \quad y^{\prime}(0)=0 \\
y(0)=c_{1}+c_{2}+\frac{3}{4}=1 \\
y^{\prime}(x)=c_{1} e^{x}+4 c_{2} e^{4 x}-\frac{2}{3} x e^{x}-\frac{2}{3} e^{x} \\
y^{\prime}(0)=c_{1}+4 c_{2}-\frac{2}{3}=0
\end{gathered}
$$

Thus we have the two equations below for $c_{1}$ and $c_{2}$ :

$$
\begin{aligned}
c_{1}+c_{2} & =\frac{1}{4} \\
c_{1}+4 c_{2} & =\frac{2}{3}
\end{aligned}
$$

, Solution is: $\left[c_{1}=\frac{1}{9}, c_{2}=\frac{5}{36}\right]$ so

$$
y(x)=\frac{1}{9} e^{x}+\frac{5}{36} e^{4 x}+\frac{3}{4}-\frac{2}{3} x e^{x}
$$

## SNB Check:

$$
\begin{gathered}
y^{\prime \prime}-5 y^{\prime}+4 y=3+2 e^{x} \\
y(0)=1 \\
y^{\prime}(0)=0
\end{gathered} \quad, \text {, Exact solution is: }\left\{\frac{1}{9} e^{x}+\frac{5}{36} e^{4 x}-\frac{2}{3} x e^{x}+\frac{3}{4}\right\}
$$

## 2. $f(x)=k \cos \beta x$ or $f(x)=k \sin \beta x$

For example, we seek a particular solution of

$$
L[y]=a y^{\prime \prime}+b y^{\prime}+c y=k \cos \beta x
$$

We shall use the complex exponential to solve for $y_{p}$. Recall

$$
k e^{i \beta x}=k \cos \beta x+i k \sin \beta x
$$

Hence we consider also the equation

$$
L[v]=a v^{\prime \prime}+b v^{\prime}+c v=k \sin \beta x
$$

By multiplying this last equation by $i$ and adding the result to $L[y] \Rightarrow$

$$
L[y]+i L[v]=k \cos \beta x+i k \sin \beta x=k e^{i \beta x} .
$$

But $i L[v]=L[i v]$, since $L$ is linear. Hence if we let $w=y+i v \Rightarrow$ the equation

$$
a w^{\prime \prime}+b w^{\prime}+c w=k e^{i \beta x}
$$

or

$$
L[y]+i L[v]=L[y]+L[i v]=L[y+i v]=L[w]=k e^{i \beta x}
$$

and therefore we have the complex equation $L[w]=k e^{i \beta x}$ for $w$. To find $w_{p}$ for this we use the formulas derived above. Then we find $y_{p}$ from $y_{p}=\operatorname{Re} w_{p}=$ real part of $w_{p}$. For $f(x)=k \sin \beta x$ we have $y_{p}=\operatorname{Im} w_{p}=$ imaginary part of $w_{p}$.

Example Find a particular solution of

$$
y^{\prime \prime}+7 y^{\prime}+12 y=3 \cos 2 x
$$

Let $w=y+i v \Rightarrow$ find $w_{p}$ for $w^{\prime \prime}+7 w^{\prime}+12 w=3 e^{2 i x}$. Now $p(\lambda)=\lambda^{2}+7 \lambda+12 \Rightarrow$ $p(\alpha)=p(2 i)=(2 i)^{2}+7(2 i)+12=-4+14 i+12 \neq 0$ $\Rightarrow$

$$
w_{p}=\frac{3 e^{2 i x}}{p(2 i)}=\frac{3 e^{2 i x}}{8+14 i} .
$$

$y_{p}=\operatorname{Re} w_{p}=$ ?
To find $y_{p}$ we shall rationalize the denominator.

$$
\begin{aligned}
w_{p} & =\frac{3 e^{2 i x}}{8+14 i} \times \frac{8-14 i}{8-14 i} \\
& =\frac{3(8-14 i) e^{2 i x}}{64+196} \\
& =\frac{3(8-14 i) e^{2 i x}}{260} \\
& =\frac{3}{260}(8-14 i)[\cos 2 x+i \sin 2 x] \\
& =\frac{3}{260}[8 \cos 2 x+14 \sin 2 x]+\frac{3}{260} i[8 \sin 2 x-14 \cos 2 x]
\end{aligned}
$$

