### Ma 221

# **CHAPTER 4 - Linear Differential Equations**

We shall now begin a detailed study of the second-order linear differential equation

$$a(x)y'' + b(x)y' + c(x)y = f(x)$$

# Fundamental theory of second-order linear equations

The following theorem gives information concerning the existence of solutions of second-order linear differential equations. We shall accept it as valid without proof.

Theorem 1: Consider the Initial Value Problem

D.E. 
$$a(x)y'' + b(x)y' + c(x)y = f(x)$$

I.C. 
$$y(x_0) = y_0$$
  $y'(x_0) = y'_0$ 

If a(x), b(x), c(x), f(x) are all continuous functions in the interval I, where  $x_0 \in I$  and  $a(x) \neq 0$  for all x in I, then the IVP possesses a unique solution. This solution has a continuous derivative and is defined throughout I.

#### **Example**

D.E. 
$$a(x)y'' + b(x)y' + c(x)y = 0$$
 Homogeneous Equation  
I.C.  $y(x_0) = 0$   $y'(x_0) = 0$ 

One solution is  $y(x) \equiv 0$ . Theorem  $1 \Rightarrow$  only solution is  $y \equiv 0$ .

We shall assume from now on that a, b, c, and f are continuous in a common interval I and  $a(x) \neq 0$  in I so that Theorem 1 holds.

Notation: Let

$$L[y] \equiv a(x)y'' + b(x)y' + c(x)y.$$

Then L[2] = 2c(x)

$$L[3x] = 3b(x) + 3xc(x).$$

With this notation the second order differential equation a(x)y'' + b(x)y' + c(y)y = f(x) can be written as L[y] = f(x). The homogeneous case is when  $f(x) = 0 \Rightarrow L[y] = 0$ . This is called the homogeneous equation. If  $f(x) \neq 0 \Rightarrow$  a nonhomogeneous equation.

L[y] is called a linear operator because it has the following property.

Theorem 2:

$$L[c_1y_1 + c_2y_2] = c_1L[y_1] + c_2L[y_2]$$

where  $y_1$  and  $y_2$  are any twice differential functions and  $c_1$  and  $c_2$  are any constants. Proof:

$$L[c_1y_1 + c_2y_2] = a(x) (c_1y_1 + c_2y_2)'' + b(x) (c_1y_1 + c_2y_2)' + c(x) (c_1y_1 + c_2y_2)$$

$$= a(x) (c_1y_1'' + c_2y_2'') + b(x) (c_1y_1' + c_2y_2') + c(x) (c_1y_1 + c_2y_2)$$

$$= c_1[a(x)y_1'' + b(x)y_1' + c(x)y_1] + c_2[a(x)y_2'' + b(x)y_2' + c(x)y_2]$$

$$\Rightarrow L[c_1y_1 + c_2y_2] = c_1L[y_1] + c_2L[y_2]$$

### **Properties of solutions of second order equations.**

Theorem 3: If  $y_1(x)$  and  $y_2(x)$  are solutions of the homogeneous equation L[y] = 0, then  $y = c_1y_1(x) + c_2y_2(x)$  is also a solution.

Proof.  $L[c_1y_1 + c_2y_2] = c_1L[y_1] + c_2L[y_2]$  from above. Since  $y_1$  is a solution of  $L[y] = 0 \Rightarrow L[y_1] = 0$ . Similarly  $L[y_2] = 0$ .

Hence  $L[c_1y_1 + c_2y_2] = c_1L[y_1] + c_2L[y_2] = 0 + 0 = 0 \Rightarrow y = c_1y_1 + c_2y_2$  is also a solution of L(y) = 0.

**Example** y'' - 9y = 0  $e^{3x}$  and  $e^{-3x}$  are solutions. Theorem  $3 \Rightarrow y = c_1 e^{3x} + c_2 e^{-3x}$  is also a solution.

Remark. We desire to be able to find the general solution of L[y] = 0. The above theorem tells us that if  $y_1$  and  $y_2$  are solutions, then  $c_1y_1 + c_2y_2$  is a solution, but it does not tell us that this is the general solution. In order to know when one has a general solution it is necessary to introduce the concept of the linear independence of two functions.

Definition: Two functions  $y_1(x)$  and  $y_2(x)$  are called linearly dependent (LD) in an interval I if it is possible to find two constants  $c_1$  and  $c_2$ , not both zero, so that

$$c_1 y_1(x) + c_2 y_2(x) = 0 \ \forall x \in I.$$

Two functions are called linearly independent (LI) if they are not linearly dependent, i.e., if

$$c_1 y_1(x) + c_2 y_2(x) = 0 \ \forall x \in I \Rightarrow c_1 = c_2 = 0.$$

Remark. If two functions are LD in  $I \Rightarrow$  one of the functions is equal to a constant times the other in I.

**Example** (a) x, 2x are LD in any interval I, since

$$(-2)x + (1) 2x = 0 \quad \forall x \in I$$

(b)  $x^2$ , x are LI in any interval I, since

$$c_1 x^2 + c_2 x = 0 \quad \forall x \in I$$

is impossible because this equation has at most two real roots in I. Thus, we must have  $c_1 = c_2 = 0$ .

(c) Two functions are LD if one of them is the zero function. If  $y_1 \equiv 0$ , then

$$c_1y_1 + 0 \cdot y_2 = c_10 + 0 \cdot y \equiv 0 \ \forall x \in I$$

and any  $c_1 \neq 0$ .

(d) If  $\lambda_1 \neq \lambda_2$ , then  $e^{\lambda_1 x}$  and  $e^{\lambda_2 x}$  are LI for if

$$c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x} \equiv 0$$

 $\Rightarrow$ 

$$c_1 \equiv -c_2 e^{(\lambda_2 - \lambda_1)x}.$$

But  $c_1$  is a constant and therefore the last equation  $\Rightarrow \lambda_1 = \lambda_2$ , which is a contradiction.

#### Facts from algebra needed in the proofs of the next theorems.

If  $d_3 = e_3 = 0$  and  $det \neq 0 \Rightarrow x = y = 0$  is the only solution.

2. 
$$\begin{vmatrix} d_1x + d_2y = 0 \\ e_1x + e_2y = 0 \end{vmatrix}$$
 has nontrivial solution.  $\Leftrightarrow \begin{vmatrix} d_1 & d_2 \\ e_1 & e_2 \end{vmatrix} = 0$ 

Definition: The Wronskian of two differentiable functions  $y_1$  and  $y_2$  is defined to be

$$W[y_1(x), y_2(x)] \equiv \begin{vmatrix} y_1(x) & y_2(x) \\ y'_1(x) & y'_2(x) \end{vmatrix} \equiv y_1(x)y'_2(x) - y'_1(x)y_2(x).$$

Theorem 4. If  $W[y_1(x), y_2(x)]$  is different from zero for at least one point in an interval I, then  $y_1(x)$  and  $y_2(x)$  are LI in I.

Proof. Suppose  $y_1$ ,  $y_2$  are LD. Then  $\exists$  constants  $c_1, c_2$ , not both zero, such that

$$c_1 y_1(x) + c_2 y_2(x) \equiv 0$$

$$c_1 y_1'(x) + c_2 y_2'(x) \equiv 0$$

By assumption these two equations have a nontrivial solution  $c_1$ ,  $c_2$  at each point x in I. Therefore the determinant of the coefficients (by 2) must be zero for each x. But the determinant of coefficients  $= W[y_1(x), y_2(x)]$  and  $W \neq 0$  for at least one point in I.  $\Rightarrow y_1$  and  $y_2$  are not LD.

