

Ma 227 Homework due 11/1/2013

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Section 13.8

3. Verify the divergence theorem is true for the vector field F on the region E .

$\vec{F} = \langle z, y, x \rangle$ E is the ball $x^2 + y^2 + z^2 \leq 161$.

$\text{div} \vec{F} = 0 + 1 + 0 = 1$ so

$$\iiint_E \text{div} F dV = \iiint_E 1 dV = V(E) = \frac{4}{3}\pi 4^3$$

Let S is a sphere of radius 4 centered at the origin which can be parametrized by

$$\vec{r}(\phi, \theta) = \langle 4 \sin \phi \cos \theta, 4 \cos \phi \sin \theta, 4 \cos \phi \rangle$$

(similar to Example 12.6.1)

$$\begin{aligned} \vec{r}_\phi \times \vec{r}_\theta &= \langle 4 \cos \phi \cos \theta, 4 \cos \phi \sin \theta, -4 \sin \phi \rangle \times \langle -4 \sin \phi \sin \theta, 4 \sin \phi \cos \theta, 0 \rangle \\ &= \langle 16 \sin^2 \phi \cos \theta, 16 \sin^2 \phi \sin \theta, 16 \cos \phi \sin \phi \rangle \end{aligned}$$

and

$$\vec{F}(\vec{r}(\phi, \theta)) = \langle 4 \cos \phi, 4 \sin \phi \sin \theta, 4 \sin \phi \cos \theta \rangle$$

$$\begin{aligned} \vec{F} \cdot (\vec{r}_\phi \times \vec{r}_\theta) &= 64 \cos \phi \sin^2 \phi \cos \theta + 64 \sin^3 \phi \sin^2 \theta + 64 \cos \phi \sin^2 \phi \cos \theta \\ &= 128 \cos \phi \sin^2 \phi \cos \theta + 64 \sin^3 \phi \sin^2 \theta \end{aligned}$$

Then

$$\begin{aligned} \iint_S \vec{F} \cdot d\vec{S} &= \iint_D \vec{F} \cdot (\vec{r}_\phi \times \vec{r}_\theta) dA = \int_0^{2\pi} \int_0^\pi (128 \cos \phi \sin^2 \phi \cos \theta + 64 \sin^3 \phi \sin^2 \theta) d\phi d\theta \\ &= \int_0^{2\pi} \left[\frac{128}{3} \sin^3 \phi \cos \theta + 64 \left(-\frac{1}{3} (2 + \sin^2 \phi) \cos \phi \right) \sin^2 \theta \right]_{\phi=0}^{\phi=\pi} d\theta \\ &= \int_0^{2\pi} \frac{256}{3} \sin^2 \theta d\theta = \frac{256}{3} \left[\frac{1}{2} \theta - \frac{1}{4} \sin 2\theta \right]_0^{2\pi} = \frac{256}{3} \pi \end{aligned}$$

5. $\text{div} \vec{F} = \partial/\partial x(xye^z) + \partial/\partial y(xy^2z^3) + \partial/\partial z(-ye^z) = ye^z + 2xyz^3 - ye^z = 2xyz^3$
by the Divergence theorem,

$$\iint_S \vec{F} \cdot d\vec{S} = \iiint_E \text{div} F dV = \int_0^3 \int_0^2 \int_0^1 2xyz^3 dz dy dx = 2 \left[\frac{1}{2} x^2 \right]_0^3 \left[\frac{1}{2} y^2 \right]_0^2 \left[\frac{1}{4} z^4 \right]_0^1 = \frac{9}{2}$$

7. $\vec{F}(x, y, z) = 3xy^2\vec{i} + xe^z\vec{j} + z^3\vec{k}$. S is the surface of the solid bounded by the cylinder $y^2 + z^2 = 1$ and the planes $x = -1$ and $x = 2$

$$\text{div} F = 3y^2 + 0 + 3z^2 = 3y^2 + 3z^2$$

so using cylindrical coordinates where $y = r \cos \theta, z = r \sin \theta$ and $x = x$

$$\iint_S \vec{F} \cdot d\vec{S} = \iiint_E (3y^2 + 3z^2) dV = \int_0^{2\pi} \int_0^1 \int_{-1}^2 (3r^2 \cos^2\theta + 3r^2 \sin^2\theta) r dx dr d\theta = \frac{9}{2}\pi$$