Thus

$$
y_{p}=\operatorname{Re} w_{p}=\frac{3}{260}[8 \cos 2 x+14 \sin 2 x]
$$

## Example

Example $y^{\prime \prime}+7 y^{\prime}+12 y=3 \cos 2 x$ again.
Let $y_{p}=A \cos 2 x+B \sin 2 x$
$y_{p}^{\prime}=-2 A \sin 2 x+2 B \cos 2 x \quad y_{p}^{\prime \prime}=4 A \cos 2 x-4 B \sin 2 x$
$\Rightarrow$

$$
-4 A \cos 2 x-4 B \sin 2 x-14 A \sin 2 x+14 B \cos 2 x+12 A \cos 2 x+12 B \sin 2 x=3 \cos 2 x
$$

$$
\Rightarrow
$$

$$
\cos 2 x[8 A+14 B]+\sin 2 x[8 B-14 A]=3 \cos 2 x
$$

$$
\Rightarrow
$$

$$
8 A+14 B=38 B-14 A=0 \Rightarrow B=\frac{7}{4} A
$$

$$
8 A+\frac{7}{2}(7) A=3 \quad 8 A+\frac{49}{2} A=3 \Rightarrow \frac{16+49}{2} A=3 \quad A=\frac{6}{65} \Rightarrow B=\frac{21}{130}
$$

$\Rightarrow y_{p}=\frac{6}{65} \cos 2 x+\frac{21}{130} \sin 2 x$ as before.
III. $f(x)=B_{0}+B_{1} x+\cdots+B_{n} x^{n} \quad$ polynomial.

We want $y_{p}$ for

$$
\begin{aligned}
& y^{\prime \prime}+4 y=3 \sin 2 x \\
& \Rightarrow \\
& w^{\prime \prime}+4 w=3 e^{2 i x} \\
& p(\lambda)=\lambda^{2}+4 \Rightarrow p(2 i)=0 \text { and } p^{\prime}(\lambda)=2 \lambda \text {. Now } p^{\prime}(2 i) \neq 0 \\
& \Rightarrow \\
& w_{p}=\frac{3 x e^{2 i x}}{p^{\prime}(2 i)}=\frac{3 x e^{2 i x}}{4 i} \times \frac{i}{i}=-\frac{3}{4} i x e^{2 i x}=-\frac{3}{4} i x[\cos 2 x+i \sin 2 x] \\
& =-\frac{3}{4} x i \cos 2 x+\frac{3}{4} x \sin 2 x \\
& \Rightarrow \\
& y_{p}=\operatorname{Im} w_{p}=-\frac{3}{4} x \cos 2 x
\end{aligned}
$$

$$
a y^{\prime \prime}+b y^{\prime}+c y=B_{0}+B_{1} x+\cdots+B_{n} x^{n}
$$

We try a solution of the form

$$
y_{p}=Q_{n}(x)=A_{0}+A_{1} x+\cdots+A_{n} x^{n}
$$

If $p(0) \neq 0$, then when we substitute $Q_{n}$ into the equation we will get a polynomial of degree $n$ and we can determine $A_{k}^{\prime} s$ by equating coefficients of like powers of $x$. If $p(0)=0$, but $p^{\prime}(0) \neq 0$ use $y_{p}=x Q_{n}(x)$. Similarly if $p(0)=p^{\prime}(0)=0$ take $y_{p}=x^{2} Q_{n}(x)$.

## Example

$$
y^{\prime \prime}+3 y^{\prime}=2 x^{2}+3 x
$$

In this example the right hand side is a polynomial of degree 2 .

$$
\begin{aligned}
& p(\lambda)=\lambda^{2}+3 \lambda \text { so } p(0)=0 . \quad p^{\prime}(\lambda)=2 \lambda+3 \text { and } p^{\prime}(0) \neq 0 \\
& \Rightarrow \\
& \Rightarrow \quad y_{p}=x Q_{2}(x)=x\left(A_{0}+A_{1} x+A_{2} x^{2}\right)=A_{0} x+A_{1} x^{2}+A_{2} x^{3} \\
& y_{p}^{\prime}=A_{0}+2 A_{1} x+3 A_{2} x^{3} \Rightarrow y_{p}^{\prime \prime}=2 A_{1}+6 A_{2} x
\end{aligned}
$$