Corollary. If  $y_1, y_2$  are LD in  $I \Rightarrow W[y_1(x), y_2(x)] \equiv 0$  in I.

Remark. Converse of Theorem 4 is not true in general, i.e., there exist functions which are LI in an

interval I and whose Wronskian is  $\equiv 0$  in I.

However, if  $y_1$  and  $y_2$  are solutions of L[y] = 0 then the following converse holds.

Theorem 5. If  $y_1(x)$ ,  $y_2(x)$  are LI solutions of L[y] = 0 in I, then  $W[y_1(x), y_2(x)]$  is never zero in I.

Proof. If  $W[y_1(x), y_2(x)] = 0$  for some  $x_0 \in I$ , then the equations

$$c_1 y_1(x_0) + c_2 y_2(x_0) = 0$$

$$c_1 y_1'(x_0) + c_2 y_2'(x_0) = 0$$

have a nontrivial solution, i.e.  $\exists c_1, c_2$  not both zero satisfying the system. For these values of  $c_1$  and  $c_2$  the function  $y(x) = c_1y_1(x) + c_2y_2(x)$  is a solution of L[y] = 0 and satisfies the initial conditions  $y(x_0) = 0$ ,  $y'(x_0) = 0$ . However, by Theorem 1 the only solution of this problem is  $y(x) = 0 \Rightarrow c_1y_1(x) + c_2y_2(x) \equiv 0 \ \forall x \in I \Rightarrow y_1, y_2 \text{ are } LD$ . Contradiction!  $\Rightarrow W[]$  is never zero in I.

Corollary. The Wronskian of 2 solutions of L[y] = 0 is either identically zero (if solutions are LD) or never zero (if solutions are LI).

Theorem 6. If  $y_1(x)$  and  $y_2(x)$  are LI solutions of L[y] = 0, then  $y = c_1y_1 + c_2y_2$  is the general solution of L[y] = 0.

**Example**  $e^{3x}$  and  $e^{-3x}$  are LI solutions of  $y'' - 9y = 0 \Rightarrow$  general solution is  $y = c_1 e^{3x} + c_2 e^{-3x}$ .

Theorem 6 tells us that the problem of finding the general solution of L[y] = 0 is reduced to finding any two linearly independent solutions.

**Example** This example is a video slide show. Slide Example

You will need Real Player to view this. To get it click on Real Player.

Question: Do two LI solutions of L[y] = 0 actually exist? The answer is given in the affirmative by the next theorem.

Theorem 7.  $\exists$  two linear independent solutions of L[y] = 0.

Proof. Let  $y_1(x)$  be the unique solution of L[y] = 0 with initial conditions  $y_1(x_0) = 1$ ,  $y'_1(x_0) = 0$ , and  $y_2(x)$  be the unique solution of L[y] = 0 with initial conditions  $y_2(x_0) = 0$ ,  $y'_2(x_0) = 1$ . Note that  $y_1$  and  $y_2$  exist by Theorem 1. Now  $y_1$  and  $y_2$  are LI by Theorem 5 since

$$W[y_1(x_0), y_2(x_0)] = \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = 1.$$

Theorem 8. If  $y_p$  is any particular solution of the nonhomogeneous equation L[y] = f(x) and  $y_h$  is the general solution of the homogeneous equation L[y] = 0, then the general solution of L[y] = f(x) is  $y = y_p + y_h$ .

**Example** Solve  $y'' - 9y = e^x$ 

We know that  $y_h = c_1 e^{3x} + c_2 e^{-3x}$ .  $y_p = ?$  Assume  $y_p = Ae^x$ 

$$\Rightarrow Ae^x - 9Ae^x = e^x \Rightarrow -8A = 1 \qquad A = -\frac{1}{8} \Rightarrow y_p = -\frac{1}{8} e^x$$
  
\Rightarrow y = c\_1 e^{3x} + c\_2 e^{-3x} - \frac{1}{8} e^x \text{ is the general solution.}

Theorem 9. Principle of superposition. If  $y_1$  is a solution of  $L[y] = f_1$  and  $y_2$  is a solution of  $L[y] = f_2$ , then  $y = y_1 + y_2$  is a solution of  $L[y] = f_1 + f_2$ .

**Example** Solve  $y'' - 9y = e^x + 5$ . Before we found that  $y = -\frac{1}{8} e^x$  was a particular solution of  $y'' - 9y = e^x$ . To find

a particular solution of y'' - 9y = 5 assume  $y = k \Rightarrow k = -\frac{5}{9}$ . The general solution of equation is therefore

$$y = c_1 e^{3x} + c_2 e^{-3x} - \frac{1}{8} e^x - \frac{5}{9}.$$

Extension: If for i = 1, 2, ..., n,  $y_i$  is a solution of  $L[y] = f_i$ , then  $\sum_{i=1}^n y_i$  is a solution of  $L[y] = \sum_{i=1}^n f_i$ .

### **Complex-valued Solutions**

A complex-valued function f of a real variable x is a function of the form

$$f(x) = u(x) + iv(x)$$

where u(x) and v(x) are real functions and  $i = \sqrt{-1}$ .

Definition. If f = u + iv, u, v real functions, then f is continuous if u and v are continuous; f is differential if u and v are differential and

$$f'(x) = u'(x) + iv'(x).$$

**Example** a)  $f(x) = 3x + ix^2 \Rightarrow f'(x) = 3 + 2ix$ 

b) 
$$\frac{d}{dx}(3x+ix^2)^2 = 2(3x+ix^2)(3+2ix) = 2(9x-2x^3+9ix^2)$$

c) Let

$$E(x) = e^{ax}(\cos bx + i\sin bx)$$

Then

$$E'(x) = ae^{ax}(\cos bx + i\sin bx) + e^{ax}(-b\sin bx + bi\cos bx)$$
$$= e^{ax}[a(\cos bx + i\sin bx) + bi(\cos bx + i\sin bx)]$$
$$= e^{ax}[a + bi](\cos bx + i\sin bx).$$

Hence

$$E'(x) = (a+bi)E(x).$$

Based on this we define the complex exponential via

$$e^{(a+bi)x} = e^{ax}\cos bx + ie^{ax}\sin bx$$

 $a = 0 \Rightarrow$ 

$$e^{bix} = \cos bx + i\sin bx$$
.

This is called Euler's formula. Hence

$$e^{(a+bi)x} = e^{ax} \cdot e^{bix}$$

**Example** 
$$y = e^{ix}$$
 satisfies  $y'' + y = 0$  since  $y' = ie^{ix}$   $y'' = -e^{ix} \Rightarrow -e^{ix} + e^{ix} = 0$ .

The theorem below gives the connection between real and complex solutions of a linear differential equation with real coefficients.

Theorem 1. Consider the differential equation

$$a(x)y'' + b(x)y' + c(x)y = 0$$

where a(x), b(x), and c(x) are real functions. The complex function y = u + iv, where u and v are real, is a solution of this equation  $\Leftrightarrow \overline{u}$  and v are solutions.

