Ma 529 Lecture IV

Green's Theorem

There is a remarkable theorem that identifies a double integral over a region R with a line integral around its boundary. It is known as Green's Theorem.

Theorem: Let P(x, y) and Q(x, y) be functions of two variables which are continuous and have continuous first partial derivatives in some rectangular region H in the x, y - plane.

If C is a simple, closed, piecewise smooth curve lying entirely in H, and if R is the bounded region enclosed by C, then

$$\oint_C \Big\{ P(x,y) \, dx + Q(x,\,y) dy \Big\} = \int \int_R \left(rac{\partial Q}{\partial x} \, - \, rac{\partial P}{\partial y}
ight) \, dA$$

Corollary: Let R be a bounded region in the x, y – plane. Then the area of R is given by

$$A = \frac{1}{2} \oint_C (x \ dy - y \ dx)$$

where C is the boundary of R

Proof: Let P = -y/2 and Q = x/2 in Green's Theorem. \Rightarrow

$$\oint_C \left(\frac{-y}{2} \, dx \, + \, \frac{x}{2} \, dy \right) = \iint_R \left(\frac{1}{2} \, + \, \frac{1}{2} \right) dA = \iint_R dA = \text{area of } R$$

Example: Find the area of the region A bounded by the curves $y = x^3$ and $y = x^{\frac{1}{2}}$.



Let $C = C_1 + C_2$. Then C is a closed curve which bounds R. We shall use x as the parameter on C and the formula in the corollary. \Rightarrow

$$egin{aligned} A &= rac{1}{2} \oint_C (x \ dy \ - \ y \ dx) \ &= rac{1}{2} \int_{C_1} [x (3x^2) \ dx - \ x^3 dx] \ + \ rac{1}{2} \int_{C_2} [x \ \left(rac{1}{2} x^{-rac{1}{2}}
ight) \ dx - x^rac{1}{2} \ dx] \ &= rac{1}{2} \int_0^1 2x^3 \ dx \ - \ rac{1}{4} \int_1^0 x^rac{1}{2} \ dx \ = \ rac{5}{12} \end{aligned}$$

Example: Evaluate the line integral $\oint_C (x^3 + 2y) dx + (4x - 3y^2) dy$ where C is the ellipse $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ Solution: $P = x^3 + 2y$, $Q = 4x - 3y^2 \Rightarrow Q_x = 4$, $P_y = 2$ By Green's Theorem: $\oint_C P dx + Q dy = \int \int_R (4-2) dA = 2 \int \int dA$ Therefore we need the area of the ellipse which is πab . $\Rightarrow \oint = 2 \pi ab$.

Example. Verify Green's theorem for $\oint_C 3xydx + 2x^2dy$ where C is the curve which bounds the region R above by y = x and below by $y = x^2 - 2x$.



Since P = 3xy and $Q = 2x^2$, we see that $Q_x - P_y = 4x - 3x = x$. Thus

$$\int \int (Q_x - P_y) \, dA = \int_0^3 \int_{x^2 - 2x}^x x \, dy dx = \frac{27}{4}$$

$$C = C_1 + C_2 \qquad C_1: \ y = x^2 - 2x \qquad C_2: \ y = x \qquad 0 \le x \le 3$$
On $C_1: \ \int_{C_1} P dx + Q dy = \int_0^3 3x(x^2 - 2x) dx + \int_0^3 2x^2(2x - 2) dx$
On $C_2: \ \int_{C_2} P dx + Q dy = \int_3^0 3x(x) dx + \int_3^0 2x^2 dx$
A straight forward calculation shows that the sum of these last two expressions also equals $\frac{27}{4}$.

Example. Use Green's theorem to evaluate

$$\int_C \left(2y \,+\, \sqrt{9+x^3}
ight)\,dx + (5x + e^{lpha rctan\,y})dy$$

where C is the circle $x^2 + y^2 = 4$. Now $Q_x - P_y = 5 - 2 = 3$. \Rightarrow

$$\iint_{x^2+y^2 \le 4} 3dA = 3 \text{(area of circle of rad 2)} = 3(4\pi) = 12\pi$$

Surface Integrals

There are three common ways of defining a surface:

I. $z = \varphi(x, y)$ (1) as above. Here φ must be a single-valued, continuous function defined on a region of the x, y – plane.

II. Often surfaces are represented by equations of the form F(x, y, z) = 0 (2). If (x_0, y_0, z_0) is a point on such a surface, we can in many cases represent the portion of the surface near (x_0, y_0, z_0) in a form analogous to (1) by solving (2) for x, y, or z in terms of the other two variables.