The differential equation $\Rightarrow$

$$
2 A_{1}+6 A_{2} x+3 A_{0}+6 A_{1} x+9 A_{2} x^{2}=2 x^{2}+3 x
$$

$\Rightarrow$

$$
2 A_{1}+3 A_{0}=0 \text { and } 6 A_{2}+6 A_{1}=3 \text { and } 9 A_{2}=2 .
$$

$\Rightarrow A_{2}=\frac{2}{9} \quad A_{2}+A_{1}=\frac{1}{2} \quad \frac{2}{9}+A_{1}=\frac{1}{2} \Rightarrow A_{1}=\frac{1}{2}-\frac{2}{9}=\frac{9-4}{18}=\frac{5}{18}$
$2\left(\frac{5}{18}\right)+3 A_{0}=0 \quad A_{0}=-\frac{10}{18(3)}=-\frac{5}{27} \Rightarrow$

$$
y_{p}=-\frac{5}{27} x+\frac{5}{18} x^{2}+\frac{2}{9} x^{3}
$$

IV. $f(x)=\left(B_{0}+B_{1} x+\cdots+B_{n} x^{n}\right) e^{\alpha x}$

We want a particular solution for the DE

$$
a y^{\prime \prime}+b y^{\prime}+c y=\left(B_{0}+B_{1} x+\cdots+B_{n} x^{n}\right) e^{\alpha x}
$$

We seek a solution of the form

$$
\begin{aligned}
& y_{p}=Q_{n}(x) e^{\alpha x} \text { if } p(\alpha) \neq 0 \\
& y_{p}=x Q_{n}(x)^{\alpha x} \text { if } p(\alpha)=0, \text { and } p^{\prime}(\alpha) \neq 0 \\
& y_{p}=x^{2} Q_{n}(x) e^{\alpha x} \text { if } p(\alpha)=p^{\prime}(\alpha)=0
\end{aligned}
$$

## Additional Examples

## Example Solve

$$
y^{\prime \prime}+y=x \cos x-\cos x
$$

Solution: Note that $y_{h}=C_{1} \cos x+C_{2} \sin x$.
First we will find a particular solution for $\cos x$. Consider

$$
y^{\prime \prime}+y=-\cos x
$$

and

$$
v^{\prime \prime}+v=-\sin x
$$

Multiply the second equation by $i$ and add it to the first equation.
Letting $w=y+i v$, we get

$$
w^{\prime \prime}+w=-(\cos x+i \sin x)=-e^{i x}
$$

Since $p(\lambda)=\lambda^{2}+1$ and $p(i)=0, p^{\prime}(\lambda)=2 \lambda$, so $p^{\prime}(i)=2 i \neq 0$

$$
w_{p_{1}}=-\frac{x e^{i x}}{2 i}=\frac{1}{2} i x e^{i x}
$$

Hence

$$
y_{p_{1}}=\operatorname{Re} w_{p_{1}}=-\frac{x}{2} \sin x
$$

Now we shall find a particular solution for $x \cos x$. Consider

$$
y^{\prime \prime}+y=x \cos x
$$

and

$$
v^{\prime \prime}+v=x \sin x
$$

Multiplying the second equation by $i$, adding it to the first equation and letting $w=y+i v$, we have

$$
w^{\prime \prime}+w=x(\cos x+i \sin x)=x e^{i x}
$$

Since $e^{i x}$ is a homogeneous solution and $x e^{i x}$ corresponds to a right hand side of $e^{i x}$, we let

$$
w_{p_{2}}=\left(A_{1} x+A_{2} x^{2}\right) e^{i x}
$$

to deal with a right side of the form $x e^{i x}$.

$$
\begin{aligned}
& w_{p_{2}}^{\prime}=\left(A_{1}+2 A_{2} x\right) e^{i x}+i\left(A_{1} x+A_{2} x^{2}\right) e^{i x} \\
& w_{p_{2}}^{\prime \prime}=2 A_{2} e^{i x}+2 i\left(A_{1}+2 A_{2} x\right) e^{i x}-\left(A_{1} x+A_{2} x^{2}\right) e^{i x}
\end{aligned}
$$

Substituting into the DE leads to

$$
2 A_{2} e^{i x}+2 i\left(A_{1}+2 A_{2} x\right) e^{i x}=x e^{i x}
$$

Therefore

$$
\begin{aligned}
2 A_{2}+2 i A_{1} & =0 \\
4 i A_{2} & =1 \text { or } A_{2}=\frac{1}{4 i}=-\frac{i}{4}
\end{aligned}
$$