Proof. As before we denote the equation by L[y] = 0. It is easily shown that L[y] = L[u] + iL[v] where L[u] and L[v] are real. Therefore y is a solution  $\Leftrightarrow L[y] = L[u] + iL[v] \equiv 0$ . Since a complex number is zero  $\Leftrightarrow$  its real and imaginary parts are zero,

$$\Rightarrow L[y] = 0 \Leftrightarrow L[u] = 0$$
 and  $L[v] = 0 \Leftrightarrow u$  and v solutions.

**Example**  $y = e^{ix}$  is a solution of y'' + y = 0. Since  $e^{ix} = \cos x + i \sin x \Rightarrow \cos x$  and  $\sin x$  are solutions. This is easily verified.

# **Homogeneous Linear Equations with Constant Coefficients**

We shall now discuss the problem of solving the homogeneous equation

$$ay'' + by' + cy = 0$$
 (\*)

where a, b and c are real constants and  $a \neq 0$ .

Possible candidates for a solution are x and powers of x. These are no good.  $\ln x$  is also no good. We shall try  $e^{\lambda x}$ . If  $y = e^{\lambda x}$  is a solution of (\*)

$$\Rightarrow a\lambda^2 e^{\lambda x} + b\lambda e^{\lambda x} + ce^{\lambda x} = e^{\lambda x} (a\lambda^2 + b\lambda + c) = 0$$
. This is to be a solution  $\forall x. \Rightarrow$ 

$$a\lambda^2 + b\lambda + c = 0$$
.

This equation for  $\lambda$  is called the *auxiliary* or *characteristic* equation.

It has the solution 
$$\lambda = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} = \frac{-b \pm \sqrt{\Delta}}{2a}$$
  $\Delta = b^2 - 4ac$ 

There are three possibilities:

(1)  $\Delta > 0$  two real, distinct roots

(2)  $\Delta = 0$  one real root, repeated

(3)  $\Delta < 0$  two imaginary roots which are the complex conjugates of each other, i.e. if  $\lambda_1 = \alpha + i\beta \Rightarrow \lambda_2 = \alpha - i\beta$ 

We shall now discuss the three cases in detail.

Case 1.  $\Delta > 0$ . There are two real distinct roots  $\lambda_1, \lambda_2$ , where  $\lambda_1 \neq \lambda_2$ 

$$\lambda_1 = \frac{-b + \sqrt{b^2 - 4ac}}{2a} \qquad \lambda_2 = \frac{-b - \sqrt{b^2 - 4ac}}{2a}$$

 $\Rightarrow$   $e^{\lambda_1 x}$  and  $e^{\lambda_2 x}$  are both solutions of the differential equation. These functions are LI,  $\Rightarrow$  general solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}.$$

where  $\lambda_1$  and  $\lambda_2$  are both real and  $\lambda_1 \neq \lambda_2$ .

**Example** 2y'' - y' - 3y = 0

$$\Rightarrow 2\lambda^2 - \lambda - 3 = 0$$

or

$$(2\lambda - 3)(\lambda + 1) = 0 \Rightarrow \lambda_1 = -1 \ \lambda_2 = \frac{3}{2} \ \Rightarrow y = c_1 e^{-x} + c_2 e^{+\frac{3}{2}x}$$

Case 2.  $\Delta = 0$ . There is one real, repeated root  $\lambda_1 = -\frac{b}{2a} \Rightarrow e^{\lambda_1 x}$  is a solution. We need a second LI solution. To find it we shall use the method of variation of parameters. We seek a solution of the form

$$v = v(x)e^{\lambda_1 x}$$

where v(x) is a function to be determined. Now

$$y' = v'e^{\lambda_1 x} + v\lambda_1 e^{\lambda_1 x}$$

and

$$y'' = v''e^{\lambda_1 x} + 2v'\lambda_1 e^{\lambda_1 x} + v\lambda_1^2 e^{\lambda_1 x}$$

 $\Rightarrow$ 

$$av''(x)e^{\lambda_1 x} + 2av'\lambda_1 e^{\lambda_1 x} + av\lambda_1^2 e^{\lambda_1 x} + bv'e^{\lambda_1 x} + bv\lambda_1 e^{\lambda_1 x} + cve^{\lambda_1 x} = 0$$

 $\Rightarrow$ 

$$av'' + (2a\lambda_1 + b)v' + (a\lambda_1^2 + b\lambda_1 + c)v = 0$$

 $\Rightarrow v'' = 0 \text{ (why?)} \Rightarrow$ 

$$v = c_1 + c_2 x$$

 $\Rightarrow$ 

$$y = ve^{\lambda_1 x} = c_1 e^{\lambda_1 x} + c_2 x e^{\lambda_1 x}$$

is a solution of the differential equation in the case where there exists one repeated root  $\lambda_1$ . Since  $e^{\lambda_1 x}$ 

and  $xc^{\lambda_1 x}$  are LI  $\Rightarrow$  this is the general solution.

**Example** 
$$y'' - 4y' + 4y = 0$$
  
 $\lambda^2 - 4\lambda + 4 = 0$  or  $(\lambda - 2)^2 = 0 \Rightarrow$  one real, repeated root  $\lambda = 2$ .  $\Rightarrow$ 

$$y = c_1 e^{2x} + c_2 x e^{2x}.$$

Case 3.  $\Delta$  < 0 2 complex roots

$$\lambda = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} = -\frac{b}{2a} \pm \frac{i\sqrt{4ac - b^2}}{2a}$$

 $\Rightarrow$ 

$$\lambda_1 = \alpha + i\beta = -\frac{b}{2a} + i\sqrt{\frac{c}{a} - \frac{b^2}{4a^2}}$$

$$\lambda_2 = \alpha - i\beta = -\frac{b}{2a} - i\sqrt{\frac{c}{a} - \frac{b^2}{4a^2}}$$

where  $\alpha$  and  $\beta$  are real numbers.

 $\Rightarrow$  two complex solutions.  $e^{(\alpha+i\beta)x} = e^{\alpha x}(\cos\beta x + i\sin\beta x)$  and  $e^{(\alpha-i\beta)x} = e^{\alpha x}(\cos\beta x - i\sin\beta x)$ 

Since the differential equation has  $\underline{\underline{real}}$  coefficients,  $\Rightarrow$  real and imaginary parts of above are solutions, i.e.,

 $e^{\alpha x}\cos\beta x$  and  $e^{\alpha x}\sin\beta x$  are both solutions in this case. These are LI functions.

 $\Rightarrow$  the solution is

 $y = e^{\alpha x} (A \cos \beta x + B \sin \beta x)$  where A, B real constants.

**Example** 

$$32y'' - 40y' + 17y = 0$$

$$32\lambda^2 - 40\lambda + 17 = 0$$

$$\lambda = \frac{40 \pm \sqrt{1600 - 4(32)(17)}}{2(32)} = \frac{40 \pm \sqrt{1600 - 2176}}{2(32)} = \frac{40 \pm i\sqrt{576}}{2(32)} = \frac{5 \pm \sqrt{9}}{8} = \frac{5}{8} \pm \frac{3}{8}i$$

Thus

$$\lambda_1 = \frac{5}{8} + \frac{3}{8}i$$
 and  $\lambda_2 = \frac{5}{8} - \frac{3}{8}i$ 

 $\Rightarrow$ 

$$y = e^{\frac{5}{8}x} \left( A \cos \frac{3}{8} x + B \sin \frac{3}{8} x \right)$$

**Example** Write down a second order homogeneous linear differential equation with real constant coefficients whose solutions are

$$\frac{1}{2}e^{-2x}\cos 3x$$
 and  $\frac{3e^{-2x}}{4}\sin 3x$ .

$$\Rightarrow \alpha = -2$$
  $\beta = 3$  so that  $\lambda_1 = -2 + 3i$  and  $\lambda_2 = -2 - 3i$ .