9. $\vec{F}(x, y, z) = x^2 \sin y \vec{i} + x \cos y \vec{j} - xz \sin y \vec{k}$. S is the "fat sphere" $x^8 + y^8 + z^8 = 8$
 $\text{div } F = 2x \sin y - x \sin y - x \sin y = 0$ so by Divergence Theorem

$$\iint_S \vec{F} \cdot d\vec{S} = \iiint_E 0 dV = 0$$

13. $\vec{F}(x, y, z) = 4x^3 z \vec{i} + 4y^3 z e^z \vec{j} + 3z^4 \vec{k}$. S is the sphere with radius R and center the origin.
 $\text{div } F = 12x^2 z + 12y^2 z + 12z^3$ so using spherical coordinates

$$\begin{aligned} \iint_S \vec{F} \cdot d\vec{S} &= \iiint_E 12z(x^2 + y^2 + z^2) dV = \int_0^{2\pi} \int_0^\pi \int_0^R 12(\rho \cos \phi)(\rho^2) \rho^2 \sin \phi d\rho d\phi d\theta \\ &= 12 \int_0^{2\pi} d\theta \int_0^\pi \sin \phi \cos \phi d\phi \int_0^R \rho^5 d\rho = 12(2\pi) \left[\frac{1}{2} \sin^2 \phi \right]_0^\pi \left[\frac{1}{6} \rho^6 \right]_0^R = 0 \end{aligned}$$

9.2 #1, 5, 7, 9 (not assigned) 12a, 13

$$1. \begin{array}{l} x_1 + 2x_2 + 2x_3 = 6 \\ 2x_1 + x_2 + x_3 = 6 \\ x_1 + x_2 + 3x_3 = 6 \end{array} = \begin{bmatrix} 1 & 2 & 2 & 6 \\ 2 & 1 & 1 & 6 \\ 1 & 1 & 3 & 6 \end{bmatrix}$$

$$R_2 - 2R_1 \quad \text{and} \quad R_3 - R_1 \quad \begin{bmatrix} 1 & 2 & 2 & 6 \\ 0 & -3 & -3 & -6 \\ 0 & -1 & 1 & 0 \end{bmatrix}$$

$$\frac{-1}{3}R_2 \quad \begin{bmatrix} 1 & 2 & 2 & 6 \\ 0 & 1 & 1 & 2 \\ 0 & -1 & 1 & 0 \end{bmatrix}$$

$$R_1 - 2R_2 \quad \text{and} \quad R_3 + R_2 \quad \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & 2 & 2 \end{bmatrix}$$

$$x_1 = 2 \quad x_2 + x_3 = 2 \quad 2x_3 = 2 \quad \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$$

$$5. \begin{array}{l} -x_1 + 2x_2 = 0 \\ 2x_1 + 3x_2 = 0 \end{array} = \begin{bmatrix} -1 & 2 & 0 \\ 2 & 3 & 0 \end{bmatrix}$$

$$R_2 + 2R_1 : \begin{bmatrix} -1 & 2 & 0 \\ 0 & 7 & 0 \end{bmatrix} = \begin{array}{l} -x_1 + 2x_2 = 0 \\ 7x_2 = 0 \end{array}$$

So $x_2=0$. Substituting 0 in for x_2 for the first equation gives $x_1=0$.

9.

We eliminate x_1 from the first equation by adding $(1-i)$ times the second equation to it:

$$[2 - (1+i)(1-i)]x_2 = 0$$

$$-x_1 - (1+i)x_2 = 0$$

Since $(1-i)(1+i)=1^2 - i^2 = 1 - (-1) = 2$, we obtain

$$0 = 0 \quad \Rightarrow \quad x_2 = \frac{-1}{1+i}x_1 = \frac{-1+i}{2}x_1$$
$$-x_1 - (1+i)x_2 = 0$$

Assigning an arbitrary complex value to x_1 , say $2s$, we see that the system has infinitely many solutions given by $x_1 = 2s$ $x_2 = (-1+i)s$ where s is any complex number.

12a.

$$2x_1 - x_2 = 2$$
$$-6x_1 + 3x_2 = 4$$

Multiplying the first equation by -3 yields $-6x_1 + 3x_2 = -6$. Both this equation and the second equation above cannot hold at the same time.

13.

$$2x_1 - 3x_2 = rx_1$$
$$x_1 - 2x_2 = rx_2$$

Or

$$(2-r)x_1 - 3x_2 = 0$$
$$x_1 + (-r-2)x_2 = 0$$

For $r = 2$ we have

$$-3x_1 = 0$$
$$x_1 - 4x_2 = 0$$

so the only solution is $x_1 = x_2 = 0$.

For $r = 1$ we have

$$x_1 - 3x_2 = 0$$
$$x_1 - 3x_2 = 0$$

Thus $x_1 = 3x_2$ So letting $x_2 = t$, we have $x_1 = 3t$, and $x_2 = t$, where t can have any value and thus we have an infinite number of solutions.