Then

$$
\begin{gathered}
A_{1}=-\frac{1}{i} A_{2}=\frac{1}{4} \\
w_{p_{2}}=\frac{1}{4} x e^{i x}-\frac{i}{4} x^{2} e^{i x}=\left(\frac{1}{4} x-\frac{i}{4} x^{2}\right)(\cos x+i \sin x) \\
y_{p_{2}}=\operatorname{Re} w_{p_{2}}=\frac{1}{4} x \cos x+\frac{1}{4} x^{2} \sin x
\end{gathered}
$$

Thus

$$
y=y_{h}+y_{p_{1}}+y_{p_{2}}=C_{1} \cos x+C_{2} \sin x-\frac{x}{2} \sin x+\frac{1}{4} x \cos x+\frac{1}{4} x^{2} \sin x
$$

Example Consider the equation

$$
\begin{equation*}
y^{\prime \prime}-3 y^{\prime}+2 y=3 e^{-x}-10 \cos 3 x \tag{}
\end{equation*}
$$

(a) Find the general solution to this equation.

$$
\begin{aligned}
& y^{\prime \prime}-3 y^{\prime}+2 y=0 \quad \text { characteristic equation: } r^{2}-3 r+2=0 ; \quad r=1,2 \\
& y_{h}=C_{1} e^{x}+C_{2} e^{2 x} \\
& y_{p}=A e^{-x}+B \sin 3 x+C \cos 3 x \quad \text { [note: } e^{-x} \text { is not a homogeneous solution.] } \\
& y_{p}^{\prime}=-A e^{-x}+3 B \cos 3 x-3 C \sin 3 x \\
& y_{p}^{\prime \prime}=A e^{-x}-9 B \sin 3 x-9 C \cos 3 x
\end{aligned}
$$

After plugging $y_{p}$ into the given DE, $y_{p}^{\prime \prime}-3 y_{p}^{\prime}+2 y_{p}$ and equating the coefficients:
Solution is: $\quad y(x)=\frac{1}{2} e^{-x}+\frac{9}{13} \sin 3 x+\frac{7}{13} \cos 3 x+C_{1} e^{x}+C_{2} e^{2 x}$
(b) Find the solution to $\left({ }^{*}\right)$ which also satisfies the initial conditions

$$
\begin{gathered}
y(0)=1, y^{\prime}(0)=2 . \\
y(x)=\frac{1}{2} e^{-x}+\frac{9}{13} \sin 3 x+\frac{7}{13} \cos 3 x+C_{1} e^{x}+C_{2} e^{2 x} \\
y(0)=\frac{27}{26}+C_{1}+C_{2}=1 \quad C_{1}=-\frac{1}{26}-C_{2} \\
y^{\prime}(x)=-\frac{1}{2} e^{-x}+\frac{27}{13} \cos 3 x-\frac{21}{13} \sin 3 x+C_{1} e^{x}+2 C_{2} e^{2 x} \\
y^{\prime}(0)=\frac{41}{26}+C_{1}+2 C_{2}=2 \quad \frac{41}{26}-\frac{1}{26}-C_{2}+2 C_{2}=2 \\
\frac{40}{26}+C_{2}=2 \quad C_{2}=2-\frac{40}{26}=\frac{6}{13} \\
\frac{27}{26}+C_{1}+\frac{6}{13}=1 \quad C_{1}=1-\frac{39}{26}=-\frac{1}{2} \\
C_{2}=\frac{6}{13} \quad \text { and } \quad C_{1}=-\frac{1}{2}
\end{gathered}
$$

Solution is:

$$
y(x)=\frac{1}{2} e^{-x}+\frac{9}{13} \sin 3 x+\frac{7}{13} \cos 3 x-\frac{1}{2} e^{x}+\frac{6}{13} e^{2 x}
$$

Example These examples are video slide shows. Slide Example 1 Slide Example 2
You will need Real Player to view this. To get it click on Real Player.

## Variation of Parameters

Let us now consider the non-homogeneous equation

$$
a(x) y^{\prime \prime}+b(x) y^{\prime}+c(x) y=f(x)
$$

where $a, b, c, f$ are continuous functions in some internal $I$ and $a(x) \neq 0 \forall x \in I$. Note we are not assuming that $a, b$, and $c$ are constants. We seek $y_{p}$, a particular solution. We shall use the method of variation of parameters.