 $\Rightarrow$ 

$$p(\lambda) = [\lambda - (-2+3i)][\lambda - (-2-3i)]$$

$$= [\lambda + 2 - 3i][\lambda + 2 + 3i]$$

$$= \lambda^2 + (2+3i)\lambda + (2-3i)\lambda + 4 + 9$$

$$= \lambda^2 + 4\lambda + 13$$

(Check: 
$$\lambda = \frac{-4 \pm \sqrt{16 - 4(1)(13)}}{2} = \frac{-4 \pm bi}{2} = -2 \pm 3i$$
)

 $\Rightarrow$  equation is

$$y'' + 4y' + 13y = 0$$

**Example** This example is a video slide show. Slide Example

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### **Undetermined Coefficients**

Let us now consider the problem of solving

$$ay'' + by' + cy = f(x)$$
  $a \ne 0$  (\*)

a,b,c real constants. We know that the general solution is  $y = y_h + y_p$ , where

 $y_h$  = the solution of the homogeneous equation

and

 $y_p$  = a particular solution of the equation

We know how to find  $y_h$ . We shall now discuss ways of finding  $y_p$  for certain special functions f(x).

1.  $f(x) = Ke^{\alpha x}$  K constant,  $\alpha$  constant.

Thus we seek  $y_p$  for

$$ay'' + by' + cy = Ke^{\alpha x}$$
.

Due to the exponential form of f(x) we seek  $y_p$  of the form

$$y_p = Ae^{\alpha x}$$

A = ? The differential equation (\*)  $\Rightarrow$ 

$$(a\alpha^2 + b\alpha + c)Ae^{\alpha x} = Ke^{\alpha x}$$

 $\Rightarrow$ 

$$A = \frac{K}{a\alpha^2 + b\alpha + c}$$

 $y_p = \frac{Ke^{\alpha x}}{a\alpha^2 + b\alpha + c}$ 

The above is a particular solution provided the denominator is non-zero. Note that the denominator is  $p(\lambda) = a\lambda^2 + b\lambda + c$  with  $\lambda = \alpha$ . This is the characteristic polynomial with  $\lambda = \alpha$ .

If  $p(\alpha) = 0$ ,  $\Rightarrow$  we do not have a  $y_p$ . However,  $p(\alpha) = 0 \Rightarrow \alpha$  is a root of characteristic equation.  $\Rightarrow e^{\alpha x}$  is solution of the homogeneous equation, and therefore  $Ae^{\alpha x}$  cannot be a solution of the nonhomogeneous equation. If  $p(\alpha) = 0$ , we try

$$y_p = Axe^{\alpha x}$$

 $\Rightarrow$   $y_p' = A\alpha x e^{\alpha x} + Ae^{\alpha x}$  and  $y_p'' = A\alpha^2 x e^{\alpha x} + A\alpha e^{\alpha x} + A\alpha e^{\alpha x} = A\alpha^2 x e^{\alpha x} + 2A\alpha e^{\alpha x}$ Substitution into the differential equation (\*)  $\Rightarrow$ 

$$Axe^{\alpha x}[a\alpha^2 + b\alpha + c] + Ae^{\alpha x}[2a\alpha + b] = Ke^{\alpha x}$$

 $\Rightarrow$ 

 $\Rightarrow$ 

$$A = \frac{K}{2a\alpha + b}$$

 $\Rightarrow$ 

$$y_p = \frac{Kxe^{\alpha x}}{2a\alpha + b}$$
 if  $p(\alpha) = 0$ 

provided, of course, that  $2a\alpha + b \neq 0$ . Note that  $p(\lambda) = a\lambda^2 + b\lambda + c \Rightarrow p'(\lambda) = 2a\lambda + b$ 

$$y_p = \frac{Kxe^{\alpha x}}{p'(\alpha)}$$
 when  $p(\alpha) = 0$  and  $p'(\alpha) \neq 0$ 

If  $p(\alpha) = 0$  and  $p'(\alpha) = 0 \Rightarrow$  above  $y_p$  is no good. But  $p'(\alpha) = 0 \Rightarrow 2a\alpha + b = 0 \Rightarrow \alpha = -\frac{b}{2a}$ .  $\Rightarrow \alpha$  is a double (repeated) root of  $a\lambda^2 + b\lambda + c = 0$ . Hence both  $e^{\alpha x}$  and  $xe^{\alpha x}$  are solutions of the homogeneous equation if  $p(\alpha) = p'(\alpha) = 0$ , and these cannot therefore be solutions of the nonhomogeneous equation. If  $p(\alpha) = p'(\alpha) = 0$  we try

$$y_p = Ax^2 e^{\alpha x}.$$

Differentiating and substituting into the equation leads to

 $\Rightarrow$ 

$$A = \frac{K}{2a} = \frac{K}{p''(\alpha)}$$

since  $p'(\lambda) = 2a\lambda + b \implies p''(\lambda) = 2a$ 

Thus

$$y_p = \frac{K}{p''(\alpha)} x^2 e^{\alpha x}$$
 if  $p(\alpha) = p'(\alpha) = 0$ .

 $p''(\alpha) \neq 0$  since  $a \neq 0$  by assumption.

Summary: A particular solution of  $L[y] = ke^{\alpha x}$  is

$$y_p = \frac{Ke^{\alpha x}}{p(\alpha)} \quad \text{if } p(\alpha) \neq 0$$

$$y_p = \frac{Kxe^{\alpha x}}{p'(\alpha)} \quad \text{if } p(\alpha) = 0, p'(\alpha) \neq 0$$

$$y_p = \frac{K}{p''(\alpha)} x^2 e^{\alpha x} \quad \text{if } p(\alpha) = p'(\alpha) = 0$$

**Example** (a)  $y'' - 5y' + 4y = 2e^x$ 

Homogeneous solution:  $p(\lambda) = \lambda^2 - 5\lambda + 4 = (\lambda - 4)(\lambda - 1)$   $\Rightarrow \lambda = 4, 1 \Rightarrow y_h = c_1 e^x + c_2 e^{4x}$ Now to find a particular solution for  $2e^x$ .  $\Rightarrow \alpha = 1$  p(1) = 0 Since  $p'(\lambda) = 2\lambda - 5$   $p'(1) = 2 - 5 = -3 \neq 0$ 

 $\Rightarrow$ 

$$y_p = \frac{kxe^{\alpha x}}{p'(\alpha)} = \frac{2xe^x}{-3}$$

 $\Rightarrow$ 

$$y = y_h + y_p = c_1 e^x + c_2 e^{4x} - \frac{2}{3} x e^x$$

(b) 
$$y'' - 5y' + 4y = 3 + 2e^x$$

$$y_h = c_1 e^x + c_2 e^{4x}$$
  $p(\lambda) = \lambda^2 - 5\lambda + 4$ 

Consider y'' - 5y' + 4y = 3

$$3 = ke^{\alpha x}$$
 with  $k = 3$   $\alpha = 0$   $p(0) = 4 \neq 0$   $\Rightarrow y'_p = \frac{3}{4}$ 