III. It is frequently convenient to describe a surface by a <u>parametric</u> representation.

Ex. $x = a \sin u \cos v$ $y = a \sin u \sin v$. $z = a \cos u$

Here u and v are independent parameters. This represents a sphere whose equation is $x^2 + y^2 + z^2 = a^2$. This equation is gotten by elimination of u and v. Note u and v are the spherical coordinates ϕ and θ .

The set of equations

$$x = x(u, v)$$
 $y = y(u, v)$ $z = z(u, v)$ (3)

where u and v are parameters, represents an arbitrary surface. This can be seen by eliminating u and v from (3), a procedure that leads to an equation of the form F(x, y, z) = 0 which is case II.

In terms of the radius vector $\vec{r} = \vec{xi} + \vec{yj} + \vec{zk}$ equation (3) for the surface may be written as

$$\overrightarrow{r} = \overrightarrow{r}(u,v) = x(u,v)\overrightarrow{i} + y(u,v)\overrightarrow{j} + z(u,v)\overrightarrow{k}$$

From the parametric equations for a surface it is possible to establish a formula for ds, the element of surface area. In general, ds is obtained by calculating the area between the curves corresponding to:

$$u = u_0, u_0 + du, v = v_0$$
 and $v_0 + dv$.

For infinitesimal areas this element will be essentially planar and have area $ds = |\overrightarrow{AB} \times \overrightarrow{AC}|$, where the vectors are the sides of the differential parallelogram shown in the diagram.





$$A = \overrightarrow{r}(u_0, v_0) \quad B = \overrightarrow{r}(u_0 + du, v_0) = \overrightarrow{r}(u_0, v_0) + \frac{\partial \overrightarrow{r}}{\partial u}(u_0, v_0) du + \cdots$$
$$C = \overrightarrow{r}(u_0, v_0 + dv) = \overrightarrow{r}(u_0, v_0) + \frac{\partial \overrightarrow{r}}{\partial v}(u_0, v_0) dv + \cdots$$

Thus $\overrightarrow{AB} = \frac{\partial \overrightarrow{r}}{\partial u} du$ $\overrightarrow{AC} = \frac{\partial \overrightarrow{r}}{\partial v} dv \Rightarrow ds = |\frac{\partial \overrightarrow{r}}{\partial u} \times \frac{\partial \overrightarrow{r}}{\partial v}| du dv$

Hence, in general, we have for a surface given by

$$x = x(u,v)$$
 $y = y(u,v)$ $z = z(u,v)$ that

 $\iint_{S} f(x, y, z) \, ds = \iint_{G} f(u, v) \, | \overrightarrow{r}_{u} \times \overrightarrow{r}_{v} | \, du dv, \text{ where } G \text{ is the image of the}$ surface S in the u, v-plane.

Example. Suppose the surface is given by the representation $z = \varphi(x, y)$ (case I). Let $x = u, \ y = v \Rightarrow z = \varphi(u, v)$ Then $\vec{r}(u, v) = u\vec{i} + v\vec{j} + \varphi(u, v)\vec{k}$

also represents the surface. Thus

$$ec{r}_u = ec{i} + arphi_u ec{k}; \quad ec{r}_v = ec{j} + arphi_v ec{k}; \quad ec{r}_u imes ec{r}_v = ec{k} - arphi_u ec{i} - arphi_v ec{j}$$

 $ds = |\vec{r}_u \times \vec{r}_v| du dv = [1 + \varphi_u^2 + \varphi_v^2]^{\frac{1}{2}} du dv.$ But since u = x, v = y we get

$$ds=[1+arphi_x^2+arphi_y^2]^{rac{1}{2}}\,dx\,dy.$$

for a surface given by $z = \varphi(x, y)$.

Example. Find the surface area of the paraboloid $z = x^2 + y^2$ below the plane z = 1.

The surface S projects into the interior of the circle $x^2 + y^2 = 1$. This is R. Here $z = \varphi(x, y) = x^2 + y^2$.