If $y_{1}(x)$ and $y_{2}(x)$ are two (known) LI solutions of the homogeneous equation $\Rightarrow$

$$
y_{h}=c_{1} y_{1}(x)+c_{2} y_{2}(x) .
$$

To find $y_{p}$ we shall replace $c_{1}$ and $c_{2}$ by unknown functions of $x$ and seek to determine these functions. Hence let

$$
y_{p}=v_{1}(x) y_{1}(x)+v_{2}(x) y_{2}(x)
$$

Substitution of the above into the differential equation $\Rightarrow$ only one condition for $v_{1}$ and $v_{2}$. We may therefore impose another condition arbitrarily but in such a manner as to simplify things.
Now

$$
y_{p}^{\prime}=v_{1} y_{1}^{\prime}+v_{2} y_{2}^{\prime}+v_{1}^{\prime} y_{1}+v_{2}^{\prime} y_{2}
$$

If we require

$$
v_{1}^{\prime} y_{1}+v_{2}^{\prime} y_{2} \equiv 0 \quad(*)
$$

then no second derivatives of $v_{1}$ and $v_{2}$ will appear in $y_{p}^{\prime \prime}$. We therefore make this one condition. The other comes from the differential equation. Now $(*) \Rightarrow$

$$
y_{p}^{\prime \prime}=v_{1}^{\prime} y_{1}^{\prime}+v_{1} y_{1}^{\prime \prime}+v_{2}^{\prime} y_{2}^{\prime}+v_{2} y_{2}^{\prime \prime}
$$

Substituting into the differential equation implies

$$
v_{1}(\underbrace{a y_{1}^{\prime \prime}+b y_{1}^{\prime}+c y_{1}})+v_{2}(\underbrace{a y_{2}^{\prime \prime}+b y_{2}^{\prime}+c y_{2}})+a v_{1}^{\prime} y_{1}^{\prime}+a v_{2}^{\prime} y_{2}^{\prime}=f(x)
$$

Since the "lower bracketed" quantities are zero, this last equation $\Rightarrow$

$$
v_{1}^{\prime} y_{1}^{\prime}+v_{2}^{\prime} y_{2}^{\prime}=\frac{f(x)}{a(x)}
$$

This is a second condition for $v_{1}^{\prime}$ and $v_{2}^{\prime}$.
$\Rightarrow$ we have found two equations to determine $v_{1}, v_{2}$ namely

$$
v_{1}^{\prime} y_{1}+v_{2}^{\prime} y_{2} \equiv 0
$$

and

$$
v_{1}^{\prime} y_{1}^{\prime}+v_{2}^{\prime} y_{2}^{\prime} \equiv \frac{f(x)}{a(x)}
$$

These two equations can be solved for $v_{1}^{\prime}, v_{2}^{\prime}$ provided

$$
\left|\begin{array}{ll}
y_{1} & y_{2} \\
y_{1}^{\prime} & y_{2}^{\prime}
\end{array}\right| \neq 0
$$

However, the above is the Wronskian of $y_{1}, y_{2}$ and is never zero since $y_{1}$ and $y_{2}$ are LI. $\Rightarrow$

$$
v_{1}=-\int \frac{y_{2} f(x)}{a(x) W\left[y_{1}, y_{2}\right]} d x
$$

and

$$
v_{2}=\int \frac{y_{1} f(x)}{a(x) W\left[y_{1}, y_{2}\right]} d x
$$

Note: It is not necessary to remember these formulas. One can usually solve the two equations for $v_{1}^{\prime}$ and $v_{2}^{\prime}$ directly and with ease. See the examples below.

The particular solution to non-homogeneous equation is

$$
y_{p}=v_{1}(x) y_{1}(x)+v_{2}(x) y_{2}(x)
$$

with $v_{1}$ and $v_{2}$ given by the above expressions.