 $\Rightarrow$ 

$$y(x) = c_1 e^x + c_2 e^{4x} + \frac{3}{4} - \frac{2}{3} x e^x$$

(c) Let us now consider an IVP for this DE.

$$y'' - 5y' + 4y = 3 + 2e^x$$
  $y(0) = 1$   $y'(0) = 0$ 

$$y(0) = c_1 + c_2 + \frac{3}{4} = 1$$

$$y'(x) = c_1 e^x + 4c_2 e^{4x} - \frac{2}{3} x e^x - \frac{2}{3} e^x$$

$$y'(0) = c_1 + 4c_2 - \frac{2}{3} = 0$$

Thus we have the two equations below for  $c_1$  and  $c_2$ :

$$c_1 + c_2 = \frac{1}{4}$$
$$c_1 + 4c_2 = \frac{2}{3}$$

, Solution is:  $[c_1 = \frac{1}{9}, c_2 = \frac{5}{36}]$  so

$$y(x) = \frac{1}{9}e^x + \frac{5}{36}e^{4x} + \frac{3}{4} - \frac{2}{3}xe^x$$

SNB Check:

$$y'' - 5y' + 4y = 3 + 2e^{x}$$

$$y(0) = 1$$
, Exact solution is:  $\left\{ \frac{1}{9}e^{x} + \frac{5}{36}e^{4x} - \frac{2}{3}xe^{x} + \frac{3}{4} \right\}$ 

$$y'(0) = 0$$

### 2. $f(x) = k \cos \beta x \text{ or } f(x) = k \sin \beta x$

For example, we seek a particular solution of

$$L[y] = ay'' + by' + cy = k\cos\beta x$$

We shall use the complex exponential to solve for  $y_p$ . Recall

$$ke^{i\beta x} = k\cos\beta x + ik\sin\beta x.$$

Hence we consider also the equation

$$L[v] = av'' + bv' + cv = k\sin\beta x$$

By multiplying this last equation by i and adding the result to  $L[y] \Rightarrow$ 

$$L[y] + iL[v] = k\cos\beta x + ik\sin\beta x = ke^{i\beta x}.$$

But iL[v] = L[iv], since L is linear. Hence if we let  $w = y + iv \Rightarrow$  the equation

$$aw'' + bw' + cw = ke^{i\beta x}$$

or

$$L[y] + iL[v] = L[y] + L[iv] = L[y + iv] = L[w] = ke^{i\beta x}$$

and therefore we have the complex equation  $L[w] = ke^{i\beta x}$  for w. To find  $w_p$  for this we use the formulas derived above. Then we find  $y_p$  from  $y_p = \text{Re } w_p = \text{real part of } w_p$ . For  $f(x) = k \sin \beta x$  we have  $y_p = \text{Im } w_p = \text{imaginary part of } w_p$ .

**Example** Find a particular solution of

$$y'' + 7y' + 12y = 3\cos 2x$$

Let  $w = y + iv \Rightarrow$  find  $w_p$  for  $w'' + 7w' + 12w = 3e^{2ix}$ . Now  $p(\lambda) = \lambda^2 + 7\lambda + 12 \Rightarrow p(\alpha) = p(2i) = (2i)^2 + 7(2i) + 12 = -4 + 14i + 12 \neq 0$ 

$$w_p = \frac{3e^{2ix}}{p(2i)} = \frac{3e^{2ix}}{8+14i}.$$

$$y_p = \text{Re } w_p = ?$$

To find  $y_p$  we shall rationalize the denominator.

$$w_p = \frac{3e^{2ix}}{8+14i} \times \frac{8-14i}{8-14i}$$

$$= \frac{3(8-14i)e^{2ix}}{64+196}$$

$$= \frac{3(8-14i)e^{2ix}}{260}$$

$$= \frac{3}{260}(8-14i)[\cos 2x + i\sin 2x]$$

$$= \frac{3}{260}[8\cos 2x + 14\sin 2x] + \frac{3}{260}i[8\sin 2x - 14\cos 2x]$$

Thus

$$y_p = \text{Re}\,w_p = \frac{3}{260}[8\cos 2x + 14\sin 2x]$$

**Example** 

$$y'' + 4y = 3\sin 2x$$

 $\Rightarrow$ 

$$w'' + 4w = 3e^{2ix}$$

$$p(\lambda) = \lambda^2 + 4 \Rightarrow p(2i) = 0 \text{ and } p'(\lambda) = 2\lambda. \text{ Now } p'(2i) \neq 0$$

 $\Rightarrow$ 

$$w_p = \frac{3xe^{2ix}}{p'(2i)} = \frac{3xe^{2ix}}{4i} \times \frac{i}{i} = -\frac{3}{4}ixe^{2ix} = -\frac{3}{4}ix[\cos 2x + i\sin 2x]$$
$$= -\frac{3}{4}xi\cos 2x + \frac{3}{4}x\sin 2x$$

 $\Rightarrow$ 

$$y_p = \operatorname{Im} w_p = -\frac{3}{4}x\cos 2x$$

**Example**  $y'' + 7y' + 12y = 3\cos 2x$  again.

Let  $y_p = A \cos 2x + B \sin 2x$ 

$$y'_p = -2A \sin 2x + 2B \cos 2x$$
  $y''_p = 4A \cos 2x - 4B \sin 2x$ 

 $\Rightarrow$ 

$$-4A\cos 2x - 4B\sin 2x - 14A\sin 2x + 14B\cos 2x + 12A\cos 2x + 12B\sin 2x = 3\cos 2x$$

 $\Rightarrow$ 

$$\cos 2x[8A + 14B] + \sin 2x[8B - 14A] = 3\cos 2x$$

 $\Rightarrow$ 

$$8A + 14B = 3 \ 8B - 14A = 0 \Rightarrow B = \frac{7}{4}A$$

$$8A + \frac{7}{2}(7)A = 3$$
  $8A + \frac{49}{2}A = 3$   $\Rightarrow \frac{16+49}{2}A = 3$   $A = \frac{6}{65} \Rightarrow B = \frac{21}{130}$   
  $\Rightarrow y_p = \frac{6}{65}\cos 2x + \frac{21}{130}\sin 2x$  as before.

III.  $f(x) = B_0 + B_1 x + \cdots + B_n x^n$  polynomial.

We want  $y_p$  for

$$ay'' + by' + cy = B_0 + B_1x + \cdot \cdot + B_nx^n$$

We try a solution of the form

$$y_p = Q_n(x) = A_0 + A_1x + \cdot \cdot \cdot + A_nx^n$$

If  $p(0) \neq 0$ , then when we substitute  $Q_n$  into the equation we will get a polynomial of degree n and we can determine  $A'_k$  s by equating coefficients of like powers of x. If p(0) = 0, but  $p'(0) \neq 0$  use  $y_p = xQ_n(x)$ . Similarly if p(0) = p'(0) = 0 take  $y_p = x^2Q_n(x)$ .