Surface area $= \int_{S} \int 1 \cdot dS = \int_{R} (1 + \varphi_x^2 + \varphi_y^2)^{\frac{1}{2}} dy dx$



Here R is circle $x^2 + y^2 \leq 1$. Thus the surface area is given by

$$\int \int \limits_R \sqrt{1+4x^2+4y^2} \, dy dx$$

To evaluate this double integral we shall use polar coordinates. Then

Surface area =
$$\int_{R} \int_{R} \sqrt{4r^2 + 1} r dr d\theta = \frac{1}{8} \int_{0}^{2\pi} \int_{0}^{1} \sqrt{4r^2 + 1} r dr d\theta$$

$$= rac{1}{8} \int_{0}^{2\pi} rac{2}{3} \left(4r^2+1
ight)^{rac{3}{2}} \left| \begin{smallmatrix} 1 \\ 0 \end{smallmatrix} d heta = rac{1}{12} \int_{0}^{2\pi} (5^{rac{3}{2}}-1) d heta = rac{\pi}{6} \left(5\sqrt{5}-1
ight).$$

Cylindrical and Spherical Coordinates

Cylindrical coordinates are related to Cartesian coordinates via

$$x = rcos \theta$$
 $y = rsin \theta$ $z = z$

The relationship between a volume element in the two systems is $dV = dxdydz \rightarrow rdrd\theta dz$, that is $\int \int \int dV = \int \int \int rdrd\theta dz$



Spherical coordinates are related to Cartesian coordinates via $x, y, z \rightarrow \rho, \theta, \phi$ where

 $x = \rho cos \theta sin \phi$ $y = \rho sin \theta sin \phi$ $z = \rho cos \phi$ $0 \le \theta \le 2\pi$ $0 \le \phi \le \pi$

The relationship between a volume element in the two systems is

 $dV = dxdydz \rightarrow \rho^2 sin\phi d\rho d\theta d\theta$, that is $\int \int \int dV = \int \int \int \rho^2 sin\phi d\rho d\theta d\theta$. It is important to keep in mind that ϕ is measured from the z axis and thus varies only from 0 to π .



Example. Find the volume above the cone $z^2 = x^2 + y^2$ and inside the sphere $x^2 + y^2 + z^2 = 2az$.



We shall use spherical coordinates.

Cone: $z^2 = x^2 + y^2$ $z = \rho \cos \phi$ $x = \rho \cos \theta \sin \phi$ $y = \rho \sin \theta \sin \phi$ The equation of the cone $\Rightarrow \rho^2 \cos^2 \phi = \rho^2 \cos^2 \theta \sin^2 \phi + \rho^2 \sin^2 \theta \sin^2 \phi$ or $\cos^2 \phi = \sin^2 \phi$ $\Rightarrow \tan \phi = 1 \Rightarrow \phi = \pm 45^\circ = \frac{\pi}{4} \text{ or } \phi = \frac{\pi}{4} + \pi = \frac{5\phi}{4}.$

Sphere: $x^2 + y^2 + z^2 - 2az = 0$ or $x^2 + y^2 + (z - a)^2 = a^2$. Center at (0, 0, a). $\Rightarrow \rho^2 - 2a\rho \cos\phi = 0$ or $\rho = 2a\cos\phi$.

We see that ϕ goes from 0 to $\frac{\pi}{4}$, θ from 0 to 2π . and ρ from 0 to $\rho = 2a\cos\phi$. Hence

Volume =
$$\int \int \int \rho^2 sin\phi dV_{\rho\theta\phi} = \int_0^{\frac{\pi}{4}} \int_0^{2acos\phi} \int_0^{2\pi} \rho^2 sin\phi d\theta d\rho d\phi$$

Example. Consider a sphere of radius <u>a</u> centered at the origin. We shall find its surface area. Now using spherical coordinates we have

$$x = a \sin u \cos v \quad y = a \sin u \sin v \quad z = a \cos u$$

$$\Rightarrow \vec{r} = a \sin u \cos v \vec{i} + a \sin u \sin v \vec{j} + a \cos u \vec{k}$$

$$\vec{r}_u \times \vec{r}_v = a^2 (\sin^2 u \cos v \vec{i} + \sin^2 u \sin v \vec{j} + \sin u \cos u \vec{k})$$

$$\Rightarrow |\vec{r}_u \times \vec{r}_v| = a^2 \sin u \quad ds = a^2 \sin u \, du dv$$
Thus $\int \int_S ds = \int \int_S a^2 \sin u \, du dv = \int_0^{2\pi} \int_0^{\pi} a^2 \sin \phi \, d\phi$

$$= 4 \pi a^2 = \text{surface area of sphere}$$

Surface Elements

Suppose R is a closed rectangular region in the u, v-plane $a \le u \le b$, $c \le v \le d$. Then the equations x = x(u, v) y = y(u, v), z = z(u, v), where x, y, z are continuous, define a set S which is part of a surface in x, y, z- space. If the functions x, y, z are also 1-1, i.e. distinct points of R are not mapped into the same point of S, then the points of S in x, y, z- space comprise a <u>simple surface element</u>. A simple surface element may be thought of as any configuration which may be obtained from a rectangular plane region by continuous deformation (bending, twisting, stretching, shrinking) without tearing and without bringing together any points which were originally distinct.