## Example

$$
y^{\prime \prime}+y=\sec x
$$

$\Rightarrow$ let $y_{1}=\cos x$ and $y_{2}=\sin x$, since these are the two LI homogeneous solutions. Then we take

$$
y_{p}=v_{1}(x) \cos x+v_{2}(x) \sin x
$$

The two conditions given above $\Rightarrow$

$$
\begin{aligned}
v_{1}^{\prime} \cos x+v_{2}^{\prime} \sin x & =0 \\
-v_{1}^{\prime} \sin x+v_{2}^{\prime} \cos x & =\sec x .
\end{aligned}
$$

Note that $W\left[y_{1}, y_{2}\right]=\cos ^{2} x+\sin ^{2} x=1$.
Solving the first equation for $v_{1}^{\prime}$ we have

$$
v_{1}^{\prime}=-\frac{v_{2}^{\prime} \sin x}{\cos x}
$$

The second equation the implies

$$
\frac{v_{2}^{\prime} \sin ^{2} x}{\cos x}+v_{2}^{\prime} \cos x=\sec x
$$

Or

$$
v_{2}^{\prime}\left[\sin ^{2} x+\cos ^{2} x\right]=1
$$

Hence $v_{2}^{\prime}=1$ and

$$
v_{2}=\int 1 d x=x
$$

From the first equation we

$$
v_{1}=-\int \frac{\sin x}{\cos X} d x=\ln |\cos x|
$$

There is no need to include constants of integration, since these just lead to homogeneous solutions in $y_{p}$.
$\Rightarrow$

$$
y_{p}=\ln |\cos x| \cos x+x \sin x .
$$

Hence we get finally that

$$
y=y_{h}+y_{p}=c_{1} \cos x+c_{2} \sin x+\ln |\cos x| \cos x+x \sin x
$$

Example This example is a video slide show. Slide Example

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## Example

Given that $x$ and $x^{4}$ are homogeneous solutions of the equation

$$
x^{2} y^{\prime \prime}-4 x y^{\prime}+4 y=x^{4}+x^{2} \quad x>0
$$

find the general solution of this equation.

## Solution

Since we have that $\left\{x^{4}, x\right\}$ is a fundamental solution set, we seek a particular solution of the form

$$
y_{p}(x)=v_{1}(x) x+v_{2}(x) x^{4}
$$

The equations for $v_{1}^{\prime}$ and $v_{2}^{\prime}$ are

$$
\begin{aligned}
& v_{1}^{\prime} x+v_{2}^{\prime} x^{4}=0 \\
& v_{1}^{\prime}+4 v_{2}^{\prime} x^{3}=\frac{f}{a}=x^{2}+1
\end{aligned}
$$

Note: The Wronskian is $\left|\begin{array}{cl}x & x^{4} \\ 1 & 4 x^{3}\end{array}\right|=4 x^{4}-x^{4}=3 x^{4} \neq 0$ for
The first equation yields

$$
v_{1}^{\prime}=-v_{2}^{\prime} X^{3}
$$

The second equation then yields

$$
v_{2}^{\prime}=\frac{1}{3} \frac{x^{2}+1}{x^{3}}=\frac{1}{3} \frac{1}{x}+\frac{1}{3} \frac{1}{x^{3}}
$$

Thus

$$
v_{2}(x)=\int\left(\frac{1}{3} \frac{1}{x}+\frac{1}{3} \frac{1}{x^{3}}\right) d x=\frac{1}{3} \ln x-\frac{1}{6 x^{2}}
$$

Then

$$
v_{1}^{\prime}=-\left(\frac{1}{3} \frac{1}{x}+\frac{1}{3} \frac{1}{x^{3}}\right) x^{3}=-\frac{1}{3}\left(x^{2}+1\right)
$$

And we have

$$
v_{1}(x)=-\frac{1}{3} \int\left(x^{2}+1\right) d x=-\frac{1}{9} x^{3}-\frac{1}{3} x
$$

Thus

$$
\begin{aligned}
y_{p}(x) & =\left(\frac{1}{3} \ln x-\frac{1}{6 x^{2}}\right) x^{4}+\left(-\frac{1}{9} x^{3}-\frac{1}{3} x\right) x \\
& =\frac{1}{18} x^{2}\left(-2 x^{2}-9+6(\ln x) x^{2}\right)
\end{aligned}
$$

The general solution is, then,

$$
y(x)=\frac{1}{18} x^{2}\left(-2 x^{2}-9+6(\ln x) x^{2}\right)+C_{1} x+C_{2} x^{4}
$$