#### **Example**

$$y'' + 3y' = 2x^2 + 3x$$

In this example the right hand side is a polynomial of degree 2.

$$p(\lambda) = \lambda^2 + 3\lambda$$
 so  $p(0) = 0$ .  $p'(\lambda) = 2\lambda + 3$  and  $p'(0) \neq 0$ 

 $\Rightarrow$ 

$$y_p = xQ_2(x) = x(A_0 + A_1x + A_2x^2) = A_0x + A_1x^2 + A_2x^3$$

 $\Rightarrow$ 

$$y'_p = A_0 + 2A_1x + 3A_2x^3 \Rightarrow y''_p = 2A_1 + 6A_2x$$

The differential equation  $\Rightarrow$ 

$$2A_1 + 6A_2x + 3A_0 + 6A_1x + 9A_2x^2 = 2x^2 + 3x$$

 $\Rightarrow$ 

$$2A_1 + 3A_0 = 0 \text{ and } 6A_2 + 6A_1 = 3 \text{ and } 9A_2 = 2.$$

$$\Rightarrow A_2 = \frac{2}{9} \quad A_2 + A_1 = \frac{1}{2} \quad \frac{2}{9} + A_1 = \frac{1}{2} \Rightarrow A_1 = \frac{1}{2} - \frac{2}{9} = \frac{9-4}{18} = \frac{5}{18}$$

$$2\left(\frac{5}{18}\right) + 3A_0 = 0 \quad A_0 = -\frac{10}{18(3)} = -\frac{5}{27} \Rightarrow$$

$$y_p = -\frac{5}{27}x + \frac{5}{18}x^2 + \frac{2}{9}x^3$$

**IV.** 
$$f(x) = (B_0 + B_1 x + \cdots + B_n x^n) e^{\alpha x}$$

We want a particular solution for the DE

$$ay'' + by' + cy = (B_0 + B_1x + \cdot \cdot \cdot + B_nx^n)e^{\alpha x}$$

We seek a solution of the form

$$y_p = Q_n(x)e^{\alpha x}$$
 if  $p(\alpha) \neq 0$   
 $y_p = xQ_n(x)^{\alpha x}$  if  $p(\alpha) = 0$ , and  $p'(\alpha) \neq 0$   
 $y_p = x^2Q_n(x)e^{\alpha x}$  if  $p(\alpha) = p'(\alpha) = 0$ 

### **Additional Examples**

**Example** Solve

$$y'' + y = x\cos x - \cos x$$

Solution: Note that  $y_h = C_1 \cos x + C_2 \sin x$ .

First we will find a particular solution for  $\cos x$ . Consider

$$y'' + y = -\cos x$$

and

$$v'' + v = -\sin x$$

Multiply the second equation by i and add it to the first equation.

Letting w = y + iv, we get

$$w'' + w = -(\cos x + i\sin x) = -e^{ix}$$

Since 
$$p(\lambda) = \lambda^2 + 1$$
 and  $p(i) = 0, p'(\lambda) = 2\lambda$ , so  $p'(i) = 2i \neq 0$ 

$$w_{p_1} = -\frac{xe^{ix}}{2i} = \frac{1}{2}ixe^{ix}$$

Hence

$$y_{p_1} = \operatorname{Re} w_{p_1} = -\frac{x}{2} \sin x$$

Now we shall find a particular solution for  $x \cos x$ . Consider

$$y'' + y = x \cos x$$

and

$$v'' + v = x \sin x$$

Multiplying the second equation by i, adding it to the first equation and letting w = y + iv, we have

$$w'' + w = x(\cos x + i\sin x) = xe^{ix}$$

Since  $e^{ix}$  is a homogeneous solution and  $xe^{ix}$  corresponds to a right hand side of  $e^{ix}$ , we let

$$w_{p_2} = (A_1 x + A_2 x^2) e^{ix}$$

to deal with a right side of the form  $xe^{ix}$ .

$$w'_{p_2} = (A_1 + 2A_2x)e^{ix} + i(A_1x + A_2x^2)e^{ix}$$
  
$$w''_{p_2} = 2A_2e^{ix} + 2i(A_1 + 2A_2x)e^{ix} - (A_1x + A_2x^2)e^{ix}$$

Substituting into the DE leads to

$$2A_2e^{ix} + 2i(A_1 + 2A_2x)e^{ix} = xe^{ix}$$

Therefore

$$2A_2 + 2iA_1 = 0$$
  
 $4iA_2 = 1 \text{ or } A_2 = \frac{1}{4i} = -\frac{i}{4}$ 

Then

$$A_{1} = -\frac{1}{i}A_{2} = \frac{1}{4}$$

$$w_{p_{2}} = \frac{1}{4}xe^{ix} - \frac{i}{4}x^{2}e^{ix} = \left(\frac{1}{4}x - \frac{i}{4}x^{2}\right)(\cos x + i\sin x)$$

$$y_{p_{2}} = \operatorname{Re} w_{p_{2}} = \frac{1}{4}x\cos x + \frac{1}{4}x^{2}\sin x$$

Thus

$$y = y_h + y_{p_1} + y_{p_2} = C_1 \cos x + C_2 \sin x - \frac{x}{2} \sin x + \frac{1}{4} x \cos x + \frac{1}{4} x^2 \sin x$$

**Example** Consider the equation

$$y'' - 3y' + 2y = 3e^{-x} - 10\cos 3x \tag{*}$$

(a) Find the general solution to this equation.

$$y'' - 3y' + 2y = 0$$
 characteristic equation:  $r^2 - 3r + 2 = 0$ ;  $r = 1,2$ 

$$y_h = C_1 e^x + C_2 e^{2x}$$

$$y_p = Ae^{-x} + B\sin 3x + C\cos 3x$$
 [note:  $e^{-x}$  is not a homogeneous solution.]

$$y_p' = -Ae^{-x} + 3B\cos 3x - 3C\sin 3x$$

$$y_p'' = Ae^{-x} - 9B\sin 3x - 9C\cos 3x$$

After plugging  $y_p$  into the given DE,  $y_p'' - 3y_p' + 2y_p$  and equating the coefficients:

Solution is: 
$$y(x) = \frac{1}{2}e^{-x} + \frac{9}{13}\sin 3x + \frac{7}{13}\cos 3x + C_1e^x + C_2e^{2x}$$

(b) Find the solution to (\*) which also satisfies the initial conditions

$$y(0) = 1, y'(0) = 2.$$

$$y(x) = \frac{1}{2}e^{-x} + \frac{9}{13}\sin 3x + \frac{7}{13}\cos 3x + C_1e^x + C_2e^{2x}$$

$$y(0) = \frac{27}{26} + C_1 + C_2 = 1 \qquad C_1 = -\frac{1}{26} - C_2$$

$$y'(x) = -\frac{1}{2}e^{-x} + \frac{27}{13}\cos 3x - \frac{21}{13}\sin 3x + C_1e^x + 2C_2e^{2x}$$

$$y'(0) = \frac{41}{26} + C_1 + 2C_2 = 2 \qquad \frac{41}{26} - \frac{1}{26} - C_2 + 2C_2 = 2$$

$$\frac{40}{26} + C_2 = 2 \qquad C_2 = 2 - \frac{40}{26} = \frac{6}{13}$$

$$\frac{27}{26} + C_1 + \frac{6}{13} = 1 \qquad C_1 = 1 - \frac{39}{26} = -\frac{1}{2}$$

$$C_2 = \frac{6}{13} \qquad \text{and} \qquad C_1 = -\frac{1}{2}$$

Solution is:

$$y(x) = \frac{1}{2}e^{-x} + \frac{9}{13}\sin 3x + \frac{7}{13}\cos 3x - \frac{1}{2}e^{x} + \frac{6}{13}e^{2x}$$

**Example** These examples are video slide shows. Slide Example 1 Slide Example 2

You will need Real Player to view this. To get it click on Real Player.