If S is a simple surface element corresponding to a rectangular region R in the u, v – plane, the points of S which correspond to the boundary of R form what is called the boundary S. Other points of S are called interior points.

All surfaces may be thought of as being built up out of simple surface elements by matching together portions of the edges of the elements. The <u>boundary</u> of a surface consists of the <u>unmatched</u> edges of its surface elements. If there are no unmatched edges, there is no boundary. For example, a hemisphere has a boundary consisting of its equatorial rim. An entire sphere, an ellipsoid, and the surface of a cube are examples of surfaces without boundary.

A surface is smooth if the functions which parametrize it are continuously differentiable. If a surface is smooth and has no boundary, it is called a <u>smooth surface</u> without <u>boundary</u>. If a surface is given by F(x, y, z) = 0, then the surface is smooth without boundary if $\nabla F \neq 0$ for all x, y, z on the surface.

Example. Consider the surface $F(x, y, z) = 4x^2 + 9y^2 - 2z^2 - 8 = 0$. Then

 $\nabla F = 8xi + 18yj - 4zk$ and $\nabla F = 0 \Rightarrow x = y = z = 0$. But (0,0,0) is not on this surface. $\Rightarrow F$ is smooth without boundary.

Example. Evaluate $\iint_S f(x, y, z) \, ds$ where $f = x^2$ and S is the part of the cone $z^2 = x^2 + y^2$ between the planes z = 1 and z = 2.

We shall use spherical coordinates $x = \rho \sin \phi \cos \theta$, $y = \rho \sin \phi \sin \theta$, $z = \rho \cos \phi$ In spherical coordinates the equation of the cone is $\phi = \frac{\pi}{4}$. Letting $u = \theta$, $v = \rho \Rightarrow$ we have for x, y, and z on the surface of the cone that

$$x(u,v)=x(heta,
ho)=~rac{\sqrt{2}}{2}
ho cos~ heta~;~~y(u,v)=y(heta,
ho)=rac{\sqrt{2}}{2}
ho sin~ heta~;~~z=rac{\sqrt{2}}{2}
ho$$

where $0 \le \theta \le 2\pi$ and $1 \le z \le 2 \Rightarrow \sqrt{2} \le \rho \le 2\sqrt{2}$

$$\Rightarrow \vec{r} = x\vec{i} + y\vec{j} + z\vec{k} = \frac{\sqrt{2}}{2}\rho\cos\theta\vec{i} + \frac{\sqrt{2}}{2}\rho\sin\theta\vec{j} + \frac{\sqrt{2}}{2}\rho\vec{k}$$

$$\Rightarrow \vec{r}_{u} = \vec{r}_{\theta} = -\frac{\sqrt{2}}{2}\rho\sin\theta\vec{i} + \frac{\sqrt{2}}{2}\rho\cos\theta\vec{j}$$

$$\Rightarrow \vec{r}_{v} = \vec{r}_{\rho} = -\frac{\sqrt{2}}{2}\cos\theta\vec{i} + \frac{\sqrt{2}}{2}\sin\theta\vec{j} + \frac{\sqrt{2}}{2}$$

$$\Rightarrow \vec{r}_{\theta} \times \vec{r}_{\rho} = \frac{1}{2}\rho\left[\cos\theta\vec{i} + \sin\theta\vec{j} - \vec{k}\right] \text{ and } |\vec{r}_{\theta} \times \vec{r}_{\rho}| = \frac{\sqrt{2}}{2}\rho$$

$$\int \int_{S} x^{2} ds = \int_{\sqrt{2}}^{2\sqrt{2}} \int_{0}^{2\pi} \frac{1}{2}\rho^{2}\cos^{2}\theta \frac{\sqrt{2}}{2}\rho d\theta d\rho = \frac{\sqrt{2}}{8} \int_{\sqrt{2}}^{2\sqrt{2}} \rho^{3} \left(\theta + \frac{\sin 2\theta}{2}\right) \Big|_{0}^{2\pi} d\rho$$

$$= \frac{15}{4}\sqrt{2}\pi$$