SNB check $x^{2} y^{\prime \prime}-4 x y^{\prime}+4 y=x^{4}+x^{2}$, Exact solution is: $C_{1} x-\frac{1}{2} x^{2}-\frac{1}{9} x^{4}+C_{2} x^{4}+\frac{1}{3} x^{4} \ln x$
Example Solve the equation

$$
y^{\prime \prime}-2 y^{\prime}+y=3 e^{t}+\frac{e^{t}}{1+t^{2}}
$$

Solution: $p(r)=r^{2}-2 r+1=(r-1)^{2}$. Thus $r=1$ is a repeated root and

$$
y_{h}=c_{1} e^{t}+c_{2} t e^{t}
$$

Since $p^{\prime}(r)=2 r-2$, then $p(1)=p^{\prime}(1)=0$ and a particular solution for $3 e^{t}$ is

$$
y_{p_{1}}=\frac{K t^{2} e^{\alpha t}}{p^{\prime \prime}(\alpha)}=\frac{3 t^{2} e^{t}}{2}
$$

To find a particular solution for $\frac{e^{t}}{1+t^{2}}$ we use the Method of Variation of Parameters.

$$
y_{p}=v_{1}(t) y_{1}(t)+v_{2}(t) y_{2}(t)
$$

Here $y_{1}=e^{t}$ and $y_{2}=t e^{t}$ so

$$
y_{p}=v_{1}(t) e^{t}+v_{2}(t) t e^{t}
$$

The equations for $v_{1}^{\prime}$ and $v_{2}^{\prime}$ are

$$
\begin{aligned}
v_{1}^{\prime} e^{t}+v_{2}^{\prime} t e^{t} & =0 \\
v_{1}^{\prime} e^{t}+v_{2}^{\prime}\left(e^{t}+t e^{t}\right) & =\frac{f}{a}=\frac{e^{t}}{1+t^{2}}
\end{aligned}
$$

since $a=1$. We many cancel the $e^{t}$ in both equations.

$$
\begin{aligned}
v_{1}^{\prime}+v_{2}^{\prime} t & =0 \\
v_{1}^{\prime}+v_{2}^{\prime}(1+t) & =\frac{1}{1+t^{2}}
\end{aligned}
$$

Then

$$
v_{1}^{\prime}=-v_{2}^{\prime} t
$$

Using this in the second equation we have

$$
v_{2}^{\prime}=\frac{1}{1+t^{2}}
$$

and therefore

$$
v_{2}=\tan ^{-1} t
$$

Then

$$
v_{1}^{\prime}=-\frac{t}{1+t^{2}}
$$

so

$$
v_{2}=-\frac{1}{2} \ln \left(1+t^{2}\right)
$$

Then

$$
y_{p_{2}}=v_{1}(x) e^{t}+v_{2}(x) t e^{t}=-\frac{1}{2} e^{t} \ln \left(1+t^{2}\right)+t e^{t} \tan ^{-1} t
$$

Finally

$$
\begin{aligned}
y & =y_{h}+y_{p_{1}}+y_{p_{2}} \\
& =c_{1} e^{t}+c_{2} t e^{t}+\frac{3 t^{2} e^{t}}{2}-\frac{1}{2} e^{t} \ln \left(1+t^{2}\right)+t e^{t} \tan ^{-1} t
\end{aligned}
$$

## Euler's Equation

The differential equation

$$
\begin{equation*}
x^{2} y^{\prime \prime}+p x y^{\prime}+q y=f(x) \tag{1}
\end{equation*}
$$

where $p$ and $q$ are constants is called Euler's Equation (or the Cauchy-Euler Equation).

Consider the homogeneous case

$$
\begin{equation*}
x^{2} y^{\prime \prime}+p x y^{\prime}+q y=0 . \tag{2}
\end{equation*}
$$

Once we find $y_{h}$ then we can find $y_{p}$ for (1) by variation of parameters. We consider (2) only for the case $x>0$ so that coefficient on $y^{\prime \prime}$ does not vanish. Notice that each term contains some power of $x$ if we try $y=x^{m}$. Hence we seek a homogeneous solution of the form

$$
y_{h}=x^{m}
$$

and shall try to determine $m$ so that $x^{m}$ is a solution. Now

$$
y_{h}^{\prime}=m x^{m-1} \text { and } y_{h}^{\prime \prime}=m(m-1) x^{m-2}
$$

so that the differential equation $\Rightarrow$

$$
x^{m}[m(m-1)+p m+q]=0 \Rightarrow x^{m}\left[m^{2}+m(p-1)+q\right]=0 .
$$

Since $x^{m} \neq 0 \Rightarrow$

$$
\begin{equation*}
m^{2}+m(p-1)+q=0 . \tag{3}
\end{equation*}
$$

(3) is call the indicial equation for $m$. It has solutions

$$
m=\frac{-(p-1) \pm \sqrt{(p-1)^{2}-4 q}}{2}
$$

Let $\Delta=(p-1)^{2}-4 q$ Then we have three cases just as we had for second order equations with constant coefficients.