#### Variation of Parameters

Let us now consider the non-homogeneous equation

$$a(x)y'' + b(x)y' + c(x)y = f(x)$$

where a, b, c, f are continuous functions in some internal I and  $a(x) \neq 0 \ \forall x \in I$ . Note we are not assuming that a, b, and c are constants. We seek  $y_p$ , a particular solution. We shall use the method of variation of parameters.

If  $y_1(x)$  and  $y_2(x)$  are two (known) LI solutions of the homogeneous equation  $\Rightarrow$ 

$$y_h = c_1 y_1(x) + c_2 y_2(x).$$

To find  $y_p$  we shall replace  $c_1$  and  $c_2$  by unknown functions of x and seek to determine these functions. Hence let

$$y_p = v_1(x)y_1(x) + v_2(x)y_2(x)$$

Substitution of the above into the differential equation  $\Rightarrow$  only one condition for  $v_1$  and  $v_2$ . We may therefore impose another condition arbitrarily but in such a manner as to simplify things. Now

$$y_p' = v_1 y_1' + v_2 y_2' + v_1' y_1 + v_2' y_2$$

If we require

$$v_1' y_1 + v_2' y_2 \equiv 0$$
 (\*)

then no second derivatives of  $v_1$  and  $v_2$  will appear in  $y_p''$ . We therefore make this one condition. The other comes from the differential equation. Now  $(*) \Rightarrow$ 

$$y_p'' = v_1'y_1' + v_1y_1'' + v_2'y_2' + v_2y_2''$$

Substituting into the differential equation implies

$$v_1(\underbrace{ay_1'' + by_1' + cy_1}) + v_2(\underbrace{ay_2'' + by_2' + cy_2}) + av_1'y_1' + av_2'y_2' = f(x)$$

Since the "lower bracketed" quantities are zero, this last equation ⇒

$$v_1'y_1' + v_2'y_2' = \frac{f(x)}{a(x)}$$

This is a second condition for  $v'_1$  and  $v'_2$ .

 $\Rightarrow$  we have found two equations to determine  $v_1, v_2$  namely

$$v_1'y_1 + v_2'y_2 \equiv 0$$

and

$$v_1'y_1' + v_2'y_2' \equiv \frac{f(x)}{a(x)}$$

These two equations can be solved for  $v'_1$ ,  $v'_2$  provided

$$\left|\begin{array}{cc} y_1 & y_2 \\ y_1' & y_2' \end{array}\right| \neq 0$$

However, the above is the Wronskian of  $y_1$ ,  $y_2$  and is never zero since  $y_1$  and  $y_2$  are LI.

 $\Rightarrow$ 

$$v_1 = -\int \frac{y_2 f(x)}{a(x) \ W[y_1, y_2]} dx$$

and

$$v_2 = \int \frac{y_1 f(x)}{a(x) \ W[y_1, y_2]} dx$$

Note: It is not necessary to remember these formulas. One can usually solve the two equations for  $v'_1$  and  $v'_2$  directly and with ease. See the examples below.

The particular solution to non-homogeneous equation is

$$y_p = v_1(x) y_1(x) + v_2(x) y_2(x)$$

with  $v_1$  and  $v_2$  given by the above expressions.

#### **Example**

$$y'' + y = \sec x$$

 $\Rightarrow$  let  $y_1 = \cos x$  and  $y_2 = \sin x$ , since these are the two LI homogeneous solutions. Then we take

$$y_p = v_1(x)\cos x + v_2(x)\sin x$$

The two conditions given above  $\Rightarrow$ 

$$v_1' \cos x + v_2' \sin x = 0$$
$$-v_1' \sin x + v_2' \cos x = \sec x.$$

Note that  $W[y_1, y_2] = \cos^2 x + \sin^2 x = 1$ .

Solving the first equation for  $v_1'$  we have

$$v_1' = -\frac{v_2' \sin x}{\cos x}$$

The second equation the implies

$$\frac{v_2'\sin^2x}{\cos x} + v_2'\cos x = \sec x$$

Or

 $\Rightarrow$ 

$$v_2'[\sin^2 x + \cos^2 x] = 1$$

Hence  $v_2' = 1$  and

$$v_2 = \int 1 dx = x$$

From the first equation we

$$v_1 = -\int \frac{\sin x}{\cos x} dx = \ln|\cos x|$$

There is no need to include constants of integration, since these just lead to homogeneous solutions in  $y_p$ .

$$y_p = \ln|\cos x|\cos x + x\sin x.$$

Hence we get finally that

$$y = y_h + y_p = c_1 \cos x + c_2 \sin x + \ln|\cos x| \cos x + x \sin x$$

**Example** This example is a video slide show. Slide Example

You will need Real Player to view this. To get it click on Real Player.

#### **Example**

Given that x and  $x^4$  are homogeneous solutions of the equation

$$x^2y'' - 4xy' + 4y = x^4 + x^2$$
  $x > 0$ 

find the general solution of this equation.

Solution

Since we have that  $\{x^4, x\}$  is a fundamental solution set, we seek a particular solution of the form

$$y_p(x) = v_1(x)x + v_2(x)x^4$$

The equations for  $v'_1$  and  $v'_2$  are

$$v'_1 x + v'_2 x^4 = 0$$
  
$$v'_1 + 4v'_2 x^3 = \frac{f}{a} = x^2 + 1$$

Note: The Wronskian is  $\begin{vmatrix} x & x^4 \\ 1 & 4x^3 \end{vmatrix} = 4x^4 - x^4 = 3x^4 \neq 0$  for

The first equation yields

$$v_1' = -v_2' x^3$$

The second equation then yields

$$v_2' = \frac{1}{3} \frac{x^2 + 1}{x^3} = \frac{1}{3} \frac{1}{x} + \frac{1}{3} \frac{1}{x^3}$$

Thus

$$v_2(x) = \int \left(\frac{1}{3}\frac{1}{x} + \frac{1}{3}\frac{1}{x^3}\right) dx = \frac{1}{3}\ln x - \frac{1}{6x^2}$$

Then

$$v_1' = -\left(\frac{1}{3}\frac{1}{x} + \frac{1}{3}\frac{1}{x^3}\right)x^3 = -\frac{1}{3}(x^2 + 1)$$

And we have

$$v_1(x) = -\frac{1}{3} \int (x^2 + 1) dx = -\frac{1}{9} x^3 - \frac{1}{3} x$$

Thus

$$y_p(x) = \left(\frac{1}{3}\ln x - \frac{1}{6x^2}\right)x^4 + \left(-\frac{1}{9}x^3 - \frac{1}{3}x\right)x$$
$$= \frac{1}{18}x^2(-2x^2 - 9 + 6(\ln x)x^2)$$

The general solution is, then,

$$y(x) = \frac{1}{18}x^2(-2x^2 - 9 + 6(\ln x)x^2) + C_1x + C_2x^4$$

SNB check  $x^2y'' - 4xy' + 4y = x^4 + x^2$ , Exact solution is:  $C_1x - \frac{1}{2}x^2 - \frac{1}{9}x^4 + C_2x^4 + \frac{1}{3}x^4 \ln x$ 

**Example** Solve the equation

$$y'' - 2y' + y = 3e^t + \frac{e^t}{1 + t^2}$$

Solution:  $p(r) = r^2 - 2r + 1 = (r - 1)^2$ . Thus r = 1 is a repeated root and

$$y_h = c_1 e^t + c_2 t e^t$$

Since p'(r) = 2r - 2, then p(1) = p'(1) = 0 and a particular solution for  $3e^t$  is

$$y_{p_1} = \frac{Kt^2e^{\alpha t}}{p''(\alpha)} = \frac{3t^2e^t}{2}$$

To find a particular solution for  $\frac{e^t}{1+t^2}$  we use the Method of Variation of Parameters.

$$y_p = v_1(t)y_1(t) + v_2(t)y_2(t)$$

Here  $y_1 = e^t$  and  $y_2 = te^t$  so

$$y_p = v_1(t)e^t + v_2(t) te^t$$

The equations for  $v'_1$  and  $v'_2$  are

$$v_1'e^t + v_2'te^t = 0$$

$$v_1'e^t + v_2'(e^t + te^t) = \frac{f}{a} = \frac{e^t}{1 + t^2}$$

since a = 1. We many cancel the  $e^t$  in both equations.

$$v_1' + v_2't = 0$$

$$v_1' + v_2'(1+t) = \frac{1}{1+t^2}$$

Then

$$v_1' = -v_2't$$

Using this in the second equation we have

$$v_2' = \frac{1}{1 + t^2}$$

and therefore

$$v_2 = \tan^{-1} t$$

Then

$$v_1' = -\frac{t}{1+t^2}$$

so

$$v_2 = -\frac{1}{2}\ln(1+t^2)$$

Then

$$y_{p_2} = v_1(x)e^t + v_2(x)te^t = -\frac{1}{2}e^t\ln(1+t^2) + te^t\tan^{-1}t$$

Finally

$$y = y_h + y_{p_1} + y_{p_2}$$
  
=  $c_1 e^t + c_2 t e^t + \frac{3t^2 e^t}{2} - \frac{1}{2} e^t \ln(1 + t^2) + t e^t \tan^{-1} t$ 

# **Euler's Equation**

The differential equation

$$x^2y'' + pxy' + qy = f(x)$$
 (1)

where p and q are constants is called Euler's Equation (or the Cauchy-Euler Equation).

Consider the homogeneous case

$$x^2y'' + pxy' + qy = 0. (2)$$

Once we find  $y_h$  then we can find  $y_p$  for (1) by variation of parameters. We consider (2) only for the case x > 0 so that coefficient on y'' does not vanish. Notice that each term contains some power of x if we try  $y = x^m$ . Hence we seek a homogeneous solution of the form

$$y_h = x^m$$

and shall try to determine m so that  $x^m$  is a solution. Now

$$y'_h = mx^{m-1}$$
 and  $y''_h = m(m-1)x^{m-2}$ 

so that the differential equation  $\Rightarrow$ 

$$x^{m}[m(m-1) + pm + q] = 0 \Rightarrow x^{m}[m^{2} + m(p-1) + q] = 0.$$

Since  $x^m \neq 0 \Rightarrow$ 

$$m^2 + m(p-1) + q = 0.$$
 (3)

(3) is call the indicial equation for m. It has solutions

$$m = \frac{-(p-1) \pm \sqrt{(p-1)^2 - 4q}}{2}$$

Let  $\triangle = (p-1)^2 - 4q$  Then we have three cases just as we had for second order equations with constant coefficients.

Case 1.  $\triangle > 0 \Rightarrow 2$  distinct roots  $m_1, m_2 \Rightarrow$ 

$$y_h = c_1 x^{m_1} + c_2 x^{m_2}.$$

Case 2.  $\triangle = 0 \Rightarrow$ 

$$m_1=\frac{1-p}{2}.$$

To get a second solution let  $y = u(x)x^{m_1}$ , where u(x) is a function to be determined. Equation (2)  $\Rightarrow$ 

$$xu'' + u' = 0.$$

Letting  $v = u' \Rightarrow xv' + v = 0 \Rightarrow$ 

$$v' + \frac{v}{x} = 0.$$

The integrating factor for this equation is  $e^{\int \frac{1}{x} dx} = e^{\ln x} = x \Rightarrow \frac{d}{dx}(xv) = 0 \Rightarrow xv = c_1 \Rightarrow v = \frac{c_1}{x}$  $u = \int v = c_1 \ln x + c_2$ 

 $\Rightarrow$ 

$$y_h = x^{m_1}[c_1 \ln x + c_2].$$

Case 3.  $\triangle < 0 \Rightarrow$  roots are complex conjugates,  $m_1 = a + bi$  and  $m_2 = a - bi$ . Thus

$$y_h = c_1 x^{m_1} + c_2 x^{m_2} = c_1 x^{a+bi} + c_2 x^{a-bi}$$

or

$$y_h = x^a [c_1 x^{bi} + c_2 x^{-bi}].$$

Now

$$x^{a+bi} = e^{(a+ib)\ln x}$$
 for  $x > 0$ .

 $\Rightarrow$ 

$$x^{bi} = e^{ib\ln x} = \cos(b\ln x) + i\sin(b\ln x)$$

 $\Rightarrow$ 

$$y_h = x^a [A\cos(b\ln x) + B\sin(b\ln x)].$$

#### **Example** Solve

$$x^2y'' + 7xy' + 5y = 0$$

Here p = 7 and q = 5. The indicial equation (3) is for this example

$$m^2 + m(p-1) + q =$$
  
 $m^2 + 6m + 5 = (m+5)(m+1)$ 

 $\Rightarrow m = -5 \text{ or } -1 \Rightarrow$ 

$$y = c_1 x^{-5} + c_2 x^{-1} = \frac{c_1}{x^5} + \frac{c_2}{x}.$$

#### **Example** Solve

$$x^2y'' + 3xy' + y = 0$$

Here p = 3 and q = 1 so the indicial equation is

$$m^2 + m(p-1) + q = m^2 + 2m + 1 = (m+1)^2$$

Thus m = -1 is a repeated root and the solution is

$$y_h = c_1 x^{-1} + c_2 x^{-1} \ln x$$

#### **Example** Solve

$$x^2y'' + 3xy' + 2y = 0$$

Here p = 3 and q = 2 so the indicial equation is

$$m^2 + m(p-1) + q = m^2 + 2m + 2$$

Thus

$$m = \frac{-2 \pm \sqrt{4 - 4(1)(2)}}{2} = -1 \pm i$$

Thus we set a = -1 and b = 1 in the formula

$$y_h = x^a [A\cos(b\ln x) + B\sin(b\ln x)].$$

and get

$$y_h = x^{-1}[A\cos(\ln x) + B\sin(\ln x)]$$