Case 1. $\Delta>0 \Rightarrow 2$ distinct roots $m_{1}, m_{2} \Rightarrow$

$$
y_{h}=c_{1} x^{m_{1}}+c_{2} x^{m_{2}} .
$$

Case 2. $\Delta=0 \Rightarrow$

$$
m_{1}=\frac{1-p}{2} .
$$

To get a second solution let $y=u(x) x^{m_{1}}$, where $u(x)$ is a function to be determined. Equation (2) $\Rightarrow$

$$
x u^{\prime \prime}+u^{\prime}=0
$$

Letting $v=u^{\prime} \Rightarrow x v^{\prime}+v=0 \Rightarrow$

$$
v^{\prime}+\frac{v}{X}=0
$$

The integrating factor for this equation is $e^{\int \frac{1}{x} d x}=e^{\ln x}=x \Rightarrow \frac{d}{d x}(x v)=0 \Rightarrow x v=c_{1} \Rightarrow v=\frac{c_{1}}{x}$ $u=\int v=c_{1} \ln x+c_{2}$
$\Rightarrow$

$$
y_{h}=x^{m_{1}}\left[c_{1} \ln x+c_{2}\right] .
$$

Case 3. $\Delta<0 \Rightarrow$ roots are complex conjugates, $m_{1}=a+b i$ and $m_{2}=a-b i$.
Thus

$$
y_{h}=c_{1} x^{m_{1}}+c_{2} x^{m_{2}}=c_{1} x^{a+b i}+c_{2} x^{a-b i}
$$

or

$$
y_{h}=x^{a}\left[c_{1} x^{b i}+c_{2} x^{-b i}\right]
$$

Now

$$
\begin{array}{cc} 
& x^{a+b i}=e^{(a+i b) \ln x} \text { for } x>0 . \\
\Rightarrow & x^{b i}=e^{i b \ln x}=\cos (b \ln x)+i \sin (b \ln x) \\
\Rightarrow & y_{h}=x^{a}[A \cos (b \ln x)+B \sin (b \ln x)] .
\end{array}
$$

Example Solve

$$
x^{2} y^{\prime \prime}+7 x y^{\prime}+5 y=0
$$

Here $p=7$ and $q=5$. The indicial equation (3) is for this example

$$
\begin{aligned}
m^{2}+m(p-1)+q & = \\
m^{2}+6 m+5 & =(m+5)(m+1)
\end{aligned}
$$

$\Rightarrow m=-5$ or $-1 \Rightarrow$

$$
y=c_{1} x^{-5}+c_{2} x^{-1}=\frac{c_{1}}{x^{5}}+\frac{c_{2}}{X}
$$

## Example Solve

$$
x^{2} y^{\prime \prime}+3 x y^{\prime}+y=0
$$

Here $p=3$ and $q=1$ so the indicial equation is

$$
m^{2}+m(p-1)+q=m^{2}+2 m+1=(m+1)^{2}
$$

Thus $m=-1$ is a repeated root and the solution is

$$
y_{h}=c_{1} x^{-1}+c_{2} x^{-1} \ln x
$$

Example Solve

$$
x^{2} y^{\prime \prime}+3 x y^{\prime}+2 y=0
$$

Here $p=3$ and $q=2$ so the indicial equation is

$$
m^{2}+m(p-1)+q=m^{2}+2 m+2
$$

Thus

$$
m=\frac{-2 \pm \sqrt{4-4(1)(2)}}{2}=-1 \pm i
$$

Thus we set $a=-1$ and $b=1$ in the formula

$$
y_{h}=x^{a}[A \cos (b \ln x)+B \sin (b \ln x)] .
$$

and get

$$
y_{h}=x^{-1}[A \cos (\ln x)+B \sin (\ln x)]
